A BayesPCN's Auto-Associative and Hetero-Associative read

Algorithm 3 Auto-Associative Memory Read

- 1: Input: Memory log density $\log p(x^0, \mathbf{h} | x_{1:T}^0)$, query vector \bar{x}^0
- 2: **Output**: Recall vector x^{0*}
- 3: Set the initial recall vector: $x^{0*} = \bar{x}^0$
- 4: repeat
- 5:
- Find the most probable latent code given the input: $\mathbf{h}^* = \operatorname{argmax}_{\mathbf{h}} \log p(x^{0*}, \mathbf{h} | x_{1:T}^0)$ Find the most probable input given the latent code: $x^{0*} = \operatorname{argmax}_{x^0} \log p(x^0, \mathbf{h}^* | x_{1:T}^0)$ 6:
- 7: until convergence or upper iteration limit

Algorithm 4 Hetero-Associative Memory Read

- Input: Memory log density log p(x⁰, h|x⁰_{1:T}), query vector x
 ⁰ = (k, v) where the key k is known but the value v is arbitrarily initialized
 Output: Recall vector x^{0*}
- 3: Find the most probable value and latent code given the key: 4: $v^*, \mathbf{h}^* = \operatorname{argmax}_{v, \mathbf{h}} \log p((k, v), \mathbf{h} | x_{1:T}^0)$
- 5: Set the final recall vector: $x^{0*} = (k, v^*)$

B Derivation of BayesPCN write

$$p(\mathbf{W}|x_{1:t}^{0}) = \frac{1}{Z}p(\mathbf{W}|x_{1:t-1}^{0})p(x_{t}^{0}|\mathbf{W})$$
(12)

$$= \frac{1}{Z} p(\mathbf{W}|x_{1:t-1}^0) \mathbb{E}_{q(\mathbf{h}_t)} [\frac{p(x_t^0, \mathbf{h}_t | \mathbf{W})}{q(\mathbf{h}_t)}]$$
(13)

$$\approx \frac{1}{Z} \left[\sum_{n=1}^{N} \omega_{t-1}^{(n)} p^{(n)}(\mathbf{W} | x_{1:t-1}^{0}, \mathbf{h}_{1:t-1}^{(n)}) \right] \mathbb{E}_{q(\mathbf{h}_{t})} \left[\frac{p(x_{t}^{0}, \mathbf{h}_{t} | \mathbf{W})}{q(\mathbf{h}_{t})} \right]$$
(14)

$$=\frac{1}{Z}\sum_{n=1}^{N}\omega_{t-1}^{(n)}p^{(n)}(\mathbf{W}|x_{1:t-1}^{0},\mathbf{h}_{1:t-1}^{(n)})\mathbb{E}_{q^{(n)}(\mathbf{h}_{t})}[\frac{p(x_{t}^{0},\mathbf{h}_{t}|\mathbf{W})}{q^{(n)}(\mathbf{h}_{t})}]$$
(15)

$$\approx \frac{1}{Z} \sum_{n=1}^{N} \omega_{t-1}^{(n)} \frac{1}{S} \sum_{i=1}^{S} \frac{p^{(n)}(\mathbf{W} | x_{1:t-1}^{0}, \mathbf{h}_{1:t-1}^{(n)}) p(x_{t}^{0}, \mathbf{h}_{t}^{(n,i)} | \mathbf{W})}{q^{(n)}(\mathbf{h}_{t}^{(n,i)})}, \quad \mathbf{h}_{t}^{(n,i)} \sim q^{(n)}(\mathbf{h}_{t})$$
(16)

$$= \frac{1}{Z} \frac{1}{S} \sum_{n=1}^{N} \sum_{i=1}^{S} \omega_{t-1}^{(n)} \frac{p^{(n)}(x_t^0, \mathbf{h}_t^{(n,i)} | x_{1:t-1}^0)}{q^{(n)}(\mathbf{h}_t^{(n,i)})} p^{(n)}(\mathbf{W} | x_{1:t}^0, \mathbf{h}_{1:t}^{(n,i)})$$
(17)

