Overparameterization Improves Robustness to Covariate Shift in High Dimensions

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Abstract

A significant obstacle in the development of robust machine learning models is *covariate shift*, a form of distribution shift that occurs when the input distributions of the training and test sets differ while the conditional label distributions remain the same. Despite the prevalence of covariate shift in real-world applications, a theoretical understanding in the context of modern machine learning has remained lacking. In this work, we examine the exact high-dimensional asymptotics of random feature regression under covariate shift and present a precise characterization of the limiting test error, bias, and variance in this setting. Our results motivate a natural partial order over covariate shifts that provides a sufficient condition for determining when the shift will harm (or even help) test performance. We find that overparameterized models exhibit enhanced robustness to covariate shift, providing one of the first theoretical explanations for this ubiquitous empirical phenomenon. Additionally, our analysis reveals an exact linear relationship between the in-distribution and out-of-distribution generalization performance, offering an explanation for this surprising recent observation.

1 Introduction

Theoretical justification for almost all machine learning methods relies upon the equality of the distributions from which the training and test data are drawn. Nevertheless, in many real-world applications, this equality is violated—naturally-occurring distribution shift between the training data and the data encountered during deployment is the rule, not the exception [31]. Even *non-adversarial* changes in distributions can uncover the surprising fragility of modern machine learning models [55, 56, 43, 26, 12, 50]. Such shifts are distinct from adversarial examples, which require explicit poisoning attacks [22]; rather, they can result from mild corruptions, ranging from changes of camera angle or blur [26], to subtle, unintended changes in data acquisition procedures [56]. Moreover, this fragility limits the application of deep learning in certain safety-critical areas [31].

Empirical studies of distribution shift have observed several intriguing phenomena, including linear trends between model performance on shifted and unshifted test distributions [56, 26, 31], dramatic degradation in calibration [50], and surprising spurious inductive biases [12]. Theoretical understanding of why such patterns occur across a variety of real-world domains is scant. Even basic questions such as what makes a certain distribution shift likely to hurt (or help) a model's performance,

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and by how much, are not understood. One reason that these phenomena have eluded theoretical understanding is that there is often a strong coupling between model and distribution, implying that the effect of a given shift cannot usually be understood in a model-agnostic way. Another reason that satisfactory explanations have remained lacking is that the go-to formalism for studying generalization in classical models, namely uniform convergence theory (see e.g. [66]), may be insufficient to explain the behavior of modern deep learning methods (even in the absence of distribution shift) [47, 68]. Indeed, classical measures of model complexity, such as various norms of the parameters, have been found to lead to ambiguous conclusions [49].

In this paper, we follow a different approach: instead of focusing on worst-case bounds for generic distributions, we study average-case behavior for narrowly specified distributions. While this change in perspective sacrifices generality, it allows us to derive more precise predictions, which we believe are necessary to fully capture the relevant phenomenology. We study a specific type of distribution shift called covariate shift, in which the distributions of the training and test covariates differ, while the conditional distribution of the labels given the covariates remains fixed. Using random matrix theory, we perform an asymptotically exact computation of the generalization error of random feature regression under covariate shift. The random feature model provides a useful testbed to (1) investigate the interplay between various factors such as model complexity, label noise, bias, variance, and covariate shift; (2) rigorously define a *model-agnostic* notion for the strength of covariate shift; and (3) provide a theoretical explanation for the linear relationships recently observed between in-distribution and out-of-distribution generalization performance [55, 56, 27].

1.1 Contributions

Our primary contributions are to:

- 1. Provide a *model-agnostic* partial order over covariate shifts that is sufficient to determine when a shift will increase or decrease the test error in random feature regression (see Def. 4.1);
- 2. Compute the test error, bias, and variance of random feature regression for general multivariate Gaussian covariates under covariate shift in the high-dimensional limit (see Sec. 5.1);
- 3. Prove that overparameterization enhances robustness to covariate shift, and that the error, bias, and variance are nonincreasing functions of the number of excess parameters (see Sec. 5.3);
- 4. Deduce an exact linear relationship between in-distribution and out-of-distribution generalization performance, offering an explanation for this surprising recent empirical observation (see Sec. 5.4).

1.2 Related work

There is extensive literature on the empirical analysis of distribution shift in all of its myriad forms, ranging from domain adaptation [62, 20, 8, 70, 69, 37, 36] to defenses against adversarial attacks [39, 60] to distributionally robust optimization [59, 15, 16], among many others. Interestingly, for naturally occurring distribution shifts [31, 26], standard robustness interventions provide little protection [56, 63]. Indeed, empirical risk minimization on clean, unshifted training data often performs better on out-of-distribution benchmarks than more sophisticated methods [31]. One of the most striking observations in the context of natural distribution shifts is that model robustness improves with the classifier's accuracy [56, 63, 26, 43]. For example, if a classifier's accuracy increases by 1.0% on the unshifted CIFAR-10 test set, this tends to increase its accuracy by 1.7% on the CIFAR-10.1 dataset (a dataset with natural distribution shift) [56]. Moreover, such linear trends between the unshifted and shifted measures of error have now been observed in several contexts [56, 63, 43, 40, 44].

The number of theoretical works studying the impact of distribution shift on generalization is far smaller. One pioneering work provides VC-dimension-based error bounds for classification that are augmented by a discrepancy measure between source and target domains [10], while another demonstrates a similar class of uniform convergence-based results in the setting of kernel regression [11]. Recent work shows that learning domain-invariant features is insufficient to guarantee generalization when the class-conditional distributions of features may shift [69]. When the source domain gradually shifts toward the target domain, non-vacuous margin-based bounds for self-training can be established [32]. In [40], assumptions based on model similarity are used to help explain why classifiers exhibit linear trends between their accuracies on shifted and unshifted test sets [56, 43].

Our technical tools build on a series of works that have studied the exact high-dimensional limit of the test error for a growing class of model families and data distributions. In the context of linear models, recent work analyzes ridge regression for general covariances and a general non-isotropic source condition on the parameters which generate the targets [57], extending earlier work studying minimum-norm interpolated least squares and ridge regression in the random design setting [9, 14, 24]. The non-isotropy of source parameter effectively induces a shift on the bias term of this model, but the phenomenon is distinct from the covariate shifts we study here. Beyond linear regression, random feature models provide a rich but tractable class of models to gain further insight into generalization phenomena [2, 3, 41, 35]. These methods are of particular interest because of their connection to neural networks, with the number of random features corresponding to the network width (or model complexity) [48, 33, 29], and because they serve as a practical method for data analysis in their own right [54, 61]. In this context, a precise characterization of the gaps between uniform convergence and the (asymptotic) exact test error as a function of the sample size and number of random features can be derived [68]. Since this paper's publication, we released follow-up work considering unequal scales in the training and test distributions and optimal regularization [64]. From the technical perspective, our analytic techniques build upon these works and a series of recent results stemming from the literature on random matrix theory and free probability [53, 52, 1, 2, 38, 51, 19, 45].

2 Preliminaries

2.1 Problem setup and notation

As in prior work studying random feature regression [24, 41, 2, 1], we compute the test error in the high-dimensional, proportional asymptotics where the dataset size m, input feature dimension n_0 , and hidden layer size n_1 all tend to infinity at the same rate, with $\phi := n_0/m$ and $\psi := n_0/n_1$ held fixed. We refer to ϕ/ψ as the *overparameterization ratio*, which is the limit of n_1/m and characterizes the normalized complexity of the (random) feature model.

Interestingly, in this high-dimensional limit, the conditional distribution of a linear labeling function is asymptotically equivalent to a wide class of nonlinear teacher functions (see [41, 2] for more details). With this in mind, we consider the task of learning an unknown function from m i.i.d. samples $(\mathbf{x}_i, y_i) \in \mathbb{R}^{n_0} \times \mathbb{R}$ for $i \in \{1, \dots, m\}$, where the covariates are Gaussian, $\mathbf{x}_i \sim \mathcal{N}(0, \Sigma)$ with positive definite covariance matrix Σ , and the labels are generated by a linear function parameterized by $\beta \in \mathbb{R}^{n_0}$, drawn from $\mathcal{N}(0, I_{n_0})$. In particular

$$y(\mathbf{x}_i) = \beta^{\top} \mathbf{x}_i / \sqrt{n_0} + \epsilon_i, \tag{1}$$

where $\epsilon_i \sim \mathcal{N}(0, \sigma_\epsilon^2)$ is additive label noise on the training points.

We study the class of prediction models defined by kernel ridge regression using unstructured random feature maps [54]. The random features are given by a single-layer, fully-connected neural network with random weights. Given a set of training data $X = [\mathbf{x}_1, \dots, \mathbf{x}_m]$ and a prospective test point \mathbf{x} , the random features embeddings of the training and test data are given by

$$F := \sigma(WX/\sqrt{n_0}) \quad \text{and} \quad f := \sigma(W\mathbf{x}/\sqrt{n_0}), \tag{2}$$

for a random weight matrix $W \in \mathbb{R}^{n_1 \times n_0}$ with i.i.d. standard Gaussian entries and an activation function $\sigma : \mathbb{R} \to \mathbb{R}$ applied elementwise. The induced kernel is

$$K(\mathbf{x}_1, \mathbf{x}_2) := \frac{1}{n_1} \sigma(W \mathbf{x}_1 / \sqrt{n_0})^{\top} \sigma(W \mathbf{x}_2 / \sqrt{n_0}),$$
(3)

and the model's predictions are given by $\hat{y}(\mathbf{x}) = YK^{-1}K_{\mathbf{x}}$, where $Y := [y(\mathbf{x}_1), \dots, y(\mathbf{x}_m)]$, $K := K(X, X) + \gamma I_m$, $K_{\mathbf{x}} := K(X, \mathbf{x})$, and $\gamma \ge 0$ is a ridge regularization constant¹. Owing to the implicit regularization effect of the nonlinear feature maps [7], in low noise settings the optimal value of γ can sometimes be negative [30]. For simplicity, we nevertheless make the standard assumption that $\gamma \ge 0$, though we emphasize our techniques readily accommodate negative values.

¹We overload the definition of K to include the additive regularization whenever no arguments are present. Also, if $\gamma = 0$ and K is not full-rank, K^{-1} should be understood as the Moore–Penrose pseudoinverse.

Our central object of study is the expected test loss for a datapoint $\mathbf{x} \sim \mathcal{N}(0, \Sigma^*)$ where Σ^* may be different from the training covariance Σ . The test error (without label noise on the test point) is

$$E_{\Sigma^*} = \mathbb{E}[(\beta^\top \mathbf{x} / \sqrt{n_0} - YK^{-1}K_{\mathbf{x}})^2]$$
(4)

$$= \underbrace{\mathbb{E}_{\mathbf{x},\beta}[(\mathbb{E}[\hat{y}(\mathbf{x})] - y(\mathbf{x}))^2]}_{B_{\Sigma^*}} + \underbrace{\mathbb{E}_{\mathbf{x},\beta}[\mathbb{V}[\hat{y}(\mathbf{x})]]}_{V_{\Sigma^*}}, \tag{5}$$

where the inner expectations defining the bias and variance are computed over W, X, and Y. We decompose the training and test covariance matrices into eigenbases as $\Sigma = \sum_{i=1}^{n_0} \lambda_i \mathbf{v}_i \mathbf{v}_i^{\top}$ and $\Sigma^* = \sum_{i=1}^{n_0} \lambda_i^* \mathbf{v}_i^* \mathbf{v}_i^{*\top}$, where the eigenvalues are in nondecreasing magnitude, i.e. $\lambda_1 \leq \lambda_2 \leq \ldots \leq \lambda_{n_0}$ and $\lambda_1^* \leq \lambda_2^* \leq \ldots \leq \lambda_{n_0}^*$. We define the *overlap coefficients*

$$r_i := \mathbf{v}_i^{\mathsf{T}} \Sigma^* \mathbf{v}_i = \sum_{j=1}^{n_0} (\mathbf{v}_j^* \cdot \mathbf{v}_i)^2 \lambda_j^*$$
 (6)

to measure the alignment of Σ^* with the ith eigendirection of Σ . In particular, r_i is the induced norm of \mathbf{v}_i with respect to Σ^* . We use $\bar{\operatorname{tr}}$ to denote the dimension-normalized trace: for a matrix $A \in \mathbb{R}^{n \times n}$, $\bar{\operatorname{tr}}(A) = \frac{1}{n} \operatorname{tr}(A)$. We use $\|A\|_{\infty}$ and $\|A\|_F$ to denote the operator norm and Frobenius norm of matrix A respectively. Finally, we use $\delta_{\mathbf{x}}$ to denote the Dirac delta function centered at \mathbf{x} .

2.2 Assumptions

Regularity assumptions on the spectra of Σ and Σ^* are necessary to state the limiting behavior of this system. As in [67], it is not sufficient to consider the spectra of these matrices individually; they must be considered jointly. We do this in an eigenbasis of Σ .

Assumption 1. We define the empirical joint spectral distribution (EJSD) as

$$\mu_{n_0} := \frac{1}{n_0} \sum_{i=1}^{n_0} \delta_{(\lambda_i, r_i)} \tag{7}$$

and assume it converges in distribution to some μ , a distribution on \mathbb{R}^2_+ as $n_0 \to \infty$. We refer to μ as the limiting joint spectral distribution (LJSD), and emphasize that this defines the relevant limiting properties of the train and test distributions². Additionally, we require that $\limsup_{n_0} \max(\|\Sigma\|_{\infty}, \|\Sigma^*\|_{\infty}) \le C$ for a constant C.

Often we use (λ, r) for random variables sampled jointly from μ and denote the marginal of λ under μ with μ_{train} . The conditional expectation $\mathbb{E}[r|\lambda]$ is an important object in our study. We frequently overload the notation $\mathbb{E}[r|\lambda]$ to view it as a function of λ , and we assume the following for simplicity.

Assumption 2. μ is either absolutely continuous or a finite sum of delta masses. Moreover, the expectations of λ and r are finite.

When the eigenspaces of Σ and Σ^* are aligned and $r_i = \lambda_i^* = \Phi(\lambda_i)$ for some smooth function Φ , the support of the LJSD degenerates. Here, Assump. 1 is essentially equivalent to assuming the empirical spectral distribution of Σ converges in distribution to some μ_{train} , which is a standard assumption in the regression literature [14, 41]. One special case of note is when there is no shift, i.e. Φ is the identity, in which case the LJSD degenerates to μ_{\emptyset} defined by

$$\mu_{\emptyset}(\lambda, r) := \mu_{\text{train}}(\lambda)\delta_{\lambda}(r), \quad i.e. \quad (\lambda, \lambda) \sim \mu_{\emptyset} \quad \text{for } \lambda \sim \mu_{\text{train}}.$$
 (8)

As our analysis will eventually take place in the high-dimensional limit, we further define the asymptotic scales of the training and test covariances as $s:=\lim_{n_0\to\infty} \bar{\mathrm{tr}}(\Sigma)=\mathbb{E}_{\mu}[\lambda]$ and $s_*:=\lim_{n_0\to\infty} \bar{\mathrm{tr}}(\Sigma^*)=\mathbb{E}_{\mu}[r]$ under the limiting behavior specified in Assump. 1.

Throughout this paper, we also enforce the following standard regularity assumptions on the activation functions to ensure the existence of the moments and derivatives we compute.

Assumption 3. The activation function $\sigma : \mathbb{R} \to \mathbb{R}$ is assumed to be differentiable almost everywhere. We assume that, $|\sigma(x)|, |\sigma'(x)| \le c_0 \exp(c_1 x)$ for constants c_0, c_1 .

²Note that the EJSD depends not only on Σ and Σ^* but also on a choice of eigendecomposition for Σ when it has repeated eigenvalues. However, all possible choices for the EJSD form an equivalence class, and the ambiguity does not affect later definitions and conclusions. See Sec. A3.

2.3 A simple family of diatomic distributions

As the above assumptions allow such a general class of covariance structures, it is useful to consider our results in the context of a simple family of distributions that readily admits a simple interpretation.

Definition 2.1. For $\alpha \geq 1$ and $\theta \in \mathbb{R}$, we define the family of (α, θ) -diatomic LJSDs with θ -power-law shifts as

$$\mu_{\alpha,\theta}^{diatomic} := \frac{1}{\alpha+1} \delta_{(\alpha,C\alpha^{\theta})} + \frac{\alpha}{\alpha+1} \delta_{(\alpha^{-1},C\alpha^{-\theta})}, \tag{9}$$

where C is a normalization constant chosen so that $\mathbb{E}_{\mu_{lpha, \theta}^{diatomic}}[r]=1$. Note that $\mu_{lpha, \theta}^{diatomic}$ is the limit of

$$\Sigma_{ij} := \begin{cases} \alpha & \text{if } i = j \text{ and } i \leq \lfloor \frac{n_0}{1+\alpha} \rfloor \\ \alpha^{-1} & \text{if } i = j \text{ and } i > \lfloor \frac{n_0}{1+\alpha} \rfloor \end{cases} \quad \text{and} \quad \Sigma^* := \frac{1}{\bar{\operatorname{tr}}(\Sigma^{\theta})} \Sigma^{\theta} . \tag{10}$$

This simple two-parameter family of distributions captures the fast eigenvalue decay observed in many datasets in machine learning, for which the covariance spectra are often dominated by several large eigenvalues and exhibit a long tail of many small eigenvalues [34]. Note that the trivial case of $\alpha=1$ yields an identity covariance with no shift. For the nontrivial setting $\alpha>1$, the exponent θ parameterizes the strength of the shift in an intuitive way: when $\theta=1$, there is no shift; when $\theta<1$, $\alpha^{\theta}<\alpha$, so the large eigendirections of the training distribution are suppressed in the test distribution, suggesting that the shift makes learning harder; when $\theta>1$, $\alpha^{\theta}>\alpha$, so the large eigendirections of the training distribution are further emphasized in the test distribution, suggesting that the shift makes learning easier. We will return to the notion of shift strength in Secs. 3 and 4.

3 Motivating example: linear regression

We first consider the relatively simple case of ridgeless linear regression (LR), which will help build some intuition for the more general analysis of random feature regression in Sec. 5.1. Assuming the labels are generated by the linear model defined above, i.e. $y_i = \beta^{\top} \mathbf{x}_i / \sqrt{n_0} + \varepsilon_i$, the estimator is given by $\hat{\beta} = (XX^{\top})^{-1}XY$, and the test risk (see Eq. (4)) has the following simple form.

Proposition 3.1. For fixed dimension n_0 and sample size $m > n_0 + 1$, the test error of LR is given by

$$E_{\Sigma^*}^{LR} = \sigma_{\epsilon}^2 \frac{n_0}{m - n_0 - 1} \bar{\text{tr}}(\Sigma^* \Sigma^{-1}) = \sigma_{\epsilon}^2 \frac{n_0}{m - n_0 - 1} \frac{1}{n_0} \sum_{i=1}^{n_0} \frac{r_i}{\lambda_i}.$$
 (11)

Under Assump. 1, as $n_0, m \to \infty$ with $\phi = n_0/m$ fixed, $E_{\Sigma^*}^{LR} \to E_{\mu}^{LR} = \sigma_{\epsilon}^2 \phi/(1-\phi) \mathbb{E}_{\mu}[r/\lambda]$.

One immediate question is whether a given shift will increase or decrease the test error relative to E_{Σ}^{LR} . While the precise answer is of course determined by the value of $\bar{\text{tr}}(\Sigma^*\Sigma^{-1})$, it useful for the subsequent analysis to develop an understanding of the individual contributions to this term. Similar decompositions of the test error into eigenspaces have proved useful in a variety of other contexts, e.g. [42, 4]. We begin with a specific example in the setting of the finite-dimensional analog of Def. 2.1.

Example 3.1. For the finite form of the (α, θ) -diatomic density defined in Eq. (10), the test error of LR is given by

$$E_{\Sigma^*}^{LR} = \sigma_{\epsilon}^2 \frac{n_0}{m - n_0 - 1} \frac{\alpha + w(\alpha^{2\theta - 1} - \alpha)}{1 + w(\alpha^{2\theta} - 1)} \quad for \quad w = \frac{1}{n_0} \left\lfloor \frac{n_0}{1 + \alpha} \right\rfloor , \tag{12}$$

and so $\frac{\partial}{\partial \theta} E_{\Sigma^*}^{LR} = \sigma_{\epsilon}^2 \frac{n_0}{m - n_0 - 1} \frac{2(1 - w)w\alpha^{2\theta - 1}(1 - \alpha^2)\log(\alpha)}{(1 + w(\alpha^{2\theta} - 1))^2} \leq 0$, which implies $E_{\Sigma_1^*}^{LR} \leq E_{\Sigma_2^*}^{LR}$ whenever $\theta_1 \geq \theta_2$, in accordance with the discussion in Sec. 2.3. It follows from Eq. (10) that the condition $\theta_1 \geq \theta_2$ not only implies $\operatorname{tr}(\Sigma_1^* \Sigma^{-1}) \leq \operatorname{tr}(\Sigma_2^* \Sigma^{-1})$, but also that the ratios of overlap coefficients $r_{i,1}/r_{i,2}$ form a nondecreasing sequence. It is this condition involving all the eigendirections that will generalize to the nonlinear random feature setting in Sec. 4.