$$=\sum_{n=1}^{N}\sum_{i=1}^{S}\frac{\omega_{t-1}^{(n)}\frac{p^{(n)}(x_{t}^{n},\mathbf{h}_{t}^{(n,i)}|x_{1:t-1}^{n})}{q^{(n)}(\mathbf{h}_{t}^{(n,i)})}}{\sum_{n'=1}^{N}\sum_{i'=1}^{S}\omega_{t-1}^{(n')}\frac{p^{(n')}(x_{t}^{n},\mathbf{h}_{t}^{(n',i')}|x_{1:t-1}^{n})}{q^{(n')}(\mathbf{h}_{t}^{(n',i')})}}p^{(n)}(\mathbf{W}|x_{1:t}^{0},\mathbf{h}_{1:t}^{(n,i)})$$
(18)

$$=\sum_{n=1}^{N}\sum_{i=1}^{S}\omega_{t}^{(n,i)}p^{(n)}(\mathbf{W}|x_{1:t}^{0},\mathbf{h}_{1:t}^{(n,i)})$$
(19)

Equation 17 holds because

$$p^{(n)}(\mathbf{W}|x_{1:t}^{0}, \mathbf{h}_{1:t}^{(n)}) = \frac{p^{(n)}(\mathbf{W}|x_{1:t-1}^{0}, \mathbf{h}_{1:t-1}^{(n)})p(x_{t}^{0}, \mathbf{h}_{t}^{(n,i)}|\mathbf{W})}{p^{(n)}(x_{t}^{0}, \mathbf{h}_{t}^{(n,i)}|x_{1:t-1}^{0})}$$
(20)

and Equation 18 holds because

$$Z = \int p(\mathbf{W}|x_{1:t-1}^0) \mathbb{E}_{q^{(n)}(\mathbf{h}_t)} [\frac{p(x_t^0, \mathbf{h}_t | \mathbf{W})}{q^{(n)}(\mathbf{h}_t)}] d\mathbf{W}$$
(21)

$$\approx \int \frac{1}{S} \sum_{n=1}^{N} \sum_{i=1}^{S} \omega_{t-1}^{(n)} \frac{p^{(n)}(x_t^0, \mathbf{h}_t^{(n,i)} | x_{1:t-1}^0)}{q^{(n)}(\mathbf{h}_t^{(n,i)})} p^{(n)}(\mathbf{W} | x_{1:t}^0, \mathbf{h}_{1:t}^{(n,i)}) d\mathbf{W}$$
(22)

$$= \frac{1}{S} \sum_{n=1}^{N} \sum_{i=1}^{S} \omega_{t-1}^{(n)} \frac{p^{(n)}(x_t^0, \mathbf{h}_t^{(n,i)} | x_{1:t-1}^0)}{q^{(n)}(\mathbf{h}_t^{(n,i)})}$$
(23)

Finally, if S = 1 we get

$$\hat{p}(\mathbf{W}|x_{1:t}^{0}) = \sum_{n=1}^{N} \frac{\omega_{t-1}^{(n)} \frac{p^{(n)}(x_{t}^{0}, \mathbf{h}_{t}^{(n)}|x_{1:t-1}^{0})}{q^{(n)}(\mathbf{h}_{t}^{(n)})}}{\sum_{n'=1}^{N} \omega_{t-1}^{(n')} \frac{p^{(n')}(x_{t}^{0}, \mathbf{h}_{t}^{(n')}|x_{1:t-1}^{0})}{q^{(n')}(\mathbf{h}_{t}^{(n')})}} p^{(n)}(\mathbf{W}|x_{1:t}^{0}, \mathbf{h}_{1:t}^{(n)})$$
(24)

C Analytical Posterior Formulae for write

Let z = f(x). Then, BayesPCN's top layer parameter update given $x^{0:L}$ is

$$\mu^* \leftarrow (\Sigma^{-1} + \frac{1}{\sigma_x^2} I)^{-1} (\Sigma^{-1} \mu + \frac{1}{\sigma_x^2} x^L)$$
(25)

$$\Sigma^* \leftarrow (\Sigma^{-1} + \frac{1}{\sigma_x^2} I)^{-1} \tag{26}$$

while the update for all other layers given $x^{0:L}$ is

$$R^{l*} \leftarrow R^{l} + U^{l} z^{l+1^{\mathsf{T}}} (z^{l+1} U^{l} z^{l+1^{\mathsf{T}}} + \sigma_{x}^{2} I)^{-1} (x^{l} - z^{l+1} R^{l})$$
(27)

$$U^{l*} \leftarrow U^{l} - U^{l} z^{l+1^{\top}} (z^{l+1} U^{l} z^{l+1^{\top}} + \sigma_{x}^{2} I)^{-1} z^{l+1} U^{l}$$
(28)

D Analytical Diffusion Formulae for forget

Let $R_0^{1:L-1}, U_0^{1:L-1}, \mu_0, \Sigma_0$ be the memory prior parameters and β be the forget strength. Then, BayesPCN's top layer diffusion update is

$$\mu^* = \sqrt{1 - \beta}\mu + (1 - \sqrt{1 - \beta})\mu_0$$
(29)
$$\Sigma^* = (1 - \beta)\Sigma + \beta\Sigma_0$$
(30)

$$R^{l*} = \sqrt{1-\beta}R^l + (1-\sqrt{1-\beta})R_0^l$$
(31)

$$U^{l*} = (1 - \beta)U^l + \beta U_0^l$$
(32)

E Connections to Hopfield Networks

We show that modern Hopfield network's recall is equivalent to the recall of a BayesPCN model with L = 0. BayesPCN's activation log density is defined as $\log p(x^0, \mathbf{h}) = \log \left(\sum_{n=1}^{N} \omega^{(n)} p^{(n)}(x^0, \mathbf{h}) \right)$, and its gradient w.r.t. the activations is

$$\nabla_{x^{0},\mathbf{h}}\log p(x^{0},\mathbf{h}) = \sum_{n=1}^{N} \frac{\exp(\log \omega^{(n)} p^{(n)}(x^{0},\mathbf{h}))}{\sum_{n'=1}^{N} \exp(\log \omega^{(n')} p^{(n')}(x^{0},\mathbf{h}))} \nabla_{x^{0},\mathbf{h}}\log p^{(n)}(x^{0},\mathbf{h}), \quad (33)$$

On the other hand, MHN's energy is

$$E(q) = \frac{\beta}{2}qq^T - \log\sum_{j=1}^N \exp(\beta qK_j^T)$$
(34)

where $q \in \mathbb{R}^{1 \times d_k}$ is the query row vector, $K \in \mathbb{R}^{N \times d_k}$ is the key matrix, and $K_j \in \mathbb{R}^{1 \times d_k}$ is the j-th key row vector. q and K correspond to x^0 and W^0 in our paper's notation. The negative of the energy can be converted to the following Gaussian mixture log density.

$$\log p(q) = \log \left(\sum_{j=1}^{N} \frac{e^{\frac{\beta}{2}K_j K_j^T}}{\sum_{j'=1}^{N} e^{\frac{\beta}{2}K_{j'} K_{j'}^T}} \frac{1}{(2\pi\beta^{-1})^{\frac{d_k}{2}}} e^{-\frac{\beta}{2}(q-K_j)(q-K_j)^T} \right)$$
(35)

Recall in both BayesPCN and MHN is gradient ascent on the above log density. When we take the gradient with respect to the input vector q, we recover Equation 33.

$$\nabla_{q} \log p(q) = \sum_{j=1}^{N} \frac{e^{\frac{\beta}{2}qK_{j}^{T}}}{\sum_{j'=1}^{N} e^{\frac{\beta}{2}qK_{j'}^{T}}} \beta(K_{j} - q)$$
(36)

$$=\sum_{n=1}^{N} \frac{\exp(\log \omega^{(n)} p^{(n)}(x^{0}, \mathbf{h}))}{\sum_{n'=1}^{N} \exp(\log \omega^{(n')} p^{(n')}(x^{0}, \mathbf{h}))} \nabla_{x^{0}, \mathbf{h}} \log p^{(n)}(x^{0}, \mathbf{h})$$
(37)

where
$$\omega^{(n)} = \frac{\beta}{2} K_n K_n^T$$
, $\log p^{(n)}(x^0, \mathbf{h}) = \log \mathcal{N}(q; K_n, \frac{1}{\beta}I)$ (38)

We conclude that recall in Modern Hopfield Network is equivalent to recall under our framework, which is gradient descent on the log joint of a normal mixture w.r.t. neuron activations, where there are no hidden layers (L = 0). However training our model with L = 0 does not lead to the same memory update as the suggested training procedure of MHN, which is setting each key vector K_j to some observed datapoint.