The following proposition captures the essence of these considerations in the context of linear regression. See Sec. A4 for the proof.

Proposition 3.2. Let $r_{i,1}$ and $r_{i,2}$ denote the overlap coefficients³ of Σ_1^* and Σ_2^* relative to Σ . If $\operatorname{tr}(\Sigma_2^*) \geq \operatorname{tr}(\Sigma_1^*)$ and the ratios $r_{i,1}/r_{i,2}$ form a nondecreasing sequence, then in the setting of Prop. 3.1, $E_{\Sigma_2^*}^{LR} \geq E_{\Sigma_1^*}^{LR}$.

Whereas the (α, θ) -diatomic LJSDs explicitly enforce the trace normalizations $\operatorname{tr}(\Sigma) = \operatorname{tr}(\Sigma_1^*) = \operatorname{tr}(\Sigma_2^*) = 1$, Prop. 3.2 provides sufficient conditions for the ordering of test errors for non-unit traces. The fact that $E_{\Sigma^*}^{LR}$ scales linearly with the overall scale of Σ^* is a unique feature of linear regression and does not generalize to the nonlinear random feature setting. We return to this issue in Sec. 4.

4 Definition of shift strength

Deriving conditions on whether a shift will hurt or help a model's performance is crucial to building an understanding of covariate shift. Motivated in part by the above results for linear regression, and in part by the results for random feature regression that we present in Sec. 5.3, we introduce the following definition of shift strength, which is a direct generalization of the conditions of Prop. 3.2:

Definition 4.1. Let μ_1 and μ_2 be LJSDs with the same marginal distribution of λ , denoted μ_{train} . If the asymptotic overlap coefficients are such that $\mathbb{E}_{\mu_1}[r|\lambda]/\mathbb{E}_{\mu_2}[r|\lambda]$ is nondecreasing as a function of λ on the support of μ_{train} and $\mathbb{E}_{\mu_1}[r] \leq \mathbb{E}_{\mu_2}[r]$, we say μ_1 is easier than μ_2 (or μ_2 is harder than μ_1), and write $\mu_1 \leq \mu_2$. Comparing against the case of no shift μ_0 , we say μ_1 is easy when $\mu_1 \leq \mu_0$ and hard when $\mu_1 \geq \mu_0$.

A priori, there is little reason to hope that such a *model-independent* definition of shift strength would adequately characterize a shift's impact on the total error, bias, or variance of a given model. Even for the relatively simple case of random feature kernel regression, the nonlinear feature maps of Eq. (2) would seem to inextricably couple the covariance distribution to the model.

Nevertheless, as we show in Sec. 5.1, the coupling between model and shift simplifies considerably in the high-dimensional proportional asymptotics. It is characterized by a handful of constants that depend solely on the overall covariance scale $\mathbb{E}_{\mu}[r]$ and a collection of functionals of μ , whose magnitudes can be bounded in terms of the ratio $\mathbb{E}_{\mu}[r|\lambda]/\mathbb{E}_{\mu_{\emptyset}}[r|\lambda]$. The conditions that Def. 4.1 places on $\mathbb{E}_{\mu}[r]$ and $\mathbb{E}_{\mu}[r|\lambda]/\mathbb{E}_{\mu_{\emptyset}}[r|\lambda]$ can be augmented by various constraints on the model to derive bounds on how the total error and bias will respond to a shift of a given strength. This perspective introduces considerable complexity and we present the details of this analysis elsewhere.

In this work, we focus on a simpler, surprising result: by merely normalizing the scales of the covariate distributions (i.e. enforcing $s = s_*$), Def. 4.1 provides a *model-independent* definition of shift strength that determines how random feature models respond to shifts of different strength. This observation motivates the following assumption.

Assumption 4. The training and test covariance scales are equal, $\mathbb{E}_{\mu}[\lambda] = \mathbb{E}_{\mu}[r]$, i.e. $s = s_*$.

We emphasize that Assump. 4 reflects common practice for many models and data modalities, as preprocessing techniques such as standardization are ubiquitous and many architectural components such as layer- or batch-normalization achieve a similar effect [21, 28, 46].

5 Covariate shift in random feature kernel regression

5.1 Main results

Our main results characterize the high-dimensional limits of the test error, bias, and variance of the nonlinear random feature model of Sec. 2. Before stating them, we first introduce some additional constants that capture the effect of the nonlinearity σ . For $z \sim \mathcal{N}(0,s)$, define

$$\eta := \mathbb{V}[\sigma(z)], \quad \rho := \left(\frac{1}{s}\mathbb{E}[z\sigma(z)]\right)^2, \quad \zeta := s\rho, \quad \text{and} \quad \omega := s(\eta/\zeta - 1).$$

Our results also depend on the covariance spectra through two sets of functionals of μ ,

$$\mathcal{I}_{a,b}(x) := \phi \, \mathbb{E}_{\mu} \left(\lambda^a \left(\phi + x \lambda \right)^{-b} \right) \quad \text{and} \quad \mathcal{I}_{a,b}^*(x) := \phi \, \mathbb{E}_{\mu} \left(r \lambda^{a-1} \left(\phi + x \lambda \right)^{-b} \right). \tag{14}$$

³Recall the definition of the overlap coefficients in Eq. (6).

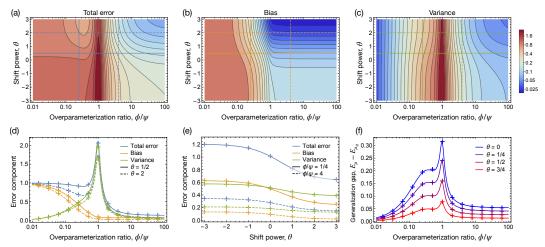


Figure 1: The asymptotic predictions of Thm. 5.1 as a function of the overparameterization ratio $(\phi/\psi=n_1/m)$ and the shift power (θ) for the $(2,\theta)$ -diatomic LJSD (Eq. (9)) with $\phi=n_0/m=0.5$, $\sigma=\text{ReLU}, \gamma=0.001$, and $\sigma_\varepsilon^2=0.1$. (a) The test error exhibits the characteristic double descent behavior for all shift powers. (b) The bias is a nonincreasing function of ϕ/ψ for all shift powers, as in Prop. 5.2. (c) The variance is the source of the double-descent peak, and is a nonincreasing function of ϕ/ψ for all shift powers in the overparameterized regime, as in Prop. 5.3. In (a,b), the total error and bias are nonincreasing functions of θ , as in Prop. 5.1. (d) 1D horizontal slices of (a,b,c) demonstrate the monotonicity in ϕ/ψ predicted by Props. 5.2 and 5.3. (e) 1D vertical slices of (a,b,c) demonstrate the monotonicity in θ predicted by Prop. 5.1 (the variance also appears monotonic, but it need not be in general). (f) The generalization gap between the error on shifted and unshifted distributions is a nonincreasing function of ϕ/ψ in the overparameterized regime, as in Prop. 5.4. Markers in (d,e,f) show simulations for $n_0=512$ and agree well with the asymptotic predictions.

Theorem 5.1. Under Assumps. 1, 2, 3 and 4, as $n_0, n_1, m \to \infty$ the test error E_{Σ^*} converges to $E_{\mu} = B_{\mu} + V_{\mu}$, with the bias B_{μ} and variance V_{μ} given by

$$B_{\mu} = \phi \mathcal{I}_{1,2}^{*}$$

$$V_{\mu} = -\rho \frac{\psi}{\phi} \frac{\partial x}{\partial \gamma} \left(\mathcal{I}_{1,1}(\omega + \phi \mathcal{I}_{1,2})(\omega + \mathcal{I}_{1,1}^{*}) + \frac{\phi^{2}}{\psi} \gamma \bar{\tau} \mathcal{I}_{1,2} \mathcal{I}_{2,2}^{*} \right)$$

$$+ \gamma \tau \mathcal{I}_{2,2}(\omega + \phi \mathcal{I}_{1,2}^{*}) + \sigma_{\varepsilon}^{2} \left((\omega + \phi \mathcal{I}_{1,2})(\omega + \mathcal{I}_{1,1}^{*}) + \frac{\phi}{\psi} \gamma \bar{\tau} \mathcal{I}_{2,2}^{*} \right) ,$$

$$(15)$$

where x is the unique nonnegative real root of $x=\frac{1-\gamma\tau}{\omega+\mathcal{I}_{1,1}}$, $\frac{\partial x}{\partial \gamma}=-\frac{x}{\gamma+\rho\gamma(\tau\psi/\phi+\bar{\tau})(\omega+\phi\mathcal{I}_{1,2})}$, and

$$\tau = \frac{\sqrt{(\psi - \phi)^2 + 4x\psi\phi\gamma/\rho} + \psi - \phi}{2\psi\gamma} \quad and \quad \bar{\tau} = \frac{1}{\gamma} + \frac{\psi}{\phi} \left(\tau - \frac{1}{\gamma}\right). \tag{17}$$

Numerical predictions from Thm. 5.1 can be obtained by first solving the self-consistent equation for x by fixed-point iteration, $x \mapsto \frac{1-\gamma\tau}{\omega+\mathcal{I}_{1,1}}$, and then plugging the result into the remaining terms. Fig. 1 shows excellent agreement between these asymptotic predictions and finite-size simulations.

At times we will find it convenient to consider the ridgeless limit of Thm. 5.1. By carefully expanding x and τ for small γ , it is straightforward to obtain the following corollary.

Corollary 5.1. In the setting of Thm. 5.1, as the ridge regularization constant $\gamma \to 0$, $E_{\mu} = B_{\mu} + V_{\mu}$ with B_{μ} given in Eq. (15) and V_{μ} given by

$$V_{\mu} = \frac{\psi}{|\phi - \psi|} x(\sigma_{\varepsilon}^{2} + \mathcal{I}_{1,1})(\omega + \mathcal{I}_{1,1}^{*}) + \begin{cases} x\left(1 - \frac{x(\omega - \sigma_{\varepsilon}^{2})}{1 - x^{2}\mathcal{I}_{2,2}}\right)\mathcal{I}_{2,2}^{*} & \phi \geq \psi\\ \frac{x^{2}\psi\mathcal{I}_{2,2}}{\phi - x^{2}\psi\mathcal{I}_{2,2}}\left(\omega + \phi\mathcal{I}_{1,2}^{*}\right) & \phi < \psi \end{cases},$$
(18)

where x is the unique positive real root of $x = \frac{\min(1, \phi/\psi)}{\omega + \mathcal{I}_{1,1}}$.

Taking $\sigma(x) = x$ and $\psi \to 0$ in Cor. 5.1 yields an expression for the test error of ridgeless linear regression that agrees with [24] and with the asymptotic form of Prop. 3.1 (see Sec. A4.2).

5.2 Harder shifts increase the bias and test error

The bias and variance in Thm. 5.1 depend on the covariate shift exclusively through $\mathcal{I}_{a,b}^*$ — all other terms such as x, τ , $\bar{\tau}$, and $\mathcal{I}_{a,b}$ only depend on the marginal of λ under μ . The functionals $\mathcal{I}_{a,b}^*$ generalize the simple ratio of overlap coefficients to eigenvalues, $\mathbb{E}_{\mu}[r/\lambda]$, that characterizes the error for linear regression (indeed, $\mathcal{I}_{0,0}^* = \phi \mathbb{E}_{\mu}[r/\lambda]$). In contrast, the error in the random feature setting is a combination of multiple such terms. Nevertheless, Def. 4.1 enables comparisons of the individual $\mathcal{I}_{a,b}^*$ functionals, which provide sufficient conditions to order the error and bias.

Proposition 5.1. Consider two LJSDs such that $\mu_1 \leq \mu_2$ (see Def. 4.1). Then, in the setting of Thm. 5.1, $B_{\mu_1} \leq B_{\mu_2}$ and, if $\sigma_{\varepsilon}^2 \leq \omega$, $E_{\mu_1} \leq E_{\mu_2}$.

Prop. 5.1 shows that Def. 4.1 provides an essentially model-independent condition to determine the impact of covariate shift on the test error⁴. Interestingly, both the bias (which arises from both regularization and model misspecification) and the total error (which has additional variance contributions from the randomness induced by W, X, and ϵ) respond to shifts in tandem in the regime of small label noise. (For large label noise, the variance can dominate the error and cause violations of monotonicity; see Sec. 5.5.) Prop. 5.1 is illustrated for the (α, θ) -diatomic LJSD in Fig. 1: following the vertical lines upward in (a), (b), or the x-axis rightward in (e) yields easier shifts and a corresponding decrease in the bias and total error.

5.3 The benefit of overparameterization

While Prop. 5.1 shows that harder shifts increase the error, it is natural to wonder whether this increase can be mitigated by judicious model selection. In practice, empirical investigations have shown that the performance of large, overparameterized models tends to deteriorate less under distribution shift than their smaller counterparts [26]. We obtain a number of theoretical results that formally prove the benefit of overparameterization in our random feature setting.

First, we show that the bias decreases (or stays constant) when additional random features are added, which increases the model capacity and accords with the intuition of the bias as a measure of the model's ability to fit the data.

Proposition 5.2. In the setting of Thm. 5.1, the bias B_{μ} is a nonincreasing function of the overparameterization ratio ϕ/ψ .

In contrast to the bias, which is monotonic for all overparameterization ratios, the variance can exhibit nonmonotonic behavior in the underparameterized regime. On the other hand, the following proposition shows that in the overparameterized regime, the variance is also nonincreasing. Note that our proof requires the setting of ridgeless regression ($\gamma=0$), but numerical investigation suggests this condition may not be necessary (see Fig. 1).

Proposition 5.3. In the setting of Cor. 5.1 and in the overparameterized regime (i.e. $\psi < \phi$), the variance V_{μ} is a nonincreasing function of the overparameterization ratio ϕ/ψ .

The explosion of variance at the interpolation threshold and then its subsequent decay have been demonstrated in previous exact asymptotic studies of random feature regression in the absence of covariate shift, in stark contrast to what classical theory would suggest [2, 41]. Prop. 5.3 confirms the existence of analogous behavior under covariate shift.

Taken together, Props. 5.2 and 5.3 imply that some of the benefits of overparameterization extend to models evaluated out-of-distribution. An additional benefit is that overparameterized models are more robust: the difference in error between unshifted and shifted test distributions is smaller for larger models. A formal statement of this enhanced robustness is given in the following result.

Proposition 5.4. Consider two LJSDs such that $\mu_1 \leq \mu_2$ (see Def. 4.1). Then, in the setting of Cor. 5.1 and in the overparameterized regime (i.e. $\psi < \phi$), the generalization gap $E_{\mu_2} - E_{\mu_1}$ is a nonincreasing function of the overparameterization ratio ϕ/ψ .

⁴The weak model-dependence arising from the condition $\sigma_{\varepsilon}^2 < \omega$ can instead be regarded as a small label-noise condition that can always be satisfied for $\omega > 0$, which is true for any nonlinear σ (see Sec. A1).

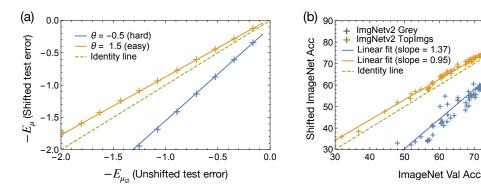


Figure 2: Linear relationship between in-distribution and out-of-distribution generalization error. (a) Asymptotic predictions for shifted versus unshifted error for models with varying degrees of overparameterization $\phi/\psi > 1$, obtained via Cor. 5.1 for the $(3, \theta)$ -diatomic LJSD (Eq. (9)) with $\phi = n_0/m = 0.5$, $\sigma = \text{ReLU}$, $\sigma_{\varepsilon}^2 = 0.01$ and two different values of the shift-power θ . Markers represent simulations for $n_0 = 512$. The negated errors are plotted so that performance improves left to right and bottom to top, in order to match the behavior of the accuracy metric. (b) Reproduction of the empirical results of [56, 63], showing the relationship between the classification accuracy of various models on the original ImageNet test set and two shifted ImageNet datasets: a "hard" dataset with greyscale corruptions, Grey, and an "easy" dataset with high inter-annotator agreement, TopImgs. In both (a) and (b), the slope is greater than one for the hard shift and less than one for the easy shift, in accordance with Prop. 5.5.

In Fig. 1, Props. 5.2, 5.3 and 5.4 are illustrated. Following the horizontal lines rightward in (a), (b), and (c) or the x-axis rightward in (d) and (f) leads to models with more parameters. The monotonicity of the bias across the whole range of parameterization is evident, as is the necessity of considering the monotonicity of the variance and generalization gap only when $\phi > \psi$.

5.4 Linear trends between in-distribution and out-of-distribution generalization

We have discussed how overparameterization yields improvements on both unshifted and shifted test distributions, which hints that these two quantities are positively correlated. Indeed, recent work has suggested increasing model size as a path to increased robustness [26]. Additional empirical studies have further refined this observation by discovering a linear relationship between the performance of models of varying complexity on unshifted and shifted data [56, 63]. In the context of ridgeless random feature regression, we provide a formal proof of this linear relationship.

Proposition 5.5. In the setting of Cor. 5.1 and in the overparameterized regime (i.e. $\psi < \phi$),

$$E_{\mu} = E_0 + \underbrace{\left(\frac{\omega + \mathcal{I}_{1,1}^*}{\omega + \mathcal{I}_{1,1}}\right)}_{\text{SLOPE}} E_{\mu_{\emptyset}}, \qquad (19)$$

70

80

90

parametrically in the overparameterization ratio ϕ/ψ , where E_0 and SLOPE are constants independent of ϕ/ψ , and E_{μ_0} is the error on the unshifted distribution. Moreover, SLOPE ≥ 1 when μ is hard and SLOPE ≤ 1 when μ is easy.

Eq. (19) implies a parametrically linear relationship between E_{μ} and $E_{\mu_{\emptyset}}$ by varying ϕ/ψ . Prop. 5.5 also makes the nontrivial prediction that an improvement on the unshifted distribution leads to a relatively greater improvement on the shifted distribution when the shift is hard, and to a relatively smaller improvement when the shift is easy. This prediction is corroborated qualitatively in the data from [55, 56, 43]. We plot this linear behavior in Fig. 2, where (a) shows the random feature model and (b) shows an example of data from [56, 63]. The striking similarity in these plots is evident.

Importance of assumptions

Props. 5.1, 5.2, 5.3, 5.4 and 5.5 rely on a number of assumptions and conditions; here we show the necessity of some of these prerequisites for our results.

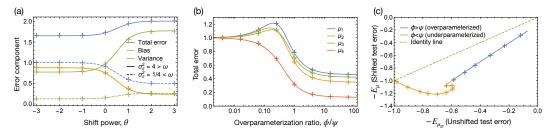


Figure 3: Relaxing the assumptions and conditions can lead to counterexamples to the propositions. (a) Asymptotic predictions (solid lines) and simulations with $n_0=4096$ (markers) for the total error, bias, and variance for the $(4,\theta)$ -diatomic LJSD with $\phi=4$, $\psi=0.25$, $\gamma=10^{-4}$, and $\sigma=\text{ReLU}$ (implying $\omega=1-\frac{2}{\pi}\approx0.36$) as a function of increasing shift power θ . When $\sigma_{\varepsilon}^2<\omega$ (dashed curves), the bias and total error are nonincreasing, as predicted by Prop. 5.1, though the variance is not. When $\sigma_{\varepsilon}^2>\omega$ (solid curves), the total error is no longer nonincreasing. (b) Asymptotic predictions (solid lines) and simulations with $n_0=256$ (markers) for the total error with $\phi=0.5$, $\gamma=0.1$, $\sigma=\text{ReLU}$ and $\sigma_{\varepsilon}^2=0.01$ as a function of the overparameterization ratio ϕ/ψ for four different LJSDs μ_1,\ldots,μ_4 , chosen such that the only comparable pairs of LJSDs under the partial order in Def. 4.1 are $\mu_1\geq\mu_4$ and $\mu_2\geq\mu_4$, and the strict ordering of the error for those pairs is seen for all values of ϕ/ψ . The orange (μ_2) and green (μ_3) curves cross one another, illustrating how nonmonotonicity of overlap ratios in Def. 4.1 can induce model-dependence in the ordering of the error. (c) Asymptotic predictions (solid lines) and simulations for $n_0=512$ (markers) for shifted versus unshifted error for models with varying values of the overparameterization ratio ϕ/ψ , obtained via Thm. 5.1 for the (3,-1/2)-diatomic LJSD with $\phi=0.5$, $\sigma=\text{ReLU}$, $\sigma_{\varepsilon}^2=0.01$, and $\gamma=0.005$. While the relationship is nearly linear in the overparameterized regime, it is markedly nonlinear in the underparameterized regime, highlighting the importance of overparameterization in Prop. 5.5.

Prop. 5.1 relies on a small label-noise condition ($\sigma_{\varepsilon}^2 \leq \omega$) to ensure that the total error is ordered with respect to shift strength. The reason this condition is necessary is that the variance can actually increase as shifts become easier. While Fig. 1 presented a configuration for which the bias, variance, and error all decrease for easier shifts, Fig. 3(a) shows that a decrease is not guaranteed for the variance, and that it can increase even under the small label-noise condition. Moreover, while the bias continues to decrease for large label noise ($\sigma_{\epsilon}^2 > \omega$), the variance can become so large that bias can no longer offset it, causing the error itself to increase, as seen in Fig. 3(a).