Universal Hopfield network [Millidge et al., 2022] proposes a framework for single-shot associative memory that decomposes recall into three components: similarity function, separation function, and projection matrix. Let $\mathbf{x} = (\bar{x}^0, \mathbf{h})$ be the row vector of all initial network activations when give the query \bar{x}^0 . Equation 33 suggests that BayesPCN read's implementation of those components is per query \bar{x}^{0} . Equation 33 suggests that BayesPCIN reaa s implementation of mose components is per-particle weighted log joint $\log \omega^{(n)} p^{(n)}(\mathbf{x})$ of the query \bar{x}^{0} for the similarity function, softmax for the separation function, and the matrix $\begin{bmatrix} \mathbf{x} + \gamma \nabla_{\mathbf{x}} \log p^{(1)}(\mathbf{x}) \\ \vdots \end{bmatrix}$ for the projection matrix where γ

$$\mathbf{x} + \gamma \nabla_{\mathbf{x}} \log p^{(N)}(\mathbf{x})$$

is the learning rate. We can accommodate the fact that BayesPCN's read does iterated conditional modes by zeroing out the fixed variable gradients in the projection matrix.

Additional Experiment Details F

All GPCN and BayesPCN models had $\sigma_W = 1, \sigma_x = 0.01$, and used Adam with learning rate 0.01 as the neuron activation gradient descent optimizer. All energy minimization w.r.t. the neuron activations took 500 gradient steps during the *write* phase. During the *read* phase, the outer loop iterated conditional mode in Algorithm 3 was repeated 30 times and the energy minimization in Algorithm 4 took 30 \times 500 gradient steps. MHN models had $\beta = 10,000$ (equivalent to $\sigma_x = 0.01$), used Adam with learning rate 1.0 as the gradient descent optimizer, and performed gradient-descent based recall similar to BayesPCN based on the connection from Appendix E. All experiments were run on CIFAR10 and/or Tiny ImageNet datasets (both of which have the MIT License) and the image pixel values were normalized to fall between [-1, 1]. Offline GPCNs received 4000 iterations of network weight gradient descent steps. Online GPCNs took a single gradient step w.r.t. the network weights after the hidden activations converged per observation, a treatment consistent with that of the fast weight memory in Schlag et al. [2021]. BayesPCN forget models had four hidden layers of width 1024, a single particle, and GELU activations. All hyperparameter ranges were chosen based on Salvatori et al. [2021]'s experiments and GPCN/BayesPCN's empirical results.

All experiments used NVIDIA Tesla V100 GPUs and were run on the university's internal clusters. Training the most expensive GPCN model (hidden layer width of 1024) and BayesPCN model (hidden layer width of 1024, 4 particles) on 1024 observations took 20 hours and 3 hours respectively. Evaluating the most expensive GPCN and BayesPCN models on all tasks took 25 minutes and 3 hours respectively.

White Noise CIFAR10 MSE					
Sequence Length	128	256	512	1024	
Identity	0.1596 ± 0.0003	0.1600 ± 0.0001	0.1600 ± 0.0000	0.1600 ± 0.0001	
MHN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	
GPCN (Offline)	0.0028 ± 0.0000	0.0046 ± 0.0001	0.0073 ± 0.0000	0.0121 ± 0.0001	
GPCN (Online)	0.0103 ± 0.0001	0.0150 ± 0.0001	0.0191 ± 0.0000	0.0210 ± 0.0001	
BayesPCN	0.0017 ± 0.0003	0.0085 ± 0.0002	0.0146 ± 0.0001	0.0337 ± 0.0007	
BayesPCN (forget)	0.0064 ± 0.0001	0.0102 ± 0.0001	0.0145 ± 0.0001	0.0188 ± 0.0002	
	White No	oise Tiny ImageNet	MSE		
Sequence Length	128	256	512	1024	
Identity	0.1600 ± 0.0000	0.1602 ± 0.0000	0.1601 ± 0.0000	0.1600 ± 0.0001	
MHN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	
GPCN (Offline)	0.0005 ± 0.0000	0.0010 ± 0.0000	0.0018 ± 0.0000	0.0067 ± 0.0004	
GPCN (Online)	0.0089 ± 0.0002	0.0112 ± 0.0002	0.0138 ± 0.0001	0.0181 ± 0.0001	