The strict ordering of overlap coefficients in Def. 4.1 are also necessary to guarantee a complete decoupling of the model and the shift strength. In the absence of these conditions, Fig. 3(b) shows how even a single out-of-order overlap coefficient induces a violation of the monotonicity with respect to shift strength suggested by Prop. 5.1 (this example is detailed further in Sec. A8).

Finally, we note that the exact linear relationship between in-distribution and out-of-distribution generalization characterized by Prop. 5.5 in Eq. (19) relies crucially on the overparameterization condition, $\psi < \phi$, as evidenced in Fig. 3(c), which shows marked nonlinearity in the underparameterized regime. This observation is perhaps unsurprising, as severely underparameterized models tend towards chance predictions, which produce comparable errors on shifted and unshifted data. Indeed, similar nonlinear behavior is seen in the low-accuracy regime for realistic models [56, Figure 17].

6 Conclusion

We have presented an exact, asymptotic calculation of the test error, bias, and variance for random feature kernel regression in the presence of covariate shift. After defining a partial order over covariate shifts (motivated by the setting of linear regression), we have proved that harder shifts imply increased error. Our results capture many empirical phenomena such as the fact that overparameterization is beneficial even under covariate shift and that a linear relationship exists between the generalization error on shifted and unshifted data. Future directions include extending our results to the non-asymptotic regime, accommodating feature learning and more general neural network models, and investigating the impact of covariate shift for other loss functions.

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Appendix: Overparameterization Improves Robustness to Covariate Shift in High Dimensions

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A1 Useful inequalities

Here we include the statements and proofs of several auxiliary inequalities that we use throughout the Appendix.

A1.1 Basic properties of the self-consistent equation for x

We begin by establishing several basic inequalities. The definitions of the following quantities can be found in Thm. 5.1.

Lemma A1.1. We have the following bounds: $\omega, \tau, \bar{\tau}, x, \mathcal{I}_{a,b} \geq 0$ and $\frac{\partial x}{\partial \gamma} \leq 0$.

Proof. As shown in [53] for the unit-variance case, a simple Hermite expansion argument establishes the relation $\eta \geq \zeta$, which implies $\omega = s(\eta/\zeta - 1) \geq 0$. From Eqs. (A343) and (A344), τ and $\bar{\tau}$ are traces of positive semi-definite matrices and are therefore nonnegative. From the same equations, it follows that $x = \gamma \rho \tau \bar{\tau} \geq 0$. Nonnegativity of x implies $\mathcal{I}_{a,b} \geq 0$ and $\mathcal{I}_{a,b}^* \geq 0$ from their definitions in Eq. (14). Finally, using the nonnegativity of ω , τ , $\bar{\tau}$, x, and $\mathcal{I}_{a,b}$, the expression for $\frac{\partial x}{\partial \gamma}$ in Thm. 5.1 immediately gives,

$$\frac{\partial x}{\partial \gamma} = -\frac{x}{\gamma + \rho \gamma (\frac{\psi}{\phi} \tau + \bar{\tau})(\omega + \phi \mathcal{I}_{1,2})} \le 0. \tag{A1}$$

Next we show that the self-consistent equation $x = \frac{1-\gamma\tau}{\omega+\mathcal{I}_{1,1}}$ appearing in Thm. 5.1 and defined in Eq. (A345) admits a unique positive real solution for x.

Lemma A1.2. There is a unique real $x \ge 0$ satisfying $x = \frac{1 - \gamma \tau}{\omega + \mathcal{I}_{1,1}}$.

Proof. Let $t = 1/x \ge 0$ and define

$$h(t) = t \left(\frac{\rho(\psi - \phi) + \sqrt{\rho^2(\psi - \phi)^2 + 4\gamma\rho\phi\psi/t}}{2\rho\psi} - 1 \right) + \omega + \mathcal{I}_{1,1}(1/t),$$
 (A2)

which is a rewriting of Eq. (A345). It suffices to show that h admits a unique real positive root. To that end, first observe that $\lim_{t\to 0} \mathcal{I}_{1,1}(1/t) = 0$ and $\lim_{t\to \infty} \mathcal{I}_{1,1}(1/t) = s$, so that

$$h(0) = \omega > 0 \quad \text{ and } \quad \lim_{t \to \infty} h(t)/t = -\min\{1, \phi/\psi\} < 0 \,, \tag{A3} \label{eq:A3}$$

which together imply that h has an odd number of positive real roots. Next, we show that h is concave for $t \ge 0$:

$$h''(t) = -\frac{2\phi}{t^3} \left(\frac{\gamma^2 \rho \phi \psi}{(\rho^2 (\psi - \phi)^2 + 4\gamma \rho \phi \psi / t)^{3/2}} + \mathcal{I}_{2,3}(1/t) \right) \le 0,$$
 (A4)

which implies that h has at most two positive real roots. Therefore, we conclude that h has exactly one positive real root.

A1.2 \mathcal{I} and \mathcal{I}^* inequalities

We now establish some useful properties of the \mathcal{I} and \mathcal{I}^* functionals defined in Eq. (14). To begin, we note that simple algebraic manipulations establish the following raising and lowering identities:

$$\mathcal{I}_{a-1,b-1} = \phi \mathcal{I}_{a-1,b} + x \mathcal{I}_{a,b} \quad \text{and} \quad \mathcal{I}_{a-1,b-1}^* = \phi \mathcal{I}_{a-1,b}^* + x \mathcal{I}_{a,b}^*.$$
 (A5)

Next, we consider how the partial order of LJSDs given in Def. 4.1 leads to inequalities on the \mathcal{I}^* functionals. We let $(\mathcal{I}_{a,b}^*)_1$ and $(\mathcal{I}_{a,b}^*)_2$ to denote the corresponding functionals with the LJSDs μ_1 and μ_2 respectively. Similarly, when comparing two different LJSDs we define s_i as the test covariance scale for μ_i for $i \in \{1,2\}$. We can then establish the following useful lemma used in the sequel.

Lemma A1.3. Let $\mu_1 \leq \mu_2$, so μ_2 is harder than μ_1 (recall Def. 4.1). Suppose the functions $f, g, h : \mathbb{R} \to \mathbb{R}$ are such that $f(\lambda) = g(\lambda)h(\lambda)$, where $g(\lambda)$ is nonnegative and $h(\lambda)$ is nonincreasing for all $\lambda > 0$, then

$$\frac{\mathbb{E}_{\mu_1}[rf(\lambda)]}{\mathbb{E}_{\mu_2}[rf(\lambda)]} \le \frac{\mathbb{E}_{\mu_1}[rg(\lambda)]}{\mathbb{E}_{\mu_2}[rg(\lambda)]}.$$
(A6)

If instead $h(\lambda)$ is nondecreasing for all $\lambda > 0$, then

$$\frac{\mathbb{E}_{\mu_1}[rf(\lambda)]}{\mathbb{E}_{\mu_2}[rf(\lambda)]} \ge \frac{\mathbb{E}_{\mu_1}[rg(\lambda)]}{\mathbb{E}_{\mu_2}[rg(\lambda)]}.$$
(A7)

Proof. By the law of iterated expectation, we have

$$\mathbb{E}_{\mu_1}[rf(\lambda)] = \mathbb{E}_{\mu_2}[rg(\lambda)]\mathbb{E}_{\lambda} \left[\frac{\mathbb{E}_{\mu_2}[rg(\lambda)|\lambda]}{\mathbb{E}_{\mu_2}[rg(\lambda)]} \frac{\mathbb{E}_{\mu_1}[r|\lambda]}{\mathbb{E}_{\mu_2}[r|\lambda]} h(\lambda) \right]. \tag{A8}$$

Note that the expectation \mathbb{E}_{λ} in Eq. (A8) over λ is the same under μ_1 and μ_2 by assumption. Moreover, the function $h(\lambda)$ is nonincreasing in $\lambda>0$ by assumption. Finally, observe that the factor $\mathbb{E}_{\mu_2}[rg(\lambda)|\lambda]/\mathbb{E}_{\mu_2}[rg(\lambda)]$ defines a change in distribution for the random variable λ , since taking its expectation over λ yields 1. Denote a new random variable with this distribution by $\tilde{\lambda}$. Then, we may apply the Harris inequality 5 to Eq. (A8) to see

$$\mathbb{E}_{\mu_1}[rf(\lambda)] = \mathbb{E}_{\mu_2}[rg(\lambda)]\mathbb{E}_{\tilde{\lambda}} \left[\frac{\mathbb{E}_{\mu_1}[r|\tilde{\lambda}]}{\mathbb{E}_{\mu_2}[r|\tilde{\lambda}]} h(\tilde{\lambda}) \right]$$
(A9)

$$\leq \mathbb{E}_{\mu_2}[rg(\lambda)]\mathbb{E}_{\tilde{\lambda}}\left[\frac{\mathbb{E}_{\mu_1}[r|\tilde{\lambda}]}{\mathbb{E}_{\mu_2}[r|\tilde{\lambda}]}\right]\mathbb{E}_{\tilde{\lambda}}\left[h(\tilde{\lambda})\right] \tag{A10}$$

$$= \mathbb{E}_{\mu_2}[rg(\lambda)] \mathbb{E}_{\lambda} \left[\frac{\mathbb{E}_{\mu_2}[rg(\lambda)|\lambda]}{\mathbb{E}_{\mu_2}[rg(\lambda)]} \frac{\mathbb{E}_{\mu_1}[r|\lambda]}{\mathbb{E}_{\mu_2}[r|\lambda]} \right] \mathbb{E}_{\lambda} \left[\frac{\mathbb{E}_{\mu_2}[rg(\lambda)|\lambda]}{\mathbb{E}_{\mu_2}[rg(\lambda)]} h(\lambda) \right]$$
(A11)

$$= \frac{\mathbb{E}_{\mu_1}[rg(\lambda)]}{\mathbb{E}_{\mu_2}[rg(\lambda)]} \mathbb{E}_{\mu_2}[rf(\lambda)] . \tag{A12}$$

To prove Eq. (A7), apply the same argument to -h, which is nonincreasing when h is nondecreasing.

The following corollary is an immediate consequence of Lem. A1.3.

Corollary A1.1. Let $\mu_1 \leq \mu_2$ (recall Def. 4.1). Then, for $a \geq 0$,

$$\frac{(\mathcal{I}_{1,a}^*)_2}{s_2} - \frac{(\mathcal{I}_{1,a}^*)_1}{s_1} \ge 0. \tag{A13}$$

If Assump. 4 also holds,

$$(\mathcal{I}_{1,a}^*)_2 \ge (\mathcal{I}_{1,a}^*)_1.$$
 (A14)

Proof. This result follows from Lem. A1.3 by choosing $g: \lambda \mapsto 1$ and $h: \lambda \mapsto \phi(\phi + x\lambda)^{-a}$ and recalling by definitions $s_1 = \mathbb{E}_{\mu_1}[r]$ and $s_2 = \mathbb{E}_{\mu_2}[r]$. For the second conclusion, note when Assump. 4 holds $s_1 = s = s_2$.

A2 Hardness is a partial order

We restate Def. 4.1 for clarity.

Definition A2.1 (Restatement of Def. 4.1). Let μ_1 and μ_2 be LJSDs with the same marginal distribution of λ . If the asymptotic overlap coefficients are such that $\mathbb{E}_{\mu_1}[r|\lambda]/\mathbb{E}_{\mu_2}[r|\lambda]$ is nondecreasing as a function of λ and $\mathbb{E}_{\mu_1}[r] \leq \mathbb{E}_{\mu_2}[r]$, we say μ_1 is easier than μ_2 (or μ_2 is harder than μ_1), and write $\mu_1 \leq \mu_2$. Comparing against the case of no shift μ_0 , we say μ_1 is easy when $\mu_1 \leq \mu_0$ and hard when $\mu_1 \geq \mu_0$.

⁵See for example [23, Section 2.2].

Proposition A2.1. Def. 4.1 (and Def. A2.1) form a partial order over covariate shifts μ .

Proof. Reflexivity is clearly satisfied as $\mathbb{E}_{\mu}[r] \leq \mathbb{E}_{\mu}[r]$ and $\mathbb{E}_{\mu}[r|\lambda]/\mathbb{E}_{\mu}[r|\lambda] = 1$ is nondecreasing for all μ .

For antisymmetry, we see $\mu_1 \leq \mu_2$ and $\mu_2 \leq \mu_1$ imply $\mathbb{E}_{\mu_1}[r] = \mathbb{E}_{\mu_2}[r]$ and that $\mathbb{E}_{\mu_1}[r|\lambda]/\mathbb{E}_{\mu_2}[r|\lambda]$ is constant in λ as it is nonincreasing and nondecreasing. However, setting $\mathbb{E}_{\mu_1}[r|\lambda] = c\mathbb{E}_{\mu_2}[r|\lambda]$ and taking expectation over λ and rearranging yields $1 = \mathbb{E}_{\mu_1}[r]/\mathbb{E}_{\mu_2}[r] = c$, so in fact $\mathbb{E}_{\mu_1}[r|\lambda] = \mathbb{E}_{\mu_2}[r|\lambda]$. Assuming that μ_1 and μ_2 are absolutely continuous (the case where they are a sum of point masses is similar), we can write their densities as $p_i(\lambda, r) = p_i(\lambda)p_i(r|\lambda)$. By assumption $p_1(\lambda) = p_2(\lambda)$, so it suffices to show $p_1(r|\lambda) = p_2(r|\lambda)$ almost everywhere. Next note

$$0 = \mathbb{E}_{\mu_1}[r|\lambda] - \mathbb{E}_{\mu_2}[r|\lambda] = \int_{\mathbb{R}^+} r\left(p_1(r|\lambda) - p_2(r|\lambda)\right) dr,\tag{A15}$$

but since r>0 over the domain of the integral, we have $p_1(r|\lambda)-p_2(r|\lambda)=0$ almost everywhere. Finally, for transitivity assume $\mu_1\leq \mu_2$ and $\mu_2\leq \mu_3$, then clearly $\mathbb{E}_{\mu_1}[r]\leq \mathbb{E}_{\mu_2}[r]\leq \mathbb{E}_{\mu_3}[r]$. Next note

$$\frac{\mathbb{E}_{\mu_1}[r|\lambda]}{\mathbb{E}_{\mu_3}[r|\lambda]} = \frac{\mathbb{E}_{\mu_1}[r|\lambda]}{\mathbb{E}_{\mu_2}[r|\lambda]} \cdot \frac{\mathbb{E}_{\mu_2}[r|\lambda]}{\mathbb{E}_{\mu_3}[r|\lambda]},\tag{A16}$$

so $\mathbb{E}_{\mu_1}[r|\lambda]/\mathbb{E}_{\mu_3}[r|\lambda]$ is the product of two nondecreasing, positive functions and is thus also nondecreasing.

A3 Repeated eigenvalues of Σ

When Σ has repeated eigenvalues (denote one such by λ), its eigendecomposition is not unique, since the eigenvectors associated to λ need only span the eigenspace $\{\mathbf{v}: \Sigma \mathbf{v} = \lambda \mathbf{v}\}$. Specifically, if the eigenspace of λ has dimension n_{λ} then the eigenvectors $\mathbf{v}_{1}^{\lambda}, \ldots, \mathbf{v}_{n_{\lambda}}^{\lambda}$ are orthonormal but not unique. However, for any other choice of orthonormal vectors $\mathbf{w}_{1}^{\lambda}, \ldots, \mathbf{w}_{n_{\lambda}}^{\lambda}$ that span the eigenspace of λ , there exists some orthogonal matrix O such that W = VO, where V and W contain the two bases as their columns.

Let $\mathbf{v}_1^*, \dots, \mathbf{v}_{n_0}^*$ and $\lambda_1^*, \dots, \lambda_{n_0}^*$ denote a choice for the eigenvectors and eigenvalues of Σ^* . The nonuniqueness of the eigenvectors implies that the corresponding overlaps to Σ^* , defined as

$$r_i^{\lambda} = \sum_{j=1}^{n_0} (\mathbf{v}_j^* \cdot \mathbf{v}_i^{*\lambda})^2 \lambda_j^* = (\mathbf{v}_i^{\lambda})^{\top} \Sigma^* \mathbf{v}_i^{\lambda}$$
(A17)

are also not unique (but do not depend on the choice of eigendecomposition for Σ^*). However, we note that the conditional expectation $\mathbb{E}[r|\lambda]$ for the EJSD is invariant to the choice of eigendecomposition for Σ . Indeed, for V, we have

$$\mathbb{E}[r|\lambda] = \frac{1}{n_{\lambda}} \sum_{i=1}^{n_{\lambda}} r_i^{\lambda} = \frac{1}{n_{\lambda}} \sum_{i=1}^{n_{\lambda}} (\mathbf{v}_i^{\lambda})^{\top} \Sigma^* \mathbf{v}_i^{\lambda} = \bar{\operatorname{tr}}(V^{\top} \Sigma^* V), \tag{A18}$$

but this is the same as $\bar{\operatorname{tr}}(W^{\top}\Sigma W)$ using W=VO and the cyclic property of the trace.

Since $\mathbb{E}[r|\lambda]$ under the EJSD is invariant to the choice of eigendecomposition for Σ , this will also be true of the LJSD. Said differently, while the choice of eigendecomposition affects both the EJSD and its corresponding LJSD, all possible choices of eigendecomposition lead to JSD in the same equivalence class, where μ_1 and μ_2 are equivalent when $\mathbb{E}_{\mu_1}[r|\lambda] = \mathbb{E}_{\mu_2}[r|\lambda]$.

Finally, since all potential EJSDs associated to Σ and Σ^* are in the same equivalence class, the particular choice has no affect on their downstream use. Specifically, Def. 4.1 is not changed as it depends only on $\mathbb{E}[r|\lambda]$, and none of the functionals of μ (e.g. $\mathcal{I}_{a,b}$ and $\mathcal{I}_{a,b}^*$) are changed due to the law of iterated expectation.

A4 Test error for linear regression

A4.1 Asymptotic and nonasymptotic results for $m > n_0 + 1$

We present a short proof of the nonasymptotic test error for linear regression.

Recall data is generated via the model for $y_i = \beta^\top \mathbf{x}_i / \sqrt{n_0} + \epsilon_i$, which is fit with the ridgeless linear regression estimator $\hat{\beta} = (XX^\top)^{-1}XY$. Although in the main text we have assumed the same isotropic prior on β that we utilize for the random feature model, no generative assumption is needed on β for this result.

Proof of Prop. 3.1. Under the condition $m > n_0 + 1$, the sample covariance is almost surely invertible so the test error can be written as

$$E_{\Sigma^*} = \mathbb{E}\left[\left(\beta^\top \mathbf{x} / \sqrt{n_0} - \hat{\beta}^\top \mathbf{x} \right)^2 \right]$$
 (A19)

$$= \sigma_{\epsilon}^{2} \operatorname{tr} \left(\Sigma^{*} \mathbb{E}[(XX^{\top})^{-1}] \right) \tag{A20}$$

$$= \sigma_{\epsilon}^2 \frac{n_0}{m - n_0 - 1} \operatorname{tr}(\Sigma^* \Sigma^{-1}), \tag{A21}$$

where we used the cyclicity and linearity of the trace, as well as a formula for the expectation of the inverse sample covariance of a Gaussian matrix (which applies when $m > n_0 + 1$) from [58, Theorem 3.1]. The asymptotic form of the result follows from the limit in the proportional asymptotics:

$$E_{\mu} = \lim_{n_0, m \to \infty} E_{\Sigma^*} = \frac{\sigma_{\epsilon}^2 \phi}{1 - \phi} \mathbb{E}_{\mu}[r/\lambda]. \tag{A22}$$

Next we prove Prop. 3.2 using the Harris inequality before proving a slightly more general result that properly handles the case where Σ may have repeated eigenvalues.

Proof of Prop. 3.2. Using the Harris inequality,

$$E_{\Sigma_{1}^{*}}^{\mathsf{LR}} = \frac{\sigma_{\epsilon}^{2} n_{0}}{m - n_{0} - 1} \frac{\bar{\mathrm{tr}}(\Sigma_{2}^{*})}{n_{0}} \sum_{i=1}^{n_{0}} \frac{r_{i,2}}{\bar{\mathrm{tr}}(\Sigma_{2}^{*})} \frac{r_{i,1}}{r_{i,2}} \frac{1}{\lambda_{i}} \leq \frac{\sigma_{\epsilon}^{2} n_{0}}{m - n_{0} - 1} \frac{\bar{\mathrm{tr}}(\Sigma_{1}^{*})}{\bar{\mathrm{tr}}(\Sigma_{2}^{*})} \frac{1}{n_{0}} \sum_{i=1}^{n_{0}} \frac{r_{i,2}}{\lambda_{i}} \leq E_{\Sigma_{2}^{*}}^{\mathsf{LR}}, \text{ (A23)}$$

since $1/\lambda_i$ and $r_{i,1}/r_{i,2}$ are nonincreasing and nondecreasing in *i* respectively.