	Dropout CIFAR10 MSE					
Sequence Length	128	256	512	1024		
Identity	1.1140 ± 0.0059	1.1178 ± 0.0009	1.1353 ± 0.0014	1.1481 ± 0.0010		
MHN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000		
GPCN (Offline)	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000		
GPCN (Online)	0.0022 ± 0.0000	0.0032 ± 0.0001	0.0053 ± 0.0001	0.0073 ± 0.0000		
BayesPCN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000		
BayesPCN (forget)	0.0000 ± 0.0000	0.0001 ± 0.0000	0.0005 ± 0.0000	0.0019 ± 0.0000		

BayesPCN (forget) 0.0026 ± 0.0000 0.0059 ± 0.0000 0.0108 ± 0.0001 0.0176 ± 0.0001

 $0.0011 \pm 0.0001 \quad 0.0033 \pm 0.0000 \quad 0.0064 \pm 0.0001 \quad 0.6606 \pm 0.0267$

BayesPCN

Dropout Tiny ImageNet MSE					
Sequence Length	128	256	512	1024	
Identity	1.0629 ± 0.0014	1.0889 ± 0.0006	1.1154 ± 0.0005	1.1072 ± 0.0008	
MHN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	
GPCN (Offline)	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	
GPCN (Online)	0.0036 ± 0.0002	0.0053 ± 0.0002	0.0069 ± 0.0001	0.0099 ± 0.0001	
BayesPCN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	
BayesPCN (forget)	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0002 ± 0.0000	0.0008 ± 0.0000	

Mask CIFAR10 MSE						
Sequence Length	128	256	512	1024		
Identity	1.1272 ± 0.0000	1.1373 ± 0.0000	1.1619 ± 0.0000	1.1653 ± 0.0000		
MHN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0011 ± 0.0000	0.0000 ± 0.0000		
GPCN (Offline)	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0009 ± 0.0000		
GPCN (Online)	0.0127 ± 0.0008	0.0255 ± 0.0009	0.0522 ± 0.0006	0.0791 ± 0.0005		
BayesPCN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000	0.0019 ± 0.0000		
BayesPCN (forget)	0.0000 ± 0.0000	0.0008 ± 0.0000	0.0096 ± 0.0001	0.0465 ± 0.0001		

Mask Tiny ImageNet MSE						
Sequence Length	128	256	512	1024		
Identity	1.0876 ± 0.0000	1.0884 ± 0.0000	1.0982 ± 0.0000	1.1132 ± 0.0000		
MHN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0010 ± 0.0000		
GPCN (Offline)	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000		
GPCN (Online)	0.0081 ± 0.0007	0.0316 ± 0.0033	0.0441 ± 0.0012	0.0698 ± 0.0010		
BayesPCN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000		
BayesPCN (forget)	0.0000 ± 0.0000	0.0003 ± 0.0000	0.0031 ± 0.0000	0.0235 ± 0.0001		

Table 2: Table 1 results with standard deviations calculated across three seeds.

G BayesPCN vs MHN Recall on Highly Noised Queries

This section reports the recall performance of MHN and BayesPCN models on high query noise associative recall tasks. The experiment setup is similar to that of Section 6 aside from the fact that the white noise tasks had the noise standard deviation set to 0.8 instead of 0.2, the dropout tasks randomly blacked out 75% of the pixels instead of 25%, and the masking tasks blacked out 75% of the rightmost pixels instead of 25%. Because the high query noise task is harder, we show the recall result after the models observed 16, 32, 64, and 128 datapoints. BayesPCN models had four hidden layers of width 256, a single particle, and GELU activations. MHNs again used $\beta = 10,000$.