Prop. 3.2 can be strengthened, and doing so motivates the occurrence of the conditional expectation in Def. 4.1. Note that we assume that the eigenvalues of Σ are in nondecreasing order, and each eigenvalue has associated to it two overlap coefficients, $r_{i,1}$ and $r_{i,2}$. Prop. 3.2 assumes that $r_{i,1}/r_{i,2}$ form a nondecreasing sequence. However, what happens when Σ has repeated eigenvalues? In this case, the ordering of the λ_i can be changed, which in turn changes the associated $r_{i,1}$ and $r_{i,2}$. Therefore, the assumption on $r_{i,1}/r_{i,2}$ is too strong—reordering the repeated eigenvalues might be sufficient to satisfy the condition even if it is violated for the original ordering. Instead, we can introduce the conditional expectation to handle this more gracefully.

In the following, we use $\tilde{\lambda}_1,\ldots,\tilde{\lambda}_k$ to denote the k non-repeated eigenvalues of the training covariance Σ and the sets S_j for $j\in\{1,\ldots,k\}$ to denote the indices of eigenvalues in $\{1,\ldots,n_0\}$ associated to the jth repeated eigenvalue of Σ . Analogously, we define the corresponding non-repeated overlap coefficients as,

$$\tilde{r}_j = \frac{1}{|S_j|} \sum_{i \in S_j} r_i, \quad j \in \{1, \dots, k\}$$
 (A24)

This is equivalent to the conditional expectation discussed in Eq. (A18). In this case, the measure-theoretic definition of *hardness* in Def. 4.1 becomes equivalent to stating that the sequence $\frac{\tilde{r}_{j,2}}{\tilde{r}_{j,1}}$ is nondecreasing as j ranges from $\{1,\ldots,k\}$ when Σ_2^* is *harder* then Σ_1^* (here $\tilde{r}_{j,1}$ and $\tilde{r}_{j,2}$ denote the non-repeated overlap coefficients of Σ_1^* and Σ_2^* respectively).

Proposition A4.1. Let $\tilde{r}_{j,1}$ and $\tilde{r}_{j,2}$ denote the non-repeated overlap coefficients⁶ of Σ_1^* and Σ_2^* relative to Σ . If $\operatorname{tr}(\Sigma_2^*) \geq \operatorname{tr}(\Sigma_1^*)$ and the ratios $\tilde{r}_{j,1}/\tilde{r}_{j,2}$ form a nondecreasing sequence, then $E_{\Sigma_2^*}^{LR} \geq E_{\Sigma_1^*}^{LR}$

Proof. From Prop. 3.1 it is enough to show ${\rm tr}(\Sigma_2^*\Sigma^{-1}) \geq {\rm tr}(\Sigma_1^*\Sigma^{-1})$. First, note that $\sum_{i=1}^{n_0} r_{i,1} = \sum_{j=1}^k |S_j| \tilde{r}_{j,1} = {\rm tr}(\Sigma_1^*)$ and $\sum_{i=1}^{n_0} r_{i,2} = \sum_{j=1}^k |S_j| \tilde{r}_{j,2} = {\rm tr}(\Sigma_2^*)$. Then,

$$\operatorname{tr}(\Sigma_{1}^{*}\Sigma^{-1}) = \sum_{i=1}^{n_{0}} \frac{r_{i,1}}{\lambda_{i}} = \sum_{i=1}^{k} |S_{j}| \frac{\tilde{r}_{j,1}}{\tilde{\lambda}_{j}} = \operatorname{tr}(\Sigma_{2}^{*}) \sum_{i=1}^{k} |S_{j}| \frac{\tilde{r}_{j,2}}{\operatorname{tr}(\Sigma_{2}^{*})} \frac{\tilde{r}_{j,1}}{\tilde{r}_{j,2}} \frac{1}{\tilde{\lambda}_{j}}$$
(A25)

$$\leq \operatorname{tr}(\Sigma_2^*) \left(\sum_{j=1}^k |S_j| \frac{\tilde{r}_{j,2}}{\operatorname{tr}(\Sigma_2^*)} \frac{\tilde{r}_{j,1}}{\tilde{r}_{j,2}} \right) \left(\sum_{j=1}^k |S_j| \frac{\tilde{r}_{j,2}}{\operatorname{tr}(\Sigma_2^*)} \frac{1}{\tilde{\lambda}_j} \right)$$
(A26)

$$=\frac{\operatorname{tr}(\Sigma_1^*)}{\operatorname{tr}(\Sigma_2^*)}\operatorname{tr}(\Sigma_2^*\Sigma^{-1}) \tag{A27}$$

$$\leq \operatorname{tr}(\Sigma_2^* \Sigma^{-1}), \tag{A28}$$

where the inequality is a consequence of the Harris inequality (see e.g. [23, Section 2.2]): since $|S_j|\tilde{r}_{j,1}/\tilde{\lambda}_j$ is a normalized measured with respect to j, the sequence $1/\tilde{\lambda}_j$ is nonincreasing in j, while the sequence $\tilde{r}_{j,1}/\tilde{r}_{j,2}$ is nondecreasing in j.

A4.2 Linear regression limit of random feature regression

In this section, we show that taking an appropriate limit of Cor. 5.1 recovers existing results for ridgeless linear regression in high-dimensions. These results fall into two cases based on whether $\phi < 1$ or $\phi > 1$. In Sec. A4.2.1, we consider $\phi < 1$ and Prop. 3.1 from the main text. In Sec. A4.2.2, we consider $\phi > 1$ and Cor. 2 of [24].

To recover these results, we let σ approach the identity activation function and $\psi \to 0^7$, since as more random features are added the kernel concentrate around its asymptotic limit. Moreover, since we are taking the limit $\psi \to 0$ and we assume $\phi > 0$, we may assume $\phi > \psi$ in all calculations for simplicity. We also note that as σ approaches the identity, the constants associated to σ approach the following limits:

$$\eta, \zeta \to 1 \quad \text{and} \quad \omega \to 0.$$
 (A29)

From Cor. 5.1, the expression for the total error is

$$E_{\mu} = \phi \mathcal{I}_{1,2}^* + \frac{\psi}{\phi - \psi} x(\sigma_{\varepsilon}^2 + \mathcal{I}_{1,1})(\omega + \mathcal{I}_{1,1}^*) + x \left(1 - \frac{x(\omega - \sigma_{\varepsilon}^2)}{1 - x^2 \mathcal{I}_{2,2}}\right) \mathcal{I}_{2,2}^*, \tag{A30}$$

where $x=1/(\omega+\mathcal{I}_{1,1})$ since we are assuming $\psi<\phi$. Taking the limit $\psi\to 0$, the total error E_μ converges to

$$\phi \mathcal{I}_{1,2}^* + x \left(1 - \frac{x(\omega - \sigma_{\varepsilon}^2)}{1 - x^2 \mathcal{I}_{2,2}} \right) \mathcal{I}_{2,2}^*. \tag{A31}$$

A4.2.1 Recovering asymptotic form of Prop. 3.1 for $\phi < 1$

Recall that Prop. 3.1 assumes that $\phi < 1$. We begin by analyzing the solution to the self-consistent equation for x in the ridgeless limit when the activation function σ becomes linear.

Lemma A4.1. Suppose $0 < \phi < 1$ and $\psi < \phi$. In the ridgeless limit, the solution x to the self-consistent equation in Cor. 5.1,

$$x = \frac{1}{\omega + \mathcal{I}_{1,1}},\tag{A32}$$

satisfies $\lim_{\omega \to 0} x = \infty$.

⁶Recall the definition in Eq. (A24).

 $^{^7}$ The order of these limits does not change the result, but for concreteness we take take the limit as $\psi \to 0$ first.

Proof. From the definition of $\mathcal{I}_{1,1}$, we see

$$\mathcal{I}_{1,1} = \phi \mathbb{E}_{\mu} \left[\frac{\lambda}{\phi + \lambda x} \right] = \frac{\phi}{x} \mathbb{E}_{\mu} \left[\frac{\lambda}{\phi / x + \lambda} \right] \le \frac{\phi}{x}. \tag{A33}$$

Using Eq. (A32), we find $x \ge (1 - \phi)/\omega$. Taking $\omega \to 0$ completes the proof.

From Lem. A4.1, the solution to the self-consistent equation for x diverges, i.e. $x \to \infty$ as σ becomes linear. In this case, by the dominated convergence theorem, we have that

$$\lim_{\omega \to 0} x \mathcal{I}_{1,1}^* = \lim_{x \to \infty} \mathbb{E}_{\mu} \left[\frac{xr}{\phi + x\lambda} \right] = \phi \mathbb{E}_{\mu} \left[r/\lambda \right], \tag{A34}$$

$$\lim_{\omega \to 0} x^2 \mathcal{I}_{2,2} = \lim_{x \to \infty} \phi \mathbb{E}_{\mu} \left[\frac{x^2 \lambda^2}{(\phi + x\lambda)^2} \right] = \phi, \tag{A35}$$

$$\lim_{\omega \to 0} x^2 \mathcal{I}_{2,2}^* = \lim_{x \to \infty} \phi \mathbb{E}_{\mu} \left[\frac{x^2 r \lambda}{(\phi + x \lambda)^2} \right] = \phi \mathbb{E}_{\mu} \left[r / \lambda \right], \tag{A36}$$

$$\lim_{\omega \to 0} \mathcal{I}_{1,1}^* = \lim_{x \to \infty} \phi \mathbb{E}_{\mu} \left[\frac{r}{(\phi + x\lambda)^2} \right] = 0, \tag{A37}$$

and
$$\lim_{\omega \to 0} \mathcal{I}_{1,2}^* = \lim_{x \to \infty} \phi \mathbb{E}_{\mu} \left[\frac{r}{(\phi + x\lambda)^2} \right] = 0.$$
 (A38)

As such, the total error in Eq. (A31) converges to

$$\sigma_{\epsilon}^2 \frac{\phi}{1 - \phi} \mathbb{E}_{\mu}[r/\lambda] \tag{A39}$$

as $\omega \to 0$ and $\psi \to 0$ as desired.

A4.2.2 Recovering results from [24] when $\Sigma = \Sigma^*$ and $\phi > 1$

The minimum-norm solution for under-determined linear regression is the same as the limiting ridge-regularized solution as the ridge constant converges to 0. As such, studying the ridgeless limit as in Cor. 5.1 allows for a comparison to prior results on minimum-norm interpolants [24]. To do so, we again take the limit as σ becomes linear; however, in contrast to the previous section, we now assume $\phi > 1$ in order to compare with [24, Cor. 2].

As [24] examines the setting in which the training and test covariate distributions are equal, $\Sigma = \Sigma^*$, we have that $\mathcal{I}_{a,b}^* = \mathcal{I}_{a,b}$. Using this relation, the total error Eq. (A31) becomes

$$E_{\mu} = \phi \mathcal{I}_{1,2} + x \left(1 - \frac{x(\omega - \sigma_{\varepsilon}^2)}{1 - x^2 \mathcal{I}_{2,2}} \right) \mathcal{I}_{2,2}. \tag{A40}$$

Next, letting σ become linear as in Eq. (A29), we obtain $x = 1/\mathcal{I}_{1,1}$ and

$$E_{\mu} \stackrel{\omega \to 0}{\longrightarrow} \mathcal{I}_{1,1} + \sigma_{\epsilon}^2 \frac{x^2 \mathcal{I}_{2,2}}{1 - x^2 \mathcal{I}_{2,2}},\tag{A41}$$

where we used the identity Eq. (A5).

We now simplify and relate the result for the asymptotic error from [24, Cor. 2] in the case of isotropic β satisfying $\|\beta\|_2 = 1$, where the total error is written as⁸

$$\frac{1}{\phi^2 c_0(H,\phi)} + \sigma_{\epsilon}^2 c_0 \phi \frac{\int \frac{s^2}{(1+c_0\phi s)^2 dH(s)}}{\int \frac{s}{(1+c_0\phi s)^2 dH(s)}}.$$
 (A42)

The measure H is the limiting empirical spectral density of the covariance, which is equivalent to the marginal distribution of λ , and c_0 satisfies the equation

$$1 - \frac{1}{\phi} = \int \frac{1}{1 + c_0 \phi s} dH(s). \tag{A43}$$

⁸[24, Cor. 2] provides expressions for a bias and variance term separately, but the decomposition is defined slightly differently than the one we utilize, so we compare directly to the total error. Note that Eq. (A42) corrects a typo in [24].

Substituting $c_0 = x/\phi^2$ and rearranging terms, we see

$$0 = 1 - \frac{1}{\phi} - \int \frac{1}{1 + c_0 \phi s} dH(s)$$
(A44)

$$= -\frac{1}{\phi} + 1 - \int \frac{1}{1 + (x/\phi)s} dH(s)$$
 (A45)

$$= -\frac{1}{\phi} + x \int \frac{s}{\phi + xs} dH(s) \tag{A46}$$

$$= -\frac{x}{\phi} \left(\frac{1}{x} - \mathcal{I}_{1,1} \right),\tag{A47}$$

which is satisfied by $x=1/\mathcal{I}_{1,1}$, implying the two self-consistent equations are equivalent and validating the identification $c_0=x/\phi^2$. Using the same substitution $c_0=x/\phi^2$ in Eq. (A42) gives

$$\mathcal{I}_{1,1} + \sigma_{\epsilon}^2 \frac{1}{x\phi} \frac{x^2 \mathcal{I}_{2,2}}{\mathcal{I}_{1,2}} = \mathcal{I}_{1,1} + \sigma_{\epsilon}^2 \frac{x^2 \mathcal{I}_{2,2}}{1 - x^2 \mathcal{I}_{2,2}},\tag{A48}$$

which matches our expression in Eq. (A41).

A5 Harder shifts increase the bias and the total error

To begin, we provide the proof of Prop. 5.1.

Proof of Prop. 5.1. Consider two LJSDs μ_1 and μ_2 such that $\mu_1 \leq \mu_2$ where Assump. 4 holds. Then,

$$B_{\mu_2} - B_{\mu_1} = \phi\left((\mathcal{I}_{1,2}^*)_2 - (\mathcal{I}_{1,2}^*)_1\right) \ge 0, \tag{A49}$$

where we have used the inequalities in Eq. (A60) which follow from Cor. A1.1 when Assump. 4 holds.

Now, additionally assume that $\sigma_{\varepsilon}^2 \leq \omega$. Reorganizing the terms specifying the asymptotic variance, we can rewrite the total error as

$$E_{\mu} = B_{\mu} + V_{\mu} \tag{A50}$$

$$\psi \, \partial x \left(\left(\frac{2}{3} - \frac{\pi}{3} \right) \left(\frac{\pi}{3} - \frac{\pi}{3} \right) \right) = \pi \cdot (\pi \cdot \pi) \cdot (\pi \cdot$$

$$=\phi(\mathcal{I}_{1,2}^*)-\rho\frac{\psi}{\phi}\frac{\partial x}{\partial \gamma}\bigg((\sigma_{\varepsilon}^2+\mathcal{I}_{1,1})(\omega+\phi\mathcal{I}_{1,2})(\omega+\mathcal{I}_{1,1}^*)+\gamma\tau\mathcal{I}_{2,2}(\omega+\phi\mathcal{I}_{1,2}^*)$$

$$+\frac{\phi}{\psi x}\gamma\bar{\tau}(\sigma_{\varepsilon}^2 + \phi \mathcal{I}_{1,2})(\mathcal{I}_{1,1}^* - \phi \mathcal{I}_{1,2}^*)\right)$$
(A51)

$$\equiv C_1 \omega + C_2 \mathcal{I}_{1,1}^* + C_3 \mathcal{I}_{1,2}^* \,, \tag{A52}$$

where the $C_i \geq 0$ and depend on μ only through the marginal λ (i.e. they only depend on the training distribution):

$$C_1 = -\rho \frac{\psi}{\phi} \frac{\partial x}{\partial \gamma} \left((\sigma_{\varepsilon}^2 + \mathcal{I}_{1,1}) (\omega + \phi \mathcal{I}_{1,2}) + \gamma \tau \mathcal{I}_{2,2} \right) \ge 0 \tag{A53}$$

$$C_2 = -\rho \frac{\partial x}{\partial \gamma} \left(\frac{\psi}{\phi} (\sigma_{\varepsilon}^2 + \mathcal{I}_{1,1}) (\omega + \phi \mathcal{I}_{1,2}) + \frac{\gamma \bar{\tau}}{x} (\sigma_{\varepsilon}^2 + \phi \mathcal{I}_{1,2}) \right) \ge 0$$
 (A54)

$$C_{3} = -\rho \frac{\partial x}{\partial \gamma} \left(\psi \gamma \tau \mathcal{I}_{2,2} - \frac{\phi \gamma \bar{\tau}}{x} (\sigma_{\varepsilon}^{2} + \phi \mathcal{I}_{1,2}) - \frac{\phi}{\rho \frac{\partial x}{\partial \gamma}} \right)$$
(A55)

$$= -\rho \frac{\partial x}{\partial \gamma} \left(\psi \gamma \tau \mathcal{I}_{2,2} - \frac{\phi \gamma \bar{\tau}}{x} (\sigma_{\varepsilon}^2 + \phi \mathcal{I}_{1,2}) + \frac{\phi}{\rho x} (\gamma + \rho \gamma (\tau \psi / \phi + \bar{\tau}) (\omega + \phi \mathcal{I}_{1,2})) \right)$$
(A56)

$$= -\rho \gamma \frac{\partial x}{\partial \gamma} \left(\psi \tau \mathcal{I}_{2,2} + \frac{\phi \bar{\tau}}{x} (\omega - \sigma_{\varepsilon}^2) + \frac{\phi}{\rho x} (1 + \rho \tau \frac{\psi}{\phi} (\omega + \phi \mathcal{I}_{1,2})) \right)$$
(A57)

$$\geq 0$$
, (A58)

where the inequalities follow from Lem. A1.1 and from the assumption $\sigma_{\varepsilon}^2 \leq \omega$. It is now straightforward to see that

$$E_{\mu_2} - E_{\mu_1} = \left(C_1 \omega + C_2(\mathcal{I}_{1,1}^*)_2 + C_3(\mathcal{I}_{1,2}^*)_2 \right) - \left(C_1 \omega + C_2(\mathcal{I}_{1,1}^*)_1 + C_3(\mathcal{I}_{1,2}^*)_1 \right)$$

= $C_2 \left((\mathcal{I}_{1,1}^*)_2 - (\mathcal{I}_{1,1}^*)_1 \right) + C_3 \left((\mathcal{I}_{11,2}^*)_2 - (\mathcal{I}_{1,2}^*)_1 \right) \ge 0,$ (A59)

where we have used the inequalities

$$(\mathcal{I}_{1,1}^*)_2 - (\mathcal{I}_{1,1}^*)_1 \ge 0, \quad (\mathcal{I}_{1,2}^*)_2 - (\mathcal{I}_{1,2}^*)_1 \ge 0.$$
 (A60)

The former two inequalities again follow from Cor. A1.1 when Assump. 4 holds.

A6 The benefit of overparameterization

A6.1 The bias is nonincreasing

We begin by examining the behavior of the bias as a function of the overparameterization ratio ϕ/ψ by showing Prop. 5.2.

Proof of Prop. 5.2. Recall from Thm. 5.1 that the bias is given by

$$B_{\mu} = \phi \mathcal{I}_{12}^*, \tag{A61}$$

where x is the unique positive real root of the self-consistent equation

$$x = \frac{1 - \gamma \tau}{\omega + \mathcal{I}_{1,1}}.$$
(A62)

Differentiating Eq. (A61) with respect to ϕ/ψ gives,

$$\frac{\partial B_{\mu}}{\partial (\phi/\psi)} = -\frac{\psi^2}{\phi} \frac{\partial B_{\mu}}{\partial \psi} = 2 \frac{\psi^2}{\phi} \frac{\partial x}{\partial \psi} \cdot \left(\phi \mathcal{I}_{2,3}^*\right) \,. \tag{A63}$$

Since Lem. A1.1 gives $\mathcal{I}_{a,b}^* \geq 0$, it is sufficient to show $\frac{\partial x}{\partial \psi} \leq 0$, which immediately follows by implicitly differentiating Eq. (A62) and simplifying the expression:

$$\frac{\partial x}{\partial \psi} = -\frac{\rho x \tau(\omega + \mathcal{I}_{1,1})}{\phi \left(1 + \rho(\bar{\tau} + \frac{\psi}{\phi}\tau)(\omega + \phi \mathcal{I}_{1,2})\right)} \le 0.$$
 (A64)

Therefore we conclude that $\frac{\partial B_{\mu}}{\partial (\phi/\psi)} \leq 0$.

A6.2 The variance is nonincreasing

Next, we turn our attention to the variance. We note the proposition only focuses on the ridgeless limit, whereas Fig. 1(d) show that result may in fact hold for nonzero ridge constant. As the proof is considerably simpler in the ridgeless limit, we defer the analysis of the nonzero ridge setting to future work.

Proof of Prop. 5.3. Using the chain rule we have that

$$\frac{\partial V_{\mu}}{\partial (\phi/\psi)} = \frac{\partial V_{\mu}}{\partial \psi} \left[\frac{\partial (\phi/\psi)}{\partial \psi} \right]^{-1} = -\frac{\partial V_{\mu}}{\partial \psi} \frac{\psi^{2}}{\phi}, \tag{A65}$$

so it is sufficient to show that $\frac{\partial V_{\mu}}{\partial \psi} \geq 0$.

From Cor. 5.1 in the overparameterized regime, the self-consistent equation for x reads $x = \frac{1}{\omega + \mathcal{I}_{1,1}}$ and is independent of ψ . Therefore, $\partial x/\partial \psi = 0$ and the expression for $\partial V_{\mu}/\partial \psi$ follows directly from Eq. (18),

$$\frac{\partial V_{\mu}}{\partial \psi} = \frac{\phi}{(\phi - \psi)^2} x (\sigma_{\varepsilon}^2 + \mathcal{I}_{1,1}) (\omega + \mathcal{I}_{1,1}^*) \ge 0, \qquad (A66)$$

where the inequality follows from Lem. A1.1.

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A6.3 The generalization gap is nonincreasing

Finally, we prove that overparameterization also confers enhanced robustness, specifically that the generalization gap between shifted and unshifted test error is a nonincreasing function of the overparameterization ratio in the overparameterized regime.

Proof of Prop. 5.4. The chain rule gives $\frac{\partial (E_{\mu_2}-E_{\mu_1})}{\partial (\phi/\psi)}=-\frac{\psi^2}{\phi}\frac{\partial (E_{\mu_2}-E_{\mu_1})}{\partial \psi}$ so it is sufficient to show $\frac{\partial (E_{\mu_2}-E_{\mu_1})}{\partial \psi}\geq 0$. To that end, recall from Cor. 5.1 in the overparameterized regime that the self-consistent equation for x reads $x=\frac{1}{\omega+\mathcal{I}_{1,1}}$ and is independent of ψ . Therefore, $\partial x/\partial \psi=0$, which implies $\partial B_{\mu_1}/\partial \psi=0$ and $\partial B_{\mu_2}/\partial \psi=0$, so that $\frac{\partial (E_{\mu_2}-E_{\mu_1})}{\partial \psi}=\frac{\partial (V_{\mu_2}-V_{\mu_1})}{\partial \psi}$, the expression for which follows directly from Eq. (18). Finally,

$$\frac{\partial (E_{\mu_2} - E_{\mu_1})}{\partial \psi} = \left(C_E(\omega + (\mathcal{I}_{1,1}^*)_2) \right) - \left(C_E(\omega + (\mathcal{I}_{1,1}^*)_1) \right) \tag{A67}$$

$$\geq C_E \left((\mathcal{I}_{1,1}^*)_2 - (\mathcal{I}_{1,1}^*)_1 \right) \tag{A68}$$

$$=0, (A69)$$

where we have introduced the shorthand $C_E = \frac{\phi}{(\phi - \psi)^2} x(\sigma_{\varepsilon}^2 + \mathcal{I}_{1,1}) \geq 0$ and in the last inequality we have used Cor. A1.1 to argue $(\mathcal{I}_{1,1}^*)_2 \geq (\mathcal{I}_{1,1}^*)_1$ which holds whenever Assump. 4 holds. \square

A7 Linear trends between in-distribution and out-of-distribution generalization

In Sec. 5.4, we investigated the linear relationship between the shifted and unshifted test error in the ridgeless, overparameterized regime. Here, we generalize the result to show that the linear relationship holds between any two LJSDs in the ridgeless, overparameterized regime.

Proposition A7.1 (Strengthened form of Prop. 5.5). *Consider two LJSDs* μ_1 *and* μ_2 . *In the setting of Cor. 5.1 and in the overparameterized regime (i.e.* $\psi < \phi$),

$$E_{\mu_2} = E_0 + \underbrace{\left(\frac{\omega + (\mathcal{I}_{1,1}^*)_2}{\omega + (\mathcal{I}_{1,1}^*)_1}\right)}_{\text{SLOPE}} E_{\mu_1}, \tag{A70}$$

parametrically in ϕ/ψ , where E_0 and SLOPE are constants independent of the overparameterization ratio ϕ/ψ . Moreover, SLOPE ≥ 1 when $\mu_1 \leq \mu_2$.

Proof of Prop. A7.1. In the overparameterized regime (i.e. $\phi > \psi$) and in the ridgeless limit, the asymptotic test error for LJSD μ_1 is given by Cor. 5.1 as

$$E_{\mu_1} = B_{\mu_1} + \frac{1}{\phi/\psi - 1} x(\sigma_{\varepsilon}^2 + \mathcal{I}_{1,1}) (\omega + (\mathcal{I}_{1,1}^*)_1) + x \left(1 - \frac{x(\omega - \sigma_{\varepsilon}^2)}{1 - x^2 \mathcal{I}_{2,2}}\right) (\mathcal{I}_{2,2}^*)_1.$$
 (A71)

Similarly, the asymptotic test error for LJSD μ_2 is given by Cor. 5.1 as

$$E_{\mu_2} = B_{\mu_2} + \frac{1}{\phi/\psi - 1} x(\sigma_{\varepsilon}^2 + \mathcal{I}_{1,1})(\omega + (\mathcal{I}_{1,1}^*)_2) + x\left(1 - \frac{x(\omega - \sigma_{\varepsilon}^2)}{1 - x^2 \mathcal{I}_{2,2}}\right) (\mathcal{I}_{2,2}^*)_2. \tag{A72}$$

Note that in both expressions, the self-consistent equation for x reads $x=\frac{1}{\omega+\mathcal{I}_{1,1}}$, which has no dependence on ψ , and, as such, x, $\mathcal{I}_{a,b}$, $(\mathcal{I}_{a,b}^*)_1$, $(\mathcal{I}_{a,b}^*)_2$, B_{μ_1} , and B_{μ_2} do not depend on the overparameterization ratio ϕ/ψ . Hence we can simply eliminate the quantity $\frac{1}{\phi/\psi-1}$ from Eqs. (A71) and (A72) to obtain

$$E_{\mu_2} = E_0 + \left(\frac{\omega + (\mathcal{I}_{1,1}^*)_2}{\omega + (\mathcal{I}_{1,1}^*)_1}\right) E_{\mu_1}, \tag{A73}$$

where E_0 does not depend on the overparameterization ratio ϕ/ψ and is given by

$$E_0 := B_{\mu_2} - \frac{\omega + (\mathcal{I}_{1,1}^*)_2}{\omega + (\mathcal{I}_{1,1}^*)_1} B_{\mu_1} + x \left(1 - \frac{x(\omega - \sigma_{\varepsilon}^2)}{1 - x^2 \mathcal{I}_{2,2}} \right) \left((\mathcal{I}_{2,2}^*)_2 - \frac{\omega + (\mathcal{I}_{1,1}^*)_2}{\omega + (\mathcal{I}_{1,1}^*)_1} (\mathcal{I}_{2,2}^*)_1 \right). \tag{A74}$$

To establish the second conclusion, recall from Sec. A5 that the conditions $\mu_1 \leq \mu_2$ in conjunction with Assump. 4 show $(\mathcal{I}_{1,1}^*)_1 \leq (\mathcal{I}_{1,1}^*)_2$ which establishes SLOPE ≥ 1 .

The first half of Prop. 5.5, namely Eq. (19), can be obtained from Prop. A7.1 by specializing to the case $\mu_1 = \mu_{\emptyset}$. The second half of Prop. 5.5, namely the conditions on the slope, can be obtained from Prop. A7.1 by separately specializing to the cases $\mu_1 = \mu_{\emptyset}$ and $\mu_2 = \mu_{\emptyset}$.

A8 Necessity of monotonicity of overlap coefficients in Def. 4.1

Here we provide an explicit description of the construction used in Sec. 5.5 and Fig. 3(b) that shows the monotonicity of overlap coefficients in Def. 4.1 is necessary in order to guarantee the ordering of errors in Prop. 5.1. The example is given by the following four LJSDs:

$$\mu_1 = \frac{1}{4} (\delta_{\lambda_1, \lambda_4} + \delta_{\lambda_2, \lambda_3} + \delta_{\lambda_3, \lambda_2} + \delta_{\lambda_4, \lambda_1}) \tag{A75}$$

$$\mu_2 = \frac{1}{4} (\delta_{\lambda_1, \lambda_4} + \delta_{\lambda_2, \lambda_3} + \delta_{\lambda_3, \lambda_1} + \delta_{\lambda_4, \lambda_2}) \tag{A76}$$

$$\mu_3 = \frac{1}{4} (\delta_{\lambda_1, \lambda_2} + \delta_{\lambda_2, \lambda_4} + \delta_{\lambda_3, \lambda_3} + \delta_{\lambda_4, \lambda_1}) \tag{A77}$$

$$\mu_4 = \frac{1}{4} (\delta_{\lambda_1, \lambda_1} + \delta_{\lambda_2, \lambda_2} + \delta_{\lambda_3, \lambda_3} + \delta_{\lambda_4, \lambda_4}), \tag{A78}$$

where $\lambda_1=0.6$, $\lambda_2=0.24$, $\lambda_3=0.12$ and $\lambda_4=0.04$. Note that $\mu_4=\mu_\emptyset$, and these LJSDs have equal training and test covariance scales, i.e. $s=s_1=s_2=s_3=s_4=1$. Moreover, the partial order in Def. 4.1 gives $\mu_1\geq \mu_4$ and $\mu_2\geq \mu_4$, and all other pairs of LJSDs are incomparable. In particular, focusing on μ_2 and μ_3 , the ratios of overlap coefficients are

$$\frac{r_{2,1}}{r_{3,1}} = \frac{1}{6}$$
 $\frac{r_{2,2}}{r_{3,2}} = 3$, $\frac{r_{2,3}}{r_{3,3}} = 5$, and $\frac{r_{2,4}}{r_{3,4}} = \frac{2}{5}$, (A79)

so the sequence $r_{2,i}/r_{3,i}$ is nonmonotonic in i. The violation of monotonicity is minimal, in the sense that only a single ratio $(r_{2,4}/r_{3,4})$ is out of order; nevertheless, the strict model-independent ordering of test errors is broken because of this nonmonotonicity, as can be seen in Fig. 3(b). For the comparable pairs of LJSDs, $\mu_1 \geq \mu_4$ and $\mu_2 \geq \mu_4$, and the strict ordering of the error is seen for all values of ϕ/ψ . The ordering is not guaranteed for the other pairs, and indeed the ordering is not satisfied for μ_2 and μ_3 , which is evidenced by the crossing of the corresponding curves in the figure. In this way, we see that the error can exhibit model dependence induced by nonmonotonicity of overlap coefficients in Def. 4.1, thereby showing that the monotonicity condition is necessary for Prop. 5.1. Finally, we note that even though Prop. 5.1 may no longer hold, it is nevertheless possible to develop nontrivial bounds when the strict monotonicity is violated, but we pursue this investigation elsewhere.

A9 Proof of Thm. 5.1

As discussed in Sec. 2, we consider predictive functions \hat{y} defined by random feature kernel ridge regression,

$$\hat{y}(\mathbf{x}) := YK^{-1}K_{\mathbf{x}} \tag{A80}$$

for $K := K(X,X) + \gamma I_m$, $K_{\mathbf{x}} := K(X,\mathbf{x})$, with γ is a ridge regularization constant. Here

$$K = \frac{1}{n_1} F^{\top} F + \gamma I_m \,, \tag{A81}$$

and, as in the main text, we have introduced the abbreviations $F := \sigma(WX/\sqrt{n_0})$. The labels are generated by a linear function parameterized by $\beta \in \mathbb{R}^{n_0}$, whose entries are drawn independently from $\mathcal{N}(0,1)$, i.e. $Y = \beta^\top X/\sqrt{n_0} + \varepsilon$. In this section, we develop the techniques and detailed calculations needed to determine the high-dimensional asymptotic limit of the test error,

$$E_{\Sigma^*} = \mathbb{E}_{\mathbf{x},\beta} \mathbb{E}[(y(\mathbf{x}) - \hat{y}(\mathbf{x}))^2] - \sigma_{\epsilon}^2 = \mathbb{E}_{\mathbf{x},\beta} \mathbb{E}[(\beta^\top \mathbf{x} / \sqrt{n_0} - YK^{-1}K_{\mathbf{x}})^2], \tag{A82}$$

as well as its decomposition into bias and variance terms,

$$E_{\Sigma^*} = \underbrace{\mathbb{E}_{\mathbf{x},\beta} \mathbb{E}[(\mathbb{E}[\hat{y}(\mathbf{x})] - y(\mathbf{x}))^2]}_{B_{\Sigma^*}} + \underbrace{\mathbb{E}_{\mathbf{x},\beta}[\mathbb{V}[\hat{y}(\mathbf{x})]]}_{V_{\Sigma^*}}.$$
 (A83)

We may also write the test loss as

$$E_{\Sigma^*} = \mathbb{E}_{(\mathbf{x},y)}(y - \hat{y}(\mathbf{x}))^2 = E_1 + E_2 + E_3 \tag{A84}$$

with

$$E_1 = \mathbb{E}_{(\mathbf{x}, \beta, \varepsilon)} y(\mathbf{x})^2 = \mathbb{E}_{(\mathbf{x}, \beta, \varepsilon)} \operatorname{tr}(y(\mathbf{x}) y(\mathbf{x})^\top)$$
(A85)

$$E_2 = -2\mathbb{E}_{(\mathbf{x},\beta,\varepsilon)}(K_{\mathbf{x}}^{\top}K^{-1}Y)y(\mathbf{x}) = -2\mathbb{E}_{(\mathbf{x},\varepsilon)}\operatorname{tr}(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top}y(\mathbf{x}))$$
(A86)

$$E_3 = \mathbb{E}_{(\mathbf{x},\beta,\varepsilon)} (K_{\mathbf{x}}^\top K^{-1} Y^\top)^2 = \mathbb{E}_{(\mathbf{x},\varepsilon)} \operatorname{tr} (K_{\mathbf{x}}^\top K^{-1} Y^\top Y K^{-1} K_{\mathbf{x}}). \tag{A87}$$

A9.1 Reducing to the mean-zero case

In this section, we aim to show that we may assume without loss of generality that the activation function is centered. More precisely, we define

$$\bar{F}_{ij} := F_{ij} - \mathbb{E}_Z \sigma \left(\sqrt{\bar{\operatorname{tr}}(\Sigma)} Z \right) \quad \text{and} \quad \bar{f}_i := f_i - \mathbb{E}_Z \sigma \left(\sqrt{\bar{\operatorname{tr}}(\Sigma^*)} Z \right)$$
 (A88)

for all i and j and $Z \sim \mathcal{N}(0,1)$. Note that this centering operation is n_0 -dependent, but in the limit under Assump. 4, $\bar{\operatorname{tr}}(\Sigma)$, $\bar{\operatorname{tr}}(\Sigma^*) \to s$, which appear in the limiting self-consistent equation. Note that although we invoke Assump. 4 throughout the rest of the paper, this proof holds non-asymptotically and allows for $\bar{\operatorname{tr}}(\Sigma) \neq \bar{\operatorname{tr}}(\Sigma^*)$.

To show that replacing F and f by \bar{F} and \bar{f} does not alter the test error in the limit, we have to show that the E_1 , E_2 , and E_3 terms of Eqs. (A85)-(A87) are not changed in the limit. Clearly this is true for E_1 as it contains neither F nor f. For E_2 we must show

$$\mathbb{E}\left[(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top} - \bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}Y^{\top})y(\mathbf{x})\right] \to 0 \tag{A89}$$

and for E_3 we must show

$$\mathbb{E}\left[(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top})^2 - (\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}Y^{\top})^2\right] \to 0, \tag{A90}$$

where

$$\bar{K} := \frac{1}{n_1} \bar{F}^\top \bar{F} + \gamma I \quad \text{and} \quad \bar{K}_{\mathbf{x}} := \frac{1}{n_1} \bar{F}^\top \bar{f}. \tag{A91}$$

Define the random variable

$$\Delta := (K_{\mathbf{x}}^{\top} K^{-1} - \bar{K}_{\mathbf{x}} \bar{K}^{-1}) Y^{\top}. \tag{A92}$$

To control the typical behavior of Δ , we will define an event \mathcal{E} (see Def. A9.1), and let $\mathbf{1}_{\mathcal{E}}$ be an indicator for \mathcal{E} . In Lem. A9.7 we show $\mathbb{P}[\mathcal{E}^c] \to 0$.

We can argue

$$|\mathbb{E}\left[\Delta y(\mathbf{x})\right]| \le |\mathbb{E}\left[\mathbf{1}_{\mathcal{E}}\Delta y(\mathbf{x})\right]| + |\mathbb{E}\left[(1 - \mathbf{1}_{\mathcal{E}})\Delta y(\mathbf{x})\right]|,\tag{A93}$$

for Eq. (A89), and

$$|\mathbb{E}\left[\Delta y(\mathbf{x})\right]| \le \left|\mathbb{E}\left[\mathbf{1}_{\mathcal{E}}\Delta(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top} + \bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}Y^{\top})\right]\right| \tag{A94}$$

$$+ \left| \mathbb{E} \left[(1 - \mathbf{1}_{\mathcal{E}}) \left((K_{\mathbf{x}}^{\top} K^{-1} Y^{\top})^2 - (\bar{K}_{\mathbf{x}}^{\top} \bar{K}^{-1} Y^{\top})^2 \right) \right] \right|, \tag{A95}$$

for Eq. (A90). We demonstrate Eqs. (A93) and (A94) are o(1) in two steps. The first terms on the right-hand sides of Eqs. (A93) and (A94) represent the typical behavior of the random variables. To bound them, we show that, given $\mathcal{E}, \Delta \to 0$ in Lem. A9.8. The second terms on the right-hand sides of Eqs. (A93) and (A94) represent the atypical behavior of the random variables. To bound them, we use the Cauchy-Schwarz inequality and the fact that $\mathbb{P}[\mathcal{E}^c] \to 0$ in Lem. A9.6.

To briefly outline the structure of this section: Sec. A9.1.1 proves concentration of some quadratic forms of the underlying random matrices and bounds their operator norms with high probability; Sec. A9.1.2 controls the atypical behavior mentioned above; Sec. A9.1.3 applies the Schur complement formula to derive an expression for Δ that we can bound; Sec. A9.1.4 defines an event where the expression for Δ from the Schur complement formula can be easily bounded; and Sec. A9.1.5 completes the argument by bounding Δ on this typical event.

A9.1.1 Prerequisites for concentration and linearization

Just as in [1], the concentration of the linear data kernel about its expectation is a key ingredient to the analysis. Define the random variables

$$\Upsilon := \frac{1}{n_0} X^{\top} X$$
 and $v^* := \|\mathbf{x}\|_2^2 / n_0$. (A96)

Remark A9.1. Throughout this section and the next we will use C to denote an arbitrarily large, n_0 -independent, positive constant, which can increase from line to line. For example, if $X \leq C$ and $Y \leq C$, we will simply write $XY \leq C$, since C^2 is still some n_0 -independent constant. This approach is valid as such replacements only occur a finite number of times. Similarly, c denotes some arbitrarily small, n_0 -independent, positive constant that can decrease from line to line.

Then we note

$$\mathbb{E}\Upsilon = \bar{\operatorname{tr}}(\Sigma)I_{n_0}$$
 and $\mathbb{E}v^* = \bar{\operatorname{tr}}(\Sigma^*).$ (A97)

For the variance, we see by Assump. 1 that

$$\mathbb{V}\Upsilon_{ij} = \frac{1 + \mathbb{I}(i=j)}{n_0} \bar{\operatorname{tr}}(\Sigma) \le C/n_0 \quad \text{and} \quad \mathbb{V}v^* = \frac{2}{n_0} \bar{\operatorname{tr}}((\Sigma^*)^2) \le C/n_0. \tag{A98}$$

This motivates the following lemma.

Lemma A9.1. The event

$$\mathcal{E}_{data} := \{ \|\Upsilon\|_{\infty} \le C \} \cap \left\{ |v^* - \bar{\operatorname{tr}}(\Sigma^*)| \le C n_0^{c-1/2} \right\} \cap \bigcap_{i,j} \left\{ |\Upsilon_{ij} - \delta_{ij} \bar{\operatorname{tr}}(\Sigma)| \le C n_0^{c-1/2} \right\}$$
 (A99)

occurs with high-probability, that is, for some positive, n_0 -independent constant C

$$\mathbb{P}[\mathcal{E}_{data}^{\mathsf{c}}] \le C n_0^{-c} \tag{A100}$$

for any positive, n_0 -independent constant c.