White Noise CIFAR10 MSE					
Sequence Length 16 32 64 128					
Identity	2.5564 ± 0.0086	2.5525 ± 0.0023	2.5586 ± 0.0105	2.5565 ± 0.0052	
MHN	0.0086 ± 0.0000	0.0023 ± 0.0000	0.0105 ± 0.0000	0.0052 ± 0.0000	
BayesPCN	0.0111 ± 0.0003	0.0203 ± 0.0002	0.0394 ± 0.0007	0.0755 ± 0.0002	

White Noise Tiny ImageNet MSE				
Sequence Length 16 32 64 128				
Identity	2.5586 ± 0.0105	2.5565 ± 0.0052	2.5584 ± 0.0047	2.5582 ± 0.0036
MHN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000
BayesPCN	0.0033 ± 0.0001	0.0064 ± 0.0002	0.0125 ± 0.0003	0.0242 ± 0.0002

Dropout CIFAR10 MSE					
Sequence Length 16 32 64 128					
Identity	1.0060 ± 0.0054	1.0276 ± 0.0044	1.0691 ± 0.0026	1.1095 ± 0.0018	
MHN	0.3517 ± 0.0027	0.3596 ± 0.0029	0.3635 ± 0.0031	0.3840 ± 0.0010	
BayesPCN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	

Dropout Tiny ImageNet MSE					
Sequence Length 16 32 64 128					
Identity	1.0365 ± 0.0022	1.0746 ± 0.0012	1.1418 ± 0.0007	1.0625 ± 0.0011	
MHN	0.4967 ± 0.0026	0.5096 ± 0.0006	0.5741 ± 0.0021	0.5630 ± 0.0036	
BayesPCN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	

Mask CIFAR10 MSE					
Sequence Length	16	32	64	128	
Identity	0.9686 ± 0.0000	0.9941 ± 0.0000	1.0563 ± 0.0000	1.0987 ± 0.0000	
MHN	0.3361 ± 0.0000	0.3315 ± 0.0000	0.3650 ± 0.0000	0.3957 ± 0.0000	
BayesPCN	0.0000 ± 0.0000	0.0001 ± 0.0000	0.0001 ± 0.0000	0.0006 ± 0.0000	

Mask Tiny ImageNet MSE					
Sequence Length 16 32 64 128					
Identity	1.0019 ± 0.0000	1.0606 ± 0.0000	1.1370 ± 0.0000	1.0597 ± 0.0000	
MHN	0.4534 ± 0.0000	0.4896 ± 0.0000	0.7033 ± 0.0000	0.6378 ± 0.0000	
BayesPCN	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000	

Table 3: Average MSE between the training images and the associative memory *read* outputs for the high query noise white noise, dropout, and mask tasks on CIFAR10 and Tiny ImageNet datasets.





Figure 4: Sample MHN (left) and BayesPCN (right) read outputs for the white noise ($\sigma = 0.8$), pixel dropout (75%), and pixel masking (75%) tasks. The top row contains the memory read inputs and the bottom row contains the memory read outputs.

H Additional Qualitative Results

Figure 5 qualitatively demonstrates how BayesPCN's read scales with the number of stored datapoints for the CIFAR10 recall tasks. BayesPCN models are able to output images that are very close to the original image even when the inputs are significantly corrupted. As the number of observations increases, the *read* operation is still able to reconstruct the original image but gets worse at recovering the original image given a corrupted version of it.



Figure 5: Example BayesPCN recall result from the CIFAR10 auto-associative and hetero-associative tasks. From top to bottom rows are the comparisons of BayesPCN's *read* inputs and outputs where the task is to recover the first observation seen during the *write* phase (the top left frog image) after sequentially observing 127, 255, 511, and 1023 additional datapoints.

I Effects of BayesPCN Hyperparameters

I.1 Network Width and Depth

Figure 6 and Table 4 illustrate how BayesPCN's recall accuracy and MSE scale with the network width and depth. A recall is considered correct if the MSE between the ground truth and the recalled data is less than 0.01. BayesPCN models had GELU activation functions, $\sigma_W = 1$, $\sigma_x = 0.01$, and a single particle.

We found that the increased network width was helpful across all tasks. Increased network depth was helpful when moving from network depth of 2 to 4, but moving from network depth of 4 to 8 had no noticeable impact across all tasks. We note that because the Figure 6 depicts recall accuracy not MSE, if the memory performance generally declines and the average recall MSE exceeds 0.01, this can lead to very low accuracy even if the actual recall MSE is not much greater than 0.01.

I.2 Network Weight Prior Uncertainty and Observation Noise

We also investigate the effect of σ_W and σ_x hyperparameters on BayesPCN's scaling properties. Since σ_W determines the prior uncertainty and σ_x determines the observation noise, higher σ_W and lower σ_x reduces the prior's impact and increases the new observation's impact on the network weight's posterior. Hence, we can control the memory *write* strength by modulating σ_W , σ_x .