Proof. Tighter concentration than is obtained directly from the variance can be shown by observing that Υ and v^* are equal in distribution to

$$\frac{1}{n_0}Z^T\Sigma Z$$
 and $\frac{1}{n_0}z^T\Sigma^*z$ (A101)

for Z an (n_0, m) -dimensional matrix and z an n_0 -dimensional vector both containing i.i.d. standard Gaussian random variables. Then using the assumption $\|\Sigma\|_{\infty}, \|\Sigma^*\|_{\infty} \leq C$ and applying the results of Sec. B of [18] (or similar concentration results), we find that for some positive constant C that

$$\mathbb{P}[|\Upsilon_{ij} - \delta_{ij}\bar{\operatorname{tr}}(\Sigma)| \ge C n_0^{c-1/2}] \le C \exp(-n_0^c), \tag{A102}$$

where c is any positive constant. An identical concentration result holds for $v^* - \bar{\operatorname{tr}}(\Sigma^*)$. Then, by the union bound, we see

$$\mathbb{P}\left[\left\{|v^* - \bar{\text{tr}}(\Sigma^*)| \ge C n_0^{-c}\right\} \cup \bigcup_{i,j} \left\{|\Upsilon_{ij} - \delta_{ij}\bar{\text{tr}}(\Sigma)| \ge C n_0^{c-1/2}\right\}\right]$$
(A103)

$$\leq C n_0^2 C \exp\left(-n_0^c\right) \tag{A104}$$

$$\leq C \exp(-n_0^c). \tag{A105}$$

The operator norm of Υ can also be bounded probabilistically. For some n_0 -independent constant C,

$$\|\Upsilon\|_{\infty} \le \|\Sigma\|_{\infty} \|Z/\sqrt{n_0}\|_{\infty}^2 \le C\|\Sigma\|_{\infty} \left(1 + \sqrt{\frac{m}{n_0}} + \sqrt{\frac{\log(2/\delta)}{n_0}}\right) \le C$$
 (A106)

with probability at least $1-\delta$, where Z is i.i.d. Gaussian (see for example [65, Theorem 4.4.5]). Thus, setting $\delta=n_0^{-c}$, we see $\mathbb{P}[\|\Upsilon\|_{\infty}\geq C]\leq n_0^{-c}$. Applying the union bound again completes the proof.

Lemma A9.2. The (squared) expected operator norm of Υ is also bounded:

$$\mathbb{E}\|\Upsilon\|_{\infty}^2 \le C \tag{A107}$$

for some positive, n_0 -independent constant C.

Proof. This result follows from a tail integration argument. That is from [65, Theorem 4.4.5]) we have that

$$\|\Upsilon\|_{\infty} \le \|\Sigma\|_{\infty} \|Z/\sqrt{n_0}\|_{\infty}^2 \le C\|\Sigma\|_{\infty} \left(1 + \sqrt{\frac{m}{n_0}} + u\right)$$
 (A108)

with probability at least $1-2\exp(-n_0u^2)$, where Z is i.i.d. Gaussian. Hence we have that $\mathbb{P}[\|\Upsilon\|_{\infty} \geq C\|\Sigma\|_{\infty}\left(1+\sqrt{\frac{m}{n_0}}+u\right)] \leq 2\exp(-n_0u^2)$. Now by the tail integration identity,

$$\mathbb{E}[\|\Upsilon\|_{\infty}^2] = 2\int_0^\infty u \mathbb{P}[\|\Upsilon\|_{\infty} \ge u] du \tag{A109}$$

$$\leq C^{2} \|\Sigma\|_{\infty}^{2} \left(1 + \sqrt{\frac{m}{n_{0}}}\right)^{2} + C^{2} \|\Sigma\|_{\infty}^{2} \int_{0}^{\infty} u \mathbb{P}\left[\|\Upsilon\|_{\infty} \geq C \|\Sigma\|_{\infty} \left(1 + \sqrt{\frac{m}{n_{0}}} + u\right)\right] du \tag{A110}$$

$$\leq C^2 \|\Sigma\|_{\infty}^2 \left(1 + \sqrt{\frac{m}{n_0}}\right)^2 + C^2 \|\Sigma\|_{\infty}^2 \cdot \frac{1}{n_0} \tag{A111}$$

$$\leq C.$$
 (A112)

by integrating the Gaussian tail.

Next, we state similar results for the matrix $\tilde{\Upsilon} := W \Sigma^* W^\top / n_0$ as were obtained for Υ above.

Lemma A9.3. The event

$$\mathcal{E}_W := \left\{ \left\| \tilde{\Upsilon} \right\|_{\infty} \le C \right\} \cap \bigcap_{i,j} \left\{ \left| \tilde{\Upsilon}_{ij} - \delta_{ij} \bar{\operatorname{tr}}(\Sigma^*) \right| \le C n_0^{c-1/2} \right\}$$
(A113)

occurs with high-probability, that is, for some positive, n_0 -independent constant C

$$\mathbb{P}[\mathcal{E}_W^{\mathsf{c}}] \le C n_0^{-c} \tag{A114}$$

for any positive, n_0 -independent constant c.

Proof. The claims follow identically to Lem. A9.1.

Lemma A9.4. Moreover on the event \mathcal{E}_W , we have

$$\mathbb{E}_{\mathbf{x}}\bar{\sigma}(W\mathbf{x}/\sqrt{n_0})_i \le Cn_0^{c-1/2} \tag{A115}$$

and

$$\mathbb{E}_{\mathbf{x}}\bar{\sigma}(W\mathbf{x}/\sqrt{n_0})\bar{\sigma}(W\mathbf{x}/\sqrt{n_0})^{\top} = \zeta\tilde{\Upsilon} + (\eta - \zeta)I_m + \Delta, \tag{A116}$$

where $\|\Delta\|_{\infty} \leq C n_0^c$.

Proof. Note that conditional on W, $W\mathbf{x}/\sqrt{n_0} \sim \mathcal{N}(0, \tilde{\Upsilon})$. Using a Taylor expansion in $\varepsilon := \tilde{\Upsilon}_{ii} - \bar{\operatorname{tr}}(\Sigma^*)$ below with Assump. 3 shows that elementwise

$$\left| \mathbb{E}_{\mathbf{x}} \bar{\sigma}(W \mathbf{x} / \sqrt{n_0})_i \right| = \left| \mathbb{E}_Z \bar{\sigma} \left(\sqrt{\tilde{\Upsilon}_{ii}} Z \right) \right|$$
(A117)

$$= \left| \mathbb{E}_{Z} \sigma \left(\sqrt{\varepsilon + \bar{\operatorname{tr}}(\Sigma^{*})} Z \right) - \mathbb{E}_{Z} \sigma \left(\sqrt{\bar{\operatorname{tr}}(\Sigma^{*})} Z \right) \right| \tag{A118}$$

$$\leq C\epsilon$$
 (A119)

$$\leq C n_0^{c-1/2},$$
 (A120)

where Z is a standard Gaussian. See [1] for additional details, but note that we are not Taylor expanding the function σ , we are expanding the p.d.f. we integrate against. This allows us to assume

that $\sigma(W\mathbf{x})$ is centered as a conditional expectation over \mathbf{x} at the expense of an elementwise $Cn_0^{c-1/2}$ error. Denoting $\bar{f} := \bar{\sigma}(W\mathbf{x}/\sqrt{n_0})$, we note this can be extended to the matrix $\mathbb{E}\bar{f}\bar{f}^{\top}$. We see

$$\mathbb{E}_{\mathbf{x}}\bar{f}\bar{f}^{\top} = \mathbb{E}_{\mathbf{x}}[(\bar{f} - \mathbb{E}_{\mathbf{x}}\bar{f})(\bar{f} - \mathbb{E}_{\mathbf{x}}\bar{f})^{\top}] + (\mathbb{E}_{\mathbf{x}}\bar{f})(\mathbb{E}_{\mathbf{x}}\bar{f})^{\top}. \tag{A121}$$

However, the second term on the right-hand side of Eq. (A121) is small is operator norm, since it is rank-1 and

$$\left\| (\mathbb{E}_{\mathbf{x}}\bar{f})(\mathbb{E}_{\mathbf{x}}\bar{f})^{\top} \right\|_{\infty} = \left\| \mathbb{E}_{\mathbf{x}}\bar{f} \right\|_{2}^{2} \le C n_{0}^{c}$$
(A122)

by Eq. (A120). Next, we see for $i \neq j$ that

$$\mathbb{E}_{\mathbf{x}}\bar{f}_i\bar{f}_j = \mathbb{E}_{Z_1,Z_2}\bar{\sigma}(c_1Z_1)\bar{\sigma}(c_{12}Z_1 + c_2Z_2)$$
(A123)

for constants c_1 , c_2 , and c_{12} depending on W and Σ^* , where Z_1 and Z_2 are independent, standard Gaussians. See [1] for details. The i=j terms can be handled similarly. Moreover, $c_{12} = \tilde{\Upsilon}_{ij}/\sqrt{\tilde{\Upsilon}_{ii}} \leq C n_0^{c-1/2}$, so Taylor expanding in $c_{12}Z_1$, we find

$$\mathbb{E}_{\mathbf{x}}\bar{f}\bar{f}^{\top} = \zeta \Upsilon + (\eta - \zeta)I + \tilde{\Delta} + (\mathbb{E}_{\mathbf{x}}\bar{f})(\mathbb{E}_{\mathbf{x}}\bar{f})^{\top}. \tag{A124}$$

As a consequence of the Taylor expansion and Assump. 3, $\tilde{\Delta}$ has entries that are bounded by Cn_0^{c-1} in absolute value. Again, see [1]. The final conclusion for $\Delta = \tilde{\Delta} + (\mathbb{E}_{\mathbf{x}}\bar{f})(\mathbb{E}_{\mathbf{x}}\bar{f})^{\top}$ follows by upper bounding $\|\tilde{\Delta}\|_{\infty} \leq \|\tilde{\Delta}\|_F \leq Cn_0^c$ and using the previous bound in Eq. (A122).

Finally we include a bound on the operator norm of the random feature matrix. The argument follows [41, Lemma C.3] closely.

Lemma A9.5. Under Assump. 3, the event

$$\mathcal{E}_F := \left\{ \left\| \bar{F} / \sqrt{n_0} \right\|_{\infty} \le C n_0^c \right\} \tag{A125}$$

occurs with high-probability, that is, for some positive, n_0 -independent constant C

$$\mathbb{P}[\mathcal{E}_F^{\mathsf{c}}] \le C n_0^{-c} \tag{A126}$$

for any positive, n_0 -independent constant c < 10.

Proof. Consider the matrix

$$\bar{R}_{ij} = 1_{i \neq j} \bar{\sigma}(z_i^{\top} \Sigma^{1/2} z_j / \sqrt{n_1}) / \sqrt{n_1}$$
(A127)

for $z_i = \Sigma^{-1/2} X_i$ (i.e. columns of $\Sigma^{-1/2} X$) for $1 \le i \le m$ and $z_{m+i} = W_i$ (i.e. rows of W) for $1 \le i \le n_0$. By construction, we note that $\bar{F}/\sqrt{n_1}$ is a minor of \bar{R} . Thus, bounding the operator norm of \bar{R} suffices to bound the operator norm of \bar{F} . Moreover, z_i are independent Gaussians distributed as $\mathcal{N}(0,I_{n_0})$.

Next we show that the entries to the activation function cannot be too large with high probability. For convenience throughout we define $M=m+n_0$ and let Ω be a symmetric matrix with $\|\Omega\|_{\infty} \leq C$. Note that, for $i \neq j$, the random variable $z_i^{\top}\Omega z_j/\sqrt{n_0} = \sum_{k=1}^{n_0} \lambda_k(\Omega) a_k b_k/\sqrt{n_0}$ where a_k and b_k are i.i.d. from $\sim \mathcal{N}(0,1)$. So the moment generating function can be bounded as,

$$\mathbb{E}\left[\exp\left(\sum_{i=1}^{n_0} t\lambda_i(\Omega)a_ib_i/\sqrt{n_0}\right)\right] = \prod_{i=1}^{n_0} \mathbb{E}[\exp(a_i \cdot t\lambda_i(\Omega)b_i/\sqrt{n_0})]$$
(A128)

$$= \prod_{i=1}^{n_0} \mathbb{E}[\exp(t^2 b_i^2 \lambda_i(\Omega)^2 / (2n_0))]$$
 (A129)

$$\leq \prod_{i=1}^{n_0} \mathbb{E}[\exp(t^2 b_i^2 C^2 / (2n_0))] \tag{A130}$$

$$\leq \mathbb{E}[\exp(t^2b_i^2C^2/2)] \tag{A131}$$

$$=\frac{1}{\sqrt{1-C^2t^2}}$$
 (A132)

for $|t| \leq \frac{1}{C}$. Further $\frac{1}{\sqrt{1-C^2t^2}} \leq \exp(C^2t^2)$ for $|t| \leq \frac{1}{2C}$. This establishes the original random variable is subexponential. Thus this random variables satisfies

$$\mathbb{P}[|z_i^{\top} \Omega z_j / \sqrt{n_0}| \ge u] \le 2 \max\{\exp(-u^2 / 2C^2), \exp(-u / 2C)\}$$
 (A133)

(see for example [66, Proposition 2.9]). Define the event

$$\mathcal{G} := \bigcap_{1 \le i < j \le M} \left\{ \left| \frac{z_i^\top \Sigma^{1/2} z_j}{\sqrt{n_0}} \right| \ge C \sqrt{\log M} \right\} \cap \bigcap_{1 \le i < j \le M} \left\{ \left| \frac{z_i^\top \Sigma z_j}{\sqrt{n_0}} \right| \ge C^2 \sqrt{\log M} \right\}. \quad (A134)$$

Then by a union bound and Markov's inequality, we have that

$$\mathbb{P}[\mathcal{G}^{\mathsf{c}}] \le 4/M^{20} \tag{A135}$$

for large enough C.

We now define a modified version of $\bar{\sigma}$, that is the same up to a constant factor on \mathcal{G} but is truncated outside of \mathcal{G} . Let $\bar{u} = C\sqrt{\log M}$ and taking the constants from Assump. 3, we see

$$\tilde{\sigma}(u) := \begin{cases} \bar{\sigma}(u) \exp(-c_1|\bar{u}|)/c_0 & \text{for } |u| \leq \bar{u} \\ \bar{\sigma}(\bar{u}) \exp(-c_1|\bar{u}|)/c_0 & \text{for } u > \bar{u} \\ \bar{\sigma}(-\bar{u}) \exp(-c_1|\bar{u}|)/c_0 & \text{for } u < -\bar{u} \end{cases}$$
(A136)

Just as we did with σ in Eq. (A88), we center $\tilde{\sigma}$ with its mean \tilde{a} . Note $\tilde{\sigma}$ is a 1-bounded and 1-Lipschitz function so $|\tilde{a}| \leq 1$.

Now consider the matrix

$$\tilde{R}_{ij} := 1_{i \neq j} (\tilde{\sigma}(z_i^{\top} \Sigma^{1/2} z_j / \sqrt{n_0}) - \tilde{a}) / \sqrt{n_1}.$$
(A137)

By controlling the operator norm of \tilde{R} , we can control the operator norm of \bar{R} at the end of the proof. By a covering argument it suffices to control

$$\|\tilde{R}\|_{\infty} \le \max_{v \in S} 10 \underbrace{|v^{\top} \tilde{R} v|}_{F_v(Z)},\tag{A138}$$

where S is a 1/4-covering of the M-dimensional sphere with cardinality $\exp(cM)$ and the matrix Z is of all the variables z_i .

We now seek to apply [13, Lemma 9, Lemma 20]. To this end we wish to show that $F_v(Z)$ is Lipschitz in Z, that is, if we define $\mathcal{Z} := \sqrt{t}Z + \sqrt{1-t}Z'$ for $(Z,Z') \in \mathcal{G} \times \mathcal{G}$, we need to show that

$$\max_{v \in S} \max_{t \in [0,1]} \left\| \nabla F_v(\sqrt{t}Z + \sqrt{1-t}Z') \right\|_F \le L \tag{A139}$$

for suitable L. Consider the gradient with respect to a column of \mathcal{Z} (denoted by ζ_l):

$$\nabla_{\zeta_l} F_v(\mathcal{Z}) = 2 \frac{v_l}{\sqrt{n_0 n_1}} \sum_{i \neq l} \Sigma^{1/2} \zeta_i \underbrace{v_i \tilde{\sigma}'(\zeta_i^\top \Sigma^{1/2} \zeta_l^\top / \sqrt{n_0})}_{\mathcal{E}_i}$$
(A140)

$$=2\frac{v_l}{\sqrt{n_0 n_1}} \Sigma^{1/2} \mathcal{Z}\xi,\tag{A141}$$

where ξ is the vector with coordinates ξ_i except at l where it is zero. Continuing, on the set \mathcal{G} , we find

$$\|\nabla_{w_l} F_v(W)\|_2^2 \le C^2 v_l^2 / n_0^2 \sum_{i \ne l, j \ne l} \left| \xi_i \xi_j w_i^\top \Sigma w_j \right|$$
 (A142)

$$\leq C v_l^2 \sqrt{\log M} / n_0^2 \sum_i \sum_{j \neq i} |\xi_i \xi_j| \tag{A143}$$

$$\leq Cv_l^2\sqrt{\log M}/n_0^2\sum_i\sum_{j\neq i}(\xi_i^2+\xi_j^2)$$
 (A144)

$$\leq C v_l^2 \sqrt{\log M} / n_0 \tag{A145}$$

where the last line follows since $|\tilde{\sigma}'(\cdot)|_2 \leq 1$ implies that $||\xi|| \leq 1$. So finally, we obtain

$$\|\nabla_W F_v(W)\|_F^2 \le C\sqrt{\log M}/n_0 =: L^2.$$
 (A146)

Now [13, Lemma 9] shows for constant a D that

$$\mathbb{P}[|v^{\top} \tilde{R} v| > D] \le C \exp\left(C n_0 - \frac{D^2}{L^2}\right) + \frac{C}{D^2} \mathbb{E}[\max_{v \in S} (F_v(Z) - F_v(Z'))^2 \cdot \mathbf{1}_{\mathcal{G}^c}]. \tag{A147}$$

We use a crude bound on the complement. First note that

$$\max_{v \in S} (F_v(Z) - F_v(Z'))^2 \le C \|\tilde{\sigma}(Z^{\top} \Sigma^{1/2} Z / \sqrt{n_0})\|_F^2 \le C \|Z^{\top} Z / \sqrt{n_0}\|_F^2 + C n_0^2, \quad (A148)$$

since removing the 1-bounded-Lipschitz $\tilde{\sigma}(\cdot)$ can be done by centering each activation with $\tilde{\sigma}(0)$. Then,

$$\mathbb{E}\left[\max_{v \in S} (F_v(Z) - F_v(Z'))^2 \cdot \mathbf{1}_{\mathcal{G}^c}\right] \le \sqrt{\frac{C}{n_1}} (\mathbb{E}[\|Z^{\top} \Sigma^{1/2} Z / \sqrt{n_0}\|_F^4] + n_0^4) \mathbb{P}[\mathcal{G}^c]. \tag{A149}$$

A short computation shows that $\mathbb{E}[\|Z^{\top}\Sigma^{1/2}Z/\sqrt{n_0}\|_F^4] \leq Cn_0^8$. Combining all terms then shows that

$$\mathbb{P}[|v^{\top} \tilde{R} v| > D] \le C \exp(C n_0) \cdot \exp\left(-\frac{n_0 D^2}{\log M}\right) + \frac{C}{D^2} \cdot \frac{C}{M^5}. \tag{A150}$$

Choosing $D = c_3 \sqrt{\log M}$ for sufficiently large c_3 shows that

$$\mathbb{P}[|v^{\top}\tilde{R}v| > D] \le C \exp(-cn_0) + \frac{C}{n_0^{10}} \le \frac{C}{n_0^{10}}, \tag{A151}$$

where c > 0.

Recalling the original ϵ -net covering, this implies that

$$\|\tilde{R}\|_{\infty} \le C\sqrt{\log n_0} \tag{A152}$$

with probability at least C/n^{10} . We can now finish the argument by relating the operator norm of \bar{R} and \tilde{R} . Recalling the rescaling between the modified and unmodified activations, we see

$$\mathbb{P}[\|\bar{R}\|_{\infty} \ge C\sqrt{\log n_0} \cdot c_0 \exp(c_1|\bar{u}|)] \le \mathbb{P}[\|\tilde{R}\|_{\infty} \ge C\sqrt{\log(n_0)}, \mathcal{G}] + \mathbb{P}[\mathcal{G}^{\mathsf{c}}] \le C/n_0^{10}.$$
 (A153)

A9.1.2 Controlling the atypical behavior

Since the argument for the atypical event is the most straightforward, we provide that first.

Lemma A9.6. Suppose $\mathbb{P}[\mathcal{E}^c] = Cn_0^{-c}$ for some n_0 -independent constants C > 0 and c > 0. Then,

$$|\mathbb{E}\left[(1 - \mathbf{1}_{\mathcal{E}})\Delta y(\mathbf{x})\right]| \to 0$$
 (A154)

and

$$\left| \mathbb{E} \left[(1 - \mathbf{1}_{\mathcal{E}}) \left((K_{\mathbf{x}}^{\top} K^{-1} Y^{\top})^2 - (\bar{K}_{\mathbf{x}}^{\top} \bar{K}^{-1} Y^{\top})^2 \right) \right] \right| \to 0$$
 (A155)

as $n_0 \to \infty$.

Proof. Applying the Cauchy-Schwarz inequality to the left-hand side of Eq. (A154), we may bound it by

$$\mathbb{E}\left|\left[\left(1 - \mathbf{1}_{\mathcal{E}}\right) \Delta y(\mathbf{x})\right]\right| \le \left(\mathbb{E}\left[\mathbf{1}_{\mathcal{E}^{c}}\right]\right)^{1/2} \left(\mathbb{E}\left|\Delta y\right|^{2}\right)^{1/2}.$$
(A156)

Since the first term $\mathbb{P}[\mathcal{E}_c] \to 0$ it also follows that $(\mathbb{P}[\mathcal{E}_c])^{1/2} \to 0$. So it suffices to show $\mathbb{E}[|\Delta y|^2] = O(1)$.

We now apply the Cauchy-Schwarz inequality again to bound the second term by

$$\mathbb{E}\left|(\Delta y(\mathbf{x}))^2\right| \le \sqrt{\mathbb{E}[\Delta^4]\mathbb{E}[y(\mathbf{x})^4]}.$$
(A157)

A simple argument shows that $\mathbb{E}[y(\mathbf{x})^4] \leq C(\mathbb{E}[(\beta^\top \mathbf{x})^4/n_0^2] + \mathbb{E}[\epsilon^4]) \leq C\mathbb{E}[\|\Sigma^{1/2}\mathbf{z}\|^4/n_0^2] + C\sigma_{\epsilon}^4 \leq C$ for $\mathbf{z} \sim \mathcal{N}(0, I_d)$ since $\mathbb{E}[\|\mathbf{z}\|_2^4]/n_0^2] \leq C$. Hence it suffices to show $\mathbb{E}[\Delta^4] \leq C$. To this end note that

$$\mathbb{E}[\Delta^{4}] \le C(\mathbb{E}[(K_{\mathbf{x}}^{\top} K^{-1} Y^{\top})^{4}] + \mathbb{E}[(\bar{K}_{\mathbf{x}}^{\top} \bar{K}^{-1} Y^{\top})^{4}]) \tag{A158}$$

An identical argument can be applied to bound both terms. We outline the argument for the first term. We see

$$|\mathbb{E}[(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top})^{4}]| \le \mathbb{E}|\mathbb{E}_{\beta,\varepsilon}[(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top})^{4}|W,X,x]|. \tag{A159}$$

Now note that by the definition of $Y = \beta^{\top} X / \sqrt{n_0} + \varepsilon$ we have that,

$$(K_{\mathbf{x}}^{\top} K^{-1} Y^{\top})^4 \le C \left((K_{\mathbf{x}}^{\top} K^{-1} \frac{X}{\sqrt{n_0}} \beta)^4 + (K_{\mathbf{x}}^{\top} K^{-1} \varepsilon)^4 \right)$$
 (A160)

Recalling that $\beta \sim \mathcal{N}(0, I_{n_0})$ and $\varepsilon \sim \mathcal{N}(0, I_m)$, we can compute the Gaussian moments (marginally in β, ε) as,

$$\mathbb{E}_{\beta,\varepsilon}[(K_{\mathbf{x}}^{\top}K^{-1}\frac{X}{\sqrt{n_0}}\beta)^4 + (K_{\mathbf{x}}^{\top}K^{-1}\varepsilon)^4|W,X,x]$$
(A161)

$$\leq C \left((K_{\mathbf{x}}^{\top} K^{-1} \left(\frac{X^{\top} X}{n_0} \right) K^{-1} K_{\mathbf{x}}^{\top})^2 + \sigma_{\epsilon}^2 (K_{\mathbf{x}}^{\top} K^{-2} K_{\mathbf{x}}^{\top})^2 \right) \tag{A162}$$

Continuing, using the definition of K_x ,

$$\mathbb{E}\left[\left(K_{\mathbf{x}}^{\top}K^{-1}\left(\frac{X^{\top}X}{n_0}\right)K^{-1}K_{\mathbf{x}}^{\top}\right)^2\right] \leq \mathbb{E}\left[\left\|\frac{f^{\top}}{\sqrt{n_0}}\frac{FK^{-1}}{\sqrt{n_0}}\frac{X^{\top}X}{n_0}\frac{K^{-1}F^{\top}}{\sqrt{n_0}}\frac{f}{\sqrt{n_0}}\right\|_{\infty}^2\right]$$
(A163)

$$\leq \mathbb{E}\left[\left\|\frac{f}{\sqrt{n_0}}\right\|_2^4 \cdot \left\|\frac{FK^{-1}}{\sqrt{n_0}}\right\|_{\infty}^4 \cdot \left\|\frac{X^{\top}X}{n_0}\right\|_{\infty}^2\right]. \tag{A164}$$

Noting that $K=FF^\top/n_0+\gamma I_m$ so an application of the SVD to $\frac{F}{\sqrt{n_0}}$ (denoting the corresponding singular values as s_i) shows that $\|\frac{FK^{-1}}{\sqrt{n_0}}\|_{\infty}=\max_i\frac{s_i}{s_i^2+\gamma}\leq \max_{s\geq 0}\frac{s}{s^2+\gamma}=1/(2\sqrt{\gamma})$. Hence, we can continue bounding Eq. (A164) by

$$C\mathbb{E}[\|f/\sqrt{n_0}\|_{\infty}^4] \cdot \mathbb{E}[\|X^{\top}X/n_0\|_{\infty}^2],$$
 (A165)

where we exploited the independence of f and X. Lem. A9.2 ensures that $\mathbb{E}[\|X^\top X/n_0\|_\infty^2] = \mathbb{E}[\|\Upsilon\|_\infty^2] \le C$. The former term becomes $\mathbb{E}[\|f/\sqrt{n_0}\|_2^4] = \mathbb{E}[\sigma(\sqrt{\operatorname{tr}(\Sigma^*)}z)^4] \le C$ for $z \sim \mathcal{N}(0,1)$ by Assump. 3. Thus, the previous displays are bounded by some constant C. An entirely analogous argument shows that $\mathbb{E}[(K_\mathbf{x}^\top K^{-2} K_\mathbf{x}^\top)^2] \le C$. Together these two results along with the previous computations establish that,

$$|\mathbb{E}[(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top})^4]| \le C \tag{A166}$$

Note that our argument did not exploit any explicit properties of the centered vs uncentered activation function σ vs. $\bar{\sigma}$. Hence an identical argument shows that, $|\mathbb{E}[(\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}Y^{\top})^4]| \leq C$. These two results imply $\mathbb{E}[\Delta^4] \leq C$ as desired.

Now we turn to the second term. Using an identical application of the Cauchy-Schwarz inequality as used for the first term, we can bound Eq. (A155) by

$$(\mathbb{E} \left[\mathbf{1}_{\mathcal{E}^{c}} \right])^{1/2} \left(\mathbb{E} \left| (K_{\mathbf{x}}^{\top} K^{-1} Y^{\top})^{2} - (\bar{K}_{\mathbf{x}}^{\top} \bar{K}^{-1} Y^{\top})^{2} \right|^{2} \right)^{1/2}.$$
 (A167)

Hence we can show Eq. (A155) is o(1) if $\mathbb{E}\left|(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top})^2-(\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}Y^{\top})^2\right|^2=O(1)$. This result follows immediately from the computations shown for the previous term since we have already established that $\mathbb{E}[(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top})^4] \leq C$ and $\mathbb{E}[(\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}Y^{\top})^4] \leq C$. These two previously shown results imply

$$\mathbb{E}\left|(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top})^{2} - (\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}Y^{\top})^{2}\right|^{2} \leq C\left(\mathbb{E}[(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top})^{4}] + \mathbb{E}[(\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}Y^{\top})^{4}]\right) \leq C. \tag{A168}$$

A9.1.3 Schur complement formula for bounding Δ

The centering procedure is a rank-1 change to F and f, so applying the Schur complement formula to understand its effect is natural. Write $a := \mathbb{E}_Z \sigma\left(\sqrt{\operatorname{tr}(\Sigma)}Z\right)$, $a^* := \mathbb{E}_Z \sigma\left(\sqrt{\operatorname{tr}(\Sigma^*)}Z\right)$, $\mathbf{v} := 1/n_1 \bar{F}^{\top} 1_{n_1}$, $\mathbf{u} := a 1_m$, $U := [\mathbf{u}, \mathbf{v}]^{\top}$, and $C := \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$. Then,

$$K^{-1} = (\bar{K} + \mathbf{u}\mathbf{v}^{\top} + \mathbf{v}\mathbf{u}^{\top} + \mathbf{u}\mathbf{u}^{\top})^{-1}$$
(A169)

$$= (\bar{K} + U^{\top}CU)^{-1} \tag{A170}$$

$$= \bar{K}^{-1} - \bar{K}^{-1} U^{\top} (C^{-1} + U\bar{K}^{-1}U^{\top})^{-1} U\bar{K}^{-1}, \tag{A171}$$

and, for $\delta := 1/n_1 \bar{f}^{\top} 1_{n_1}$ and $P := (\delta + a^*, a^*)^{\top}$,

$$K_{\mathbf{x}} = \bar{K}_{\mathbf{x}} + \frac{1}{n_1} (F - \bar{F})^{\top} \bar{f} + \frac{1}{n_1} \bar{F}^{\top} (f - \bar{f}) + \frac{1}{n_1} (F - \bar{F})^{\top} (f - \bar{f})$$
(A172)

$$= \bar{K}_{\mathbf{x}} + (\delta + a^*)\mathbf{u} + a^*\mathbf{v} \tag{A173}$$

$$= \bar{K}_{\mathbf{x}} + U^{\mathsf{T}} P \,. \tag{A174}$$

Combining these expressions,

$$K^{-1}K_{\mathbf{x}} = K^{-1}(\bar{K}_{\mathbf{x}} + U^{\top}P) \tag{A175}$$

$$= \bar{K}^{-1}(\bar{K}_{\mathbf{x}} + U^{\top}P) - \bar{K}^{-1}U^{\top}(C^{-1} + U\bar{K}^{-1}U^{\top})^{-1}U\bar{K}^{-1}(\bar{K}_{\mathbf{x}} + U^{\top}P) \quad (A176)$$

$$=\bar{K}^{-1}\bar{K}_{\mathbf{x}} + T_1 + T_2, \tag{A177}$$

with

$$T_1 = \bar{K}^{-1} U^{\top} \left(I_2 - (C^{-1} + U\bar{K}^{-1}U^{\top})^{-1} U\bar{K}^{-1}U^{\top} \right) P \tag{A178}$$

$$= \bar{K}^{-1}U^{\top} \left(I_2 + CU\bar{K}^{-1}U^{\top} \right)^{-1} P \tag{A179}$$

$$T_2 = -\bar{K}^{-1}U^{\top}(C^{-1} + U\bar{K}^{-1}U^{\top})^{-1}U\bar{K}^{-1}\bar{K}_{\mathbf{x}}$$
(A180)

$$= -\bar{K}^{-1}U^{\top} \left(I_2 + CU\bar{K}^{-1}U^{\top} \right)^{-1} CU\bar{K}^{-1}\bar{K}_{\mathbf{x}}. \tag{A181}$$

Furthermore, writing $c_0 := \frac{1}{m} \mathbf{u}^{\top} \bar{K}^{-1} \mathbf{u}, c_1 := 1 + \mathbf{u}^{\top} \bar{K}^{-1} \mathbf{v}, c_2 := 1 - \mathbf{v}^{\top} \bar{K}^{-1} \mathbf{v},$

$$(I_2 + CU\bar{K}^{-1}U^{\top})^{-1} = \frac{1}{c_1^2 + mc_0c_2} \begin{pmatrix} c_1 & c_2 - c_1 \\ -mc_0 & mc_0 + c_1 \end{pmatrix},$$
 (A182)

so that,

$$(I_2 + CU\bar{K}^{-1}U^{\top})^{-1}P = \frac{1}{c_1^2 + mc_0c_2} \begin{pmatrix} c_1\delta + c_2a^* \\ -mc_0\delta + c_1a^* \end{pmatrix},$$
 (A183)

and,

$$(I_2 + CU\bar{K}^{-1}U^{\top})^{-1}C = \frac{1}{c_1^2 + mc_0c_2} \begin{pmatrix} c_2 & c_1 \\ c_1 & -mc_0 \end{pmatrix}.$$
 (A184)

A9.1.4 Concentration with high-probability

Definition A9.1. Recall the definitions from Sec. A9.1.3. To characterize the typical behavior of the random variables, we define the event

$$\mathcal{E} := \mathcal{E}_{data} \cap \mathcal{E}_W \cap \mathcal{E}_F \cap \left\{ |\delta| \le C n_0^{c-1/2} \right\} \cap \left\{ c n_0^{-c} \le c_0 \le C n_0^c \right\} \cap \left\{ c_1 \le C n_0^{c+1/2} \right\}$$
 (A185)

$$\cap \left\{ c n_0^{-c} \le c_2 \le C n_0^c \right\} \cap \left\{ Y \bar{K}^{-1} \mathbf{v}^\top \le C n_0^c \right\} \cap \left\{ Y \bar{K}^{-1} \mathbf{u}^\top \le C n_0^{c+1/2} \right\}. \tag{A186}$$

$$\cap \left\{ \bar{K}_{\mathbf{x}} \bar{K}^{-1} \mathbf{u}^{\top} \le C n_0^c \right\} \cap \left\{ \bar{K}_{\mathbf{x}} \bar{K}^{-1} \mathbf{v}^{\top} \le C n_0^{c-1/2} \right\} \cap \left\{ y(\mathbf{x}) \le C n_0^c \right\}$$
(A187)

Lemma A9.7. The event \mathcal{E} is high-probability, that is, $\mathbb{P}[\mathcal{E}^c] \leq C n_0^{-c}$ for some constant C > 0 and any constant 0 < c < 10.

Proof. First, we already know \mathcal{E}_{data} , \mathcal{E}_W , and \mathcal{E}_F all occur with high-probability (see Lems. A9.1, A9.3 and A9.5). When bounding the other events in Eqs. (A185)-(A187), it will be useful to introduce conditioning on one of \mathcal{E}_{data} , \mathcal{E}_W , or \mathcal{E}_F . This will suffice since for any event \mathcal{A} , we have

$$\mathbb{P}[\mathcal{A}^{\mathsf{c}}] \leq \mathbb{P}[\mathcal{A}^{\mathsf{c}}|\mathcal{E}_{\mathsf{data}}] + \mathbb{P}[\mathcal{E}^{\mathsf{c}}_{\mathsf{data}}] \leq \mathbb{P}[\mathcal{A}^{\mathsf{c}}|\mathcal{E}_{\mathsf{data}}] + Cn_0^{-c}$$
(A188)

for example. We will explicitly denote this conditioning, but when taking expectation over some random variables (e.g. x or W) we will not explicitly denote that we are conditioning on the remaining independent random variables (e.g. X). Once we have bounded the probability of the complement of each event in Eqs. (A185)-(A187), we can apply the union bound to complete the proof.

For future reference recall $\mathbf{v} := 1/n_1 \bar{F}^{\top} 1_{n_1}$ and $\mathbf{u} := a 1_m$. We deal with each event in Eqs. (A185)-(A187) in turn.

Controlling δ : Here, we introduce conditioning on the event $\mathcal{E}_{\text{data}}$. To control δ , we want to calculate its mean and variance to apply Chebyshev's inequality. Note that $\mathcal{E}_{\text{data}}$ is independent of W, so the expectations over W below are unchanged by this conditioning. Recall

$$\delta = \frac{1}{n_1} \sum_{k=1}^{n_1} \sigma \left(\sum_{j=1}^{n_0} W_{kj} x_j / \sqrt{n_0} \right) - a^*$$
 (A189)

and note that conditional on x the sum $\sum_{j} W_{kj} x_j / \sqrt{n_0}$ is distributed as $\mathcal{N}(0, v^*)$ for all k.

Expanding in $v^* - \bar{\operatorname{tr}}(\Sigma^*)$, we see

$$\mathbb{E}_{W}[\delta|\mathcal{E}_{\text{data}}] = \mathbb{E}[\mathbb{E}_{Z \sim \mathcal{N}(0,1)}[\sigma(\sqrt{\bar{\text{tr}}(\Sigma^*) + (\upsilon^* - \bar{\text{tr}}(\Sigma^*))}Z)] - a^*|\mathcal{E}_{\text{data}}]$$
(A190)

$$= \mathbb{E}[\mathbb{E}_Z[\sigma(\sqrt{\overline{\operatorname{tr}}(\Sigma^*)}Z)] - a^*|\mathcal{E}_{\text{data}}] \tag{A191}$$

$$+ \mathbb{E} \left[\frac{1}{2} \frac{(\upsilon^* - \bar{\operatorname{tr}}(\Sigma^*))}{\bar{\operatorname{tr}}(\Sigma^*)} \mathbb{E}_Z[\sqrt{\bar{\operatorname{tr}}(\Sigma^*)} Z \sigma(\sqrt{\bar{\operatorname{tr}}(\Sigma^*)} Z)] + \Delta \middle| \mathcal{E}_{\operatorname{data}} \right]$$
(A192)

$$= \mathbb{E}\left[\frac{1}{2}\frac{(\upsilon^* - \bar{\operatorname{tr}}(\Sigma^*))}{\bar{\operatorname{tr}}(\Sigma^*)}\mathbb{E}_Z[\sqrt{\bar{\operatorname{tr}}(\Sigma^*)}Z\sigma(\sqrt{\bar{\operatorname{tr}}(\Sigma^*)}Z)] + \Delta|\mathcal{E}_{\operatorname{data}}\right],\tag{A193}$$

where Z is a standard Gaussian. The first term of Eq. (A193) is less than $Cn_0^{c-1/2}$ and the remainder term Δ is less than Cn_0^{c-1} on $\mathcal{E}_{\text{data}}$. More detail on this argument can be found in [1]. Taking expectation over the remaining randomness, we see $\mathbb{E}[\delta|\mathcal{E}_{\text{data}}] \leq Cn_0^{c-1/2}$.

Similarly,

$$\mathbb{V}_{W}[\delta|\mathcal{E}_{\text{data}}] = \frac{1}{n_{1}^{2}} \sum_{k=1}^{n_{1}} \mathbb{V}_{W} \left[\sigma \left(\sum_{j=1}^{n_{0}} W_{kj} x_{j} / \sqrt{n_{0}} \right) \middle| \mathcal{E}_{\text{data}} \right] = \frac{1}{n_{1}} \mathbb{V}_{Z \sim \mathcal{N}(0, \upsilon^{*})} \sigma(Z), \quad (A194)$$

where we can again Taylor expand in $v^* - \bar{\operatorname{tr}}(\Sigma^*)$ to get the bound $\mathbb{V}_W[\delta|\mathcal{E}_{\text{data}}] \leq C/n_0$ on $\mathcal{E}_{\text{data}}$. Using the law of total variance, we can then bound $\mathbb{V}[\delta|\mathcal{E}_{\text{data}}] \leq C/n_0$.

Finally applying Chebyshev's inequality implies for all c > 0 that

$$\mathbb{P}[|\delta - \mathbb{E}[\delta|\mathcal{E}_{\text{data}}]| > Cn_0^{c-1/2}|\mathcal{E}_{\text{data}}] \le Cn_0^{-c}, \tag{A195}$$

and so

$$\mathbb{P}[|\delta| > C n_0^{c-1/2} | \mathcal{E}_{\text{data}}] \le C n_0^{-c}. \tag{A196}$$

Controlling c_0 , c_1 , and c_2 : Here, we introduce conditioning on the event \mathcal{E}_F . The results for c_0 , c_1 , and c_2 can be found using a similar argument to terms in [41, Lemma 9.6/Step 3]. The identifications $c_0 \leftrightarrow K_{11}$, $c_1 \leftrightarrow K_{12}$, $c_2 \leftrightarrow 1 - K_{22}$ hold.

For $c_0 = \frac{1}{m} \mathbf{u}^{\top} \bar{K}^{-1} \mathbf{u}$ we have that

$$c_0 \le \frac{a^2 \|1_m\|^2}{m} \|\bar{K}^{-1}\|_{\infty} \le \frac{C}{\gamma}$$
 (A197)

and

$$c_0 \ge \frac{a^2 \|1_m\|^2}{m} \lambda_{\min}(\bar{K}^{-1}) \ge \frac{C}{(\gamma + \|\bar{F}\|_{-1}^2 / n_0)} \ge c n_0^{-c}$$
(A198)

using the operator norm bound on the event \mathcal{E}_F .

For $c_1 = 1 + \mathbf{u}^{\top} \bar{K}^{-1} \mathbf{v}$ we have

$$|c_1| = \left| 1 + a \mathbf{1}_m^\top \bar{K}^{-1} \frac{\bar{F}^\top}{\sqrt{n_1}} \frac{\mathbf{1}_{n_1}}{\sqrt{n_1}} \right| \le 1 + a \|\mathbf{1}_m\|_2 \frac{\|\mathbf{1}_{n_1}\|_2}{\sqrt{n_1}} \|\bar{K}^{-1} \frac{\bar{F}}{\sqrt{n_1}}\| \le C n_0^{1/2}, \tag{A199}$$

where the bound $\|\bar{K}^{-1}\frac{\bar{F}}{\sqrt{n_1}}\| \leq C$ follows by considering the SVD of \bar{F} .

For $c_2 = 1 - \mathbf{v}^{\top} \bar{K}^{-1} \mathbf{v}$ we obviously have that $c_2 \leq 1$ since $\mathbf{v}^{\top} \bar{K}^{-1} \mathbf{v} \geq 0$. Additionally, we have that

$$c_2 = 1 - \frac{1}{n_1} \mathbf{1}_{n_1}^{\top} \frac{\bar{F}}{\sqrt{n_1}} \bar{K}^{-1} \frac{\bar{F}^{\top}}{\sqrt{n_1}} \mathbf{1}_{n_1}$$
 (A200)

$$= \frac{1_{n_1}^{\top}}{\sqrt{n_1}} \left(I_{n_1} - \frac{\bar{F}}{\sqrt{n_1}} \bar{K}^{-1} \frac{\bar{F}^{\top}}{\sqrt{n_1}} \right) \frac{1_{n_1}}{\sqrt{n_1}}$$
(A201)

$$\geq 1 - \|\frac{\bar{F}}{\sqrt{n_1}}\bar{K}^{-1}\frac{\bar{F}^{\top}}{\sqrt{n_1}}\|_{\infty}$$
 (A202)

$$=1-\frac{\|\bar{F}/\sqrt{n_1}\|_{\infty}^2}{\gamma+\|\bar{F}/\sqrt{n_1}\|_{\infty}^2} \ge 1-\frac{cn_0^c}{\gamma+cn_0^c}$$
(A203)

$$\geq \frac{C\gamma}{cn_0^c} \tag{A204}$$

$$\geq c n_0^{-c} \tag{A205}$$

as desired once again using the conditioning on the event \mathcal{E}_F .

Finally,

$$\mathbf{v}^{\top} \bar{K}^{-1} \mathbf{v} = \frac{1}{n_1} \mathbf{1}_{n_1}^{\top} \frac{\bar{F}}{\sqrt{n_1}} \bar{K}^{-1} \frac{\bar{F}^{\top}}{\sqrt{n_1}} \mathbf{1}_{n_1} \le \frac{\|\mathbf{1}_{n_1}\|_2^2}{n_1} \left\| \frac{\bar{F}}{\sqrt{n_1}} \bar{K}^{-1} \frac{\bar{F}^{\top}}{\sqrt{n_1}} \right\|_{\infty} \le C$$
 (A206)

since $\frac{\bar{F}}{\sqrt{n_1}}\bar{K}^{-1}\frac{\bar{F}^{\top}}{\sqrt{n_1}} \leq C$ follows once again by considering the SVD of \bar{F} .

Controlling $Y\bar{K}^{-1}\mathbf{v}^{\top}$: Here, we introduce conditioning on the event $\mathcal{E}_{\text{data}}$ and note its independence from β and ε . Recalling that $Y = \beta^{\top}X/\sqrt{n_0} + \varepsilon$, we note that Y has expectation zero since $\mathbb{E}_{\beta,\varepsilon}[Y\bar{K}^{-1}\mathbf{v}^{\top}|\mathcal{E}_{\text{data}}] = 0$. Similarly the conditional variance can be bounded as

$$\mathbb{V}_{\beta,\varepsilon}[Y\bar{K}^{-1}\mathbf{v}^{\top}|\mathcal{E}_{\text{data}}] = \mathbf{v}^{\top}\bar{K}^{-1}(\Upsilon + \sigma_{\varepsilon}^{2}I_{m})\bar{K}^{-1}\mathbf{v}$$
(A207)

$$\leq \left\| \Upsilon + \sigma_{\varepsilon}^{2} I_{m} \right\|_{\infty} \left\| \bar{K}^{-1} \frac{\bar{F}^{\top}}{\sqrt{n_{1}}} \right\|_{\infty}^{2} \left\| \frac{1_{n_{1}}}{\sqrt{n_{1}}} \right\|_{2}^{2} \tag{A208}$$

$$\leq C.$$
 (A209)

The bound $\|\bar{K}^{-1}\frac{\bar{F}^{\top}}{\sqrt{n_1}}\|_{\infty} \leq C$ follows by considering the SVD of F as in the proof of Lem. A9.6, while the bound $\|\Upsilon\| \leq C$ holds on $\mathcal{E}_{\text{data}}$. The law of total variance then shows $\mathbb{V}[Y\bar{K}^{-1}\mathbf{v}^{\top}|\mathcal{E}_{\text{data}}] \leq C$ also. Hence an application of Chebyshev's inequality shows that

$$\mathbb{P}[|Y\bar{K}^{-1}\mathbf{v}^{\top}| \ge Cn_0^c | \mathcal{E}_{\text{data}}] \le Cn_0^{-c} \tag{A210}$$

for some C > 0 and any c > 0.

Controlling $Y\bar{K}^{-1}\mathbf{u}^{\top}$: Again, we introduce conditioning on the event $\mathcal{E}_{\text{data}}$ and note its independence from β and ε . A nearly identical argument to the previous one suffices, so we only outline the

argument. Again $\mathbb{E}[Y\bar{K}^{-1}\mathbf{v}^{\top}|\mathcal{E}_{\text{data}}]=0$ and the conditional variance can be bounded as

$$\mathbb{V}_{\beta,\varepsilon}[Y\bar{K}^{-1}\mathbf{u}^{\top}|\mathcal{E}_{\text{data}}] = \mathbf{u}^{\top}\bar{K}^{-1}(\Upsilon + \sigma_{\varepsilon}^{2}I_{m})\bar{K}^{-1}\mathbf{u}$$
(A211)

$$\leq \|\bar{K}^{-1}\|_{\infty}^{2} \|\Upsilon + \sigma_{\varepsilon}^{2} I_{m}\|_{\infty} \|\mathbf{u}\|_{2}^{2}$$
 (A212)

$$\leq \frac{1}{\gamma^2} \cdot a^2 m \cdot \|\Upsilon + \sigma_{\varepsilon}^2 I_m\|_{\infty} \tag{A213}$$

$$\leq C n_0.$$
 (A214)

Finally, Chebyshev's inequality suffices to show

$$\mathbb{P}[|Y\bar{K}^{-1}\mathbf{u}^{\top}| \ge Cn_0^{c+1/2}|\mathcal{E}_{data}] \le Cn_0^{-c}$$
(A215)

for some C > 0 and any c > 0.

Controlling $\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}\mathbf{u}^{\top}$: Here, we introduce conditioning on the event \mathcal{E}_W and note its independence from \mathbf{x} . The overall argument then uses Chebyshev's inequality exploiting the randomness in \mathbf{x} . First,

$$\left| \mathbb{E}_{\mathbf{x}} [\bar{K}_{\mathbf{x}}^{\top} \bar{K}^{-1} \mathbf{u}^{\top} | \mathcal{E}_{W}] \right| = \left| \mathbb{E}_{\mathbf{x}} [\bar{f}^{\top} | \mathcal{E}_{W}] \frac{\bar{F}}{\sqrt{n_{1}}} \bar{K}^{-1} \mathbf{u}^{\top} / \sqrt{n_{1}} \right|$$
(A216)

$$\leq \left\| \mathbb{E}_{\mathbf{x}}[\bar{f}|\mathcal{E}_W] \right\|_2 \left\| \frac{\bar{F}}{\sqrt{n_1}} \bar{K}^{-1} \right\|_{\infty} \left\| \mathbf{u} / \sqrt{n_1} \right\|_2 \tag{A217}$$

$$\leq C n_0^c. \tag{A218}$$

The bound $\|\frac{\bar{F}}{\sqrt{n_1}}\bar{K}^{-1}\|_{\infty} \leq C$ follows by an SVD as before, while the first bound $\|\mathbb{E}_{\mathbf{x}}[\bar{f}^{\top}|\mathcal{E}_W]\|_2 \leq C n_0^c$ follows from the fact $\mathbb{E}_{\mathbf{x}}\bar{\sigma}(W\mathbf{x})_i \leq C n_0^{c-1/2}$ on \mathcal{E}_W (see Lem. A9.4). Next we turn to the conditional variance. We see

$$\mathbb{V}_{\mathbf{x}}[\bar{K}_{\mathbf{x}}\bar{K}^{-1}\mathbf{u}|\mathcal{E}_{W}] = \mathbf{u}^{\top}\bar{K}^{-1}\mathbb{E}_{\mathbf{x}}[\bar{K}_{\mathbf{x}}\bar{K}_{\mathbf{x}}^{\top}|\mathcal{E}_{W}]\bar{K}^{-1}\mathbf{u}$$
(A219)

$$= \frac{1}{n_1^2} \mathbf{u}^{\top} \bar{K}^{-1} \bar{F}^{\top} \left(\frac{\rho}{n_0} W \Sigma^* W^{\top} + (\eta - \zeta) I_{n_1} + \Delta \right) \bar{F} \bar{K}^{-1} \mathbf{u}$$
 (A220)

$$\leq \left\| \frac{\mathbf{u}}{\sqrt{n_1}} \right\|_2^2 \left\| \bar{K}^{-1} \frac{\bar{F}^\top}{\sqrt{n_1}} \right\|_2^2 \cdot \left(\left\| \rho \tilde{\Upsilon} \right\|_{\infty} + \left\| (\eta - \zeta) I_{n_1} \right\|_{\infty} + \left\| \Delta \right\|_{\infty} \right) \quad (A221)$$

$$\leq C \cdot (C + C + n_0^c) \tag{A222}$$

$$\leq C n_0^c. \tag{A223}$$

Once again the bound $\|\bar{K}^{-1}\frac{\bar{F}^{\top}}{\sqrt{n_1}}\|_2^2$ follows by considering the SVD, while the nontrivial operator norm bounds follow from Lem. A9.4. Using the law of total variance, we see

$$\mathbb{V}[\bar{K}_{\mathbf{x}}\bar{K}^{-1}\mathbf{u}|\mathcal{E}_{W}] = \mathbb{E}[\mathbb{V}_{\mathbf{x}}[\bar{K}_{\mathbf{x}}\bar{K}^{-1}\mathbf{u}|\mathcal{E}_{W}]|\mathcal{E}_{W}] + \mathbb{V}[\mathbb{E}_{\mathbf{x}}[\bar{K}_{\mathbf{x}}\bar{K}^{-1}\mathbf{u}|\mathcal{E}_{W}]|\mathcal{E}_{W}] \le Cn_{0}^{c}$$
(A224)

by Eqs. (A218) and (A223). Applying Chebyshev's inequality yields

$$\mathbb{P}[|\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}\mathbf{u} - \mathbb{E}_{\mathbf{x}}[\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}\mathbf{u}]| \ge Cn_0^c|\mathcal{E}_W] \le Cn_0^{-c},\tag{A225}$$

and so

$$\mathbb{P}[|\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}\mathbf{u}| \ge Cn_0^c|\mathcal{E}_W] \le Cn_0^{-c}$$
(A226)

by the triangle inequality since $|\mathbb{E}_{\mathbf{x}}[\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}\mathbf{u}]| \leq Cn_0^c$.

Controlling $\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}\mathbf{v}^{\top}$: Again, we introduce conditioning on the event \mathcal{E}_W and note its independence from \mathbf{x} . A nearly identical argument to the previous one shows the result for this term. Hence we only outline the argument. First, we see

$$\left| \mathbb{E}_{\mathbf{x}} [\bar{K}_{\mathbf{x}}^{\top} \bar{K}^{-1} \mathbf{v}^{\top} | \mathcal{E}_{W}] \right| = \left| \mathbb{E}_{\mathbf{x}} [\bar{f}^{\top} | \mathcal{E}_{W}] \frac{\bar{F}}{\sqrt{n_{1}}} \bar{K}^{-1} \frac{\bar{F}^{\top}}{\sqrt{n_{1}}} \frac{1_{n_{1}}}{n_{1}} \right|$$
(A227)

$$\leq \left\| \mathbb{E}_{\mathbf{x}}[\bar{f}^{\top} | \mathcal{E}_{W}] \right\|_{2} \left\| \frac{\bar{F}}{\sqrt{n_{1}}} \bar{K}^{-1} \frac{\bar{F}^{\top}}{\sqrt{n_{1}}} \right\|_{1} \left\| \frac{1_{n_{1}}}{n_{1}} \right\|_{2}$$
(A228)

$$\leq C n_0^{c-1/2}. (A229)$$

The bound $\|\frac{\bar{F}}{\sqrt{n_1}}\bar{K}^{-1}\frac{\bar{F}^{\top}}{\sqrt{n_1}}\|_{\infty} \leq 1$ follows by an SVD as before, while the first bound again follows from Lem. A9.4. Next we compute the conditional variance and bound as in Eq. (A223) to find

$$\mathbb{V}_{\mathbf{x}}[\bar{K}_{\mathbf{x}}\bar{K}^{-1}\mathbf{v}^{\top}|\mathcal{E}_{W}] = \mathbf{v}^{\top}\bar{K}^{-1}\mathbb{E}_{\mathbf{x}}[\bar{K}_{\mathbf{x}}\bar{K}_{\mathbf{x}}^{\top}|\mathcal{E}_{W}]\bar{K}^{-1}\mathbf{v}$$

$$= \frac{1}{n_{1}^{4}}\mathbf{1}_{n_{1}}^{\top}\bar{F}\bar{K}^{-1}\bar{F}^{\top}\left(\frac{\rho}{n_{0}}W\Sigma^{*}W^{\top} + (\eta - \zeta)I_{n_{1}} + \Delta\right)\bar{F}\bar{K}^{-1}\bar{F}^{\top}\mathbf{1}_{n_{1}}$$
(A231)

$$\leq \frac{1}{n_{1}} \left\| \frac{1_{n_{1}}}{\sqrt{n_{1}}} \right\|_{2}^{2} \cdot \left\| \frac{\bar{F}}{\sqrt{n_{1}}} \bar{K}^{-1} \frac{\bar{F}^{\top}}{\sqrt{n_{1}}} \right\|_{2}^{2} \cdot \left(\left\| \rho \tilde{\Upsilon} \right\|_{\infty} + \left\| (\eta - \zeta) I_{n_{1}} \right\|_{\infty} + \left\| \Delta \right\|_{\infty} \right)$$
(A232)

$$\leq \frac{C \cdot (C + C + n_0^c)}{n_1} \tag{A233}$$

$$\leq C n_0^{c-1}. (A234)$$

Once again the bound $\|\frac{\bar{F}}{\sqrt{n_1}}\bar{K}^{-1}\frac{\bar{F}^{\top}}{\sqrt{n_1}}\|_2 \leq 1$ follows by considering the SVD while the nontrivial operator norm bounds follow on \mathcal{E}_W . Now applying Chebyshev's inequality as before shows

$$\mathbb{P}[|\bar{K}_{\mathbf{x}}^{\top}\bar{K}^{-1}\mathbf{v}^{\top}| \ge Cn_0^{c-1/2}|\mathcal{E}_W] \le Cn_0^{-c}.$$
(A235)

Controlling $y(\mathbf{x})$: Finally we show $y(\mathbf{x}) \leq C n_0^c$ with probability at least $C n_0^{-c}$. Note that $\mathbb{E}[y(\mathbf{x})] = 0$ and a short computation shows that $\mathbb{V}[y(\mathbf{x})] = \bar{\operatorname{tr}}(\Sigma^*) + \sigma_\epsilon^2 \leq C$. So a direct application of Chebyshev's inequality shows that

$$\mathbb{P}[|y(\mathbf{x})| \ge Cn_0^c] \le Cn_0^{-c}.\tag{A236}$$

A9.1.5 Completing the argument for the typical behavior

Lemma A9.8. For some n_0 -independent constants c > 0 and C > 0, we have

$$|\mathbb{E}\left[\mathbf{1}_{\mathcal{E}}\Delta y(\mathbf{x})\right]| \le Cn_0^{-c} \tag{A237}$$

and

$$\left| \mathbb{E} \left[\mathbf{1}_{\mathcal{E}} \Delta (K_{\mathbf{x}}^{\top} K^{-1} Y^{\top} + \bar{K}_{\mathbf{x}}^{\top} \bar{K}^{-1} Y^{\top}) \right] \right| \le C n_0^{-c}$$
(A238)

Proof. Obviously, $|\mathbb{E}[\mathbf{1}_{\mathcal{E}}\Delta y(\mathbf{x})]|$ is bounded by $|\mathbb{E}[\Delta y(\mathbf{x})]|\mathcal{E}|$, so we can remove the indicator $\mathbf{1}_{\mathcal{E}}$ from the expectations in Eqs. (A237) and (A238) by conditioning on \mathcal{E} .

We want to show that conditional on \mathcal{E} and for some n_0 -independent constants c>0 and C>0, the bounds $|\Delta| \leq C n_0^{-2c}$, $|y(\mathbf{x})| \leq C n_0^c$, and $\left|(K_{\mathbf{x}}^\top K^{-1} Y^\top + \bar{K}_{\mathbf{x}}^\top \bar{K}^{-1} Y^\top)\right| \leq C n_0^c$ hold.

Recall,
$$a := \mathbb{E}_Z \sigma\left(\sqrt{\operatorname{tr}(\Sigma)}Z\right)$$
, $a^* := \mathbb{E}_Z \sigma\left(\sqrt{\operatorname{tr}(\Sigma^*)}Z\right)$, $\mathbf{v} := 1/n_1 \bar{F}^\top 1_{n_1}$, $\mathbf{u} := a 1_m$, $U := [\mathbf{u}, \mathbf{v}]^\top$, and $C := \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$.

First, consider the term $\Delta = YT_1 + YT_2$. To show that $|\Delta| \leq Cn_0^{-2c}$ on \mathcal{E} , we write out YT_1 and YT_2 more explicitly:

$$YT_1 = Y\bar{K}^{-1}U^{\top} \left(I_2 + CU\bar{K}^{-1}U^{\top} \right)^{-1} P \tag{A239}$$

$$= \frac{1}{c_1^2 + mc_0c_2} \begin{pmatrix} Y\bar{K}^{-1}\mathbf{u} \\ Y\bar{K}^{-1}\mathbf{v} \end{pmatrix}^{\top} \begin{pmatrix} c_1\delta + c_2a^* \\ -mc_0\delta + c_1a^* \end{pmatrix}$$
(A240)

$$= \frac{1}{c_1^2 + mc_0c_2} \left(Y\bar{K}^{-1}\mathbf{u} \cdot (c_1\delta + c_2a^*) + Y\bar{K}^{-1}\mathbf{v} \cdot (-mc_0\delta + c_1a^*) \right)$$
(A241)

(A242)

and

$$YT_2 = -Y\bar{K}^{-1}U^{\top} \left(I_2 + CU\bar{K}^{-1}U^{\top} \right)^{-1} CU\bar{K}^{-1}\bar{K}_{\mathbf{x}}$$
 (A243)

$$= \frac{1}{c_1^2 + mc_0c_2} \begin{pmatrix} Y\bar{K}^{-1}\mathbf{u} \\ Y\bar{K}^{-1}\mathbf{v} \end{pmatrix}^{\top} \begin{pmatrix} c_2 & c_1 \\ c_1 & -mc_0 \end{pmatrix} \begin{pmatrix} \mathbf{u}^{\top}\bar{K}^{-1}\bar{K}_{\mathbf{x}} \\ \mathbf{v}^{\top}\bar{K}^{-1}\bar{K}_{\mathbf{x}} \end{pmatrix}$$
(A244)

$$\leq \frac{1}{c_1^2 + mc_0c_2} \left(Y \bar{K}^{-1} \mathbf{u} \cdot (c_2 \mathbf{u}^\top \bar{K}^{-1} \bar{K}_{\mathbf{x}} + c_1 \mathbf{v}^\top \bar{K}^{-1} \bar{K}_{\mathbf{x}} \right) \tag{A245}$$

$$+ Y \bar{K}^{-1} \mathbf{v} \cdot \left(c_1 \mathbf{u}^\top \bar{K}^{-1} \bar{K}_{\mathbf{x}} - m c_0 \mathbf{v}^\top \bar{K}^{-1} \bar{K}_{\mathbf{x}} \right) \right). \tag{A246}$$

Now using Eq. (A239) and the definition of \mathcal{E} , we see that on \mathcal{E}

$$|YT_{1}| \leq \left| \frac{1}{c_{1}^{2} + mc_{0}c_{2}} \right| \left(\left| Y\bar{K}^{-1}\mathbf{u} \right| \left(\left| c_{1} \right| \left| \delta \right| + \left| c_{2} \right| \left| a^{*} \right| \right) + \left| Y\bar{K}^{-1}\mathbf{v} \right| \left(m \left| c_{0} \right| \left| \delta \right| + \left| c_{1} \right| \left| a^{*} \right| \right) \right)$$
(A247)

$$\leq C n_0^{2c-1} \left(C n_0^{c+1/2} (C n_0^c C n_0^{c-1/2} + C n_0^c) + C n_0^c (C n_0 C n_0^c C n_0^{c-1/2} + C n_0^c) \right) \ \, (\text{A248})$$

$$\leq C n_0^{5c-1/2}.$$
(A249)

Since the cs used in the bounds above can be arbitrarily small, we may replace write $|YT_1| \le Cn_0^{c-1/2}$ for arbitrarily small c > 0. Finally, a similar argument for Eq. (A243) yields the bound

$$|YT_2| \le \left| \frac{1}{c_1^2 + mc_0 c_2} \right| \