Table 5 describes the CIFAR10 recall results of nine structurally identical BayesPCN models with four hidden layers of size 1024, a single particle, and GELU activations but with different values of σ_W and σ_x . We observe that lower σ_W and higher σ_x tend to alleviate the memory overloading behaviour. We hypothesize that this is the case because lower σ_W and higher σ_x encourage the synaptic weights' Frobenius norms to remain small, causing activation gradient descent more stable.



Figure 6: Recall accuracy of BayesPCN with different network width and depth on CIFAR10 (left) and Tiny ImageNet (right) tasks.

White Noise CIFAR10 MSE				
Sequence Length	128	256	512	1024
BayesPCN L2	0.0284 ± 0.0001	0.0445 ± 0.0000	0.0470 ± 0.0001	0.0830 ± 0.0034
BayesPCN L4	0.0058 ± 0.0001	0.0092 ± 0.0001	0.0146 ± 0.0001	0.0337 ± 0.0007
BayesPCN L8	0.0058 ± 0.0001	0.0092 ± 0.0001	0.0146 ± 0.0000	0.0344 ± 0.0015

White Noise Tiny ImageNet MSE						
Sequence Length	128	256	512	1024		
BayesPCN L2	0.0083 ± 0.0001	0.0096 ± 0.0001	0.0178 ± 0.0001	0.3458 ± 0.1281		
BayesPCN L4	0.0020 ± 0.0001	0.0037 ± 0.0001	0.0066 ± 0.0002	12.4499 ± 1.1542		
BayesPCN L8	0.0020 ± 0.0001	0.0036 ± 0.0001	0.0065 ± 0.0002	13.8584 ± 1.3771		

Dropout CIFAR10 MSE							
Sequence Length	128	256	1024				
BayesPCN L2	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0142 ± 0.0000			
BayesPCN L4	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000			
BayesPCN L8	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000			

Dropout Tiny ImageNet MSE							
Sequence Length	128	256	512	1024			
BayesPCN L2	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000			
BayesPCN L4	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000			
BayesPCN L8	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0006 ± 0.0006			

Mask CIFAR10 MSE							
Sequence Length	128	256	512	1024			
BayesPCN L2	0.0000 ± 0.0000	0.0002 ± 0.0000	0.0081 ± 0.0027	0.1024 ± 0.0001			
BayesPCN L4	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000	0.0019 ± 0.0000			
BayesPCN L8	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000	0.0019 ± 0.0000			

Mask Tiny ImageNet MSE							
Sequence Length	128	256	512	1024			
BayesPCN L2	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0001 ± 0.0000	0.0004 ± 0.0000			
BayesPCN L4	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000			
BayesPCN L8	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000	0.0000 ± 0.0000			

Table 4: Average MSE between the training images and the associative memory *read* outputs for the high query noise white noise, dropout, and mask tasks on CIFAR10 and Tiny ImageNet datasets.

White Noise CIFAR10 MSE								
σ_W	σ_x	16	32	64	128	256	512	1024
0.5	0.05	0.0294	0.0304	0.0304	0.0289	0.0256	0.0222	0.0189
0.5	0.01	0.0012	0.0018	0.0031	0.0052	0.0083	0.0133	0.0213
0.5	0.005	0.0012	0.0018	0.0032	0.0055	0.0095	0.0169	1.859
1.0	0.05	0.0250	0.0264	0.0267	0.0256	0.0230	0.0204	0.0180
1.0	0.01	0.0014	0.0021	0.0036	0.0058	0.0091	0.0146	0.0329
1.0	0.005	0.0011	0.0045	0.0166	0.0325	0.0361	0.0328	2.8281
5.0	0.05	0.0258	0.0285	0.0279	0.0324	0.0814	0.1494	0.7720
5.0	0.01	0.2567	1.0674	1.5191	1.8586	5.7848	13.1495	29.4737
5.0	0.005	0.3738	1.4906	2.2916	3.0278	14.7747	99.3011	79.1281
			Dro	pout CIFA	R10 MSI	F.		
σ_W	σ_{x}	16	32	64	128	256	512	1024
0.5	0.05	0.0001	0.0002	0.0002	0.0004	0.0007	0.0015	0.0025
0.5	0.01	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0001
0.5	0.005	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
1.0	0.05	0.0001	0.0002	0.0002	0.0004	0.0007	0.0015	0.0025
1.0	0.01	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0001
1.0	0.005	0.0000	0.0000	0.0000	0.0000	0.0000	0.0001	0.0262
5.0	0.05	0.0001	0.0001	0.0002	0.0003	0.0005	0.0009	0.0153
5.0	0.01	0.0001	0.0001	0.0001	0.0002	0.0311	0.1426	0.2543
5.0	0.005	0.0000	0.0001	0.0001	0.0002	0.0274	0.1984	0.7999
	1			1.07547				.1
			Ma	ask CIFAI	RIO MSE			1001
σ_W	σ_x	16	32	64	128	256	512	1024
0.5	0.05	0.0002	0.0004	0.0008	0.0017	0.0048	0.0114	0.0239
0.5	0.01	0.0000	0.0000	0.0000	0.0000	0.0000	0.0002	0.0028
0.5	0.005	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0002
1.0	0.05	0.0002	0.0003	0.0007	0.0015	0.0046	0.0112	0.0240
1.0	0.01	0.0000	0.0000	0.0000	0.0000	0.0000	0.0001	0.0019
1.0	0.005	0.0000	0.0000	0.0000	0.0000	0.0000	0.0003	0.2248
5.0	0.05	0.0001	0.0003	0.0005	0.0010	0.0026	0.0061	0.2153
5.0	0.01	0.0000	0.0000	0.0001	0.0002	2 0.1472	0.7554	1.8079
5.0	0.005	0.0000	0.0000	0.0001	0.0001	0.1713	0.8259	6.8712

Table 5: Average MSE between the training images and the associative memory *read* outputs for BayesPCN models with different σ_W, σ_x hyperparameters after observing 16, 32, 64, 128, 256, 512, and 1024 CIFAR10 images.

As an aside, the white noise recall MSE of BayesPCN with $\sigma_x = 0.05$ and $\sigma_W \in \{0.5, 1.0\}$ decreased as more datapoints were observed from sequence length 64 and onward. On visual inspection, we found that the model's auto-associative recall outputs for both observed and unobserved inputs became less blurry as more datapoints were written into memory. We hypothesize that the model learned to generalize at some point of its training.

J BayesPCN Generalization

Figure 7 illustrates BayesPCN's read outputs for unseen image queries after different number of datapoints have been stored into memory. As BayesPCN observes more data, it learns to "generalize" and gets better at reconstructing and even mildly removing white noise from unseen images. This can be attributed to the model continual learning its internal representation that better "describe" the data distribution. We expected this behaviour to occur since S-NCN [Ororbia et al., 2019], a model similar in structure to GPCN, could continually learn to perform discriminative tasks.



Figure 7: BayesPCN's *read* outputs given ground truth (**left**) and noised (**right**) unseen images as inputs after observing 2, 8, 32, 128, 512 training images.

K BayesPCN Sampling

Both GPCN and BayesPCN at the core are as much generative models as they are associative memories. We examine the quality of ancestral sampling samples from both models in Figure 8. When ancestral sampling, BayesPCN did not marginalize out the synaptic weights and instead fixed them to the mean parameters of $p(\mathbf{W}|x_{1:t-1}^0, \mathbf{h}_{1:t-1}^{(n)})$.



(a) GPCN trained on 4 ob-(b) GPCN trained on 1024 (c) BayesPCN trained on 4 (d) BayesPCN trained on servations. observations. 1024 observations.

Figure 8: Ancestral sampling results from GPCN and BayesPCN models trained on CIFAR10.

We find that both GPCN and BayesPCN samples are superpositions of the training images. However, as BayesPCN is trained on more and more observations, its sample quality quickly deteriorates. We hypothesize that the poor sample quality for both GPCN and BayesPCN stems from the approximate nature of their parameter estimation. For example, BayesPCN's particle count would have to be much greater than 4 to accurately capture the true posterior $p(\mathbf{W}|x_{1:t-1}^0)$ using its sequential importance sampling estimate and the variational distribution over the hidden activations should not be Dirac distributed. However, we note that Ororbia and Kifer [2022] has successfully trained predictive coding networks to be good generative models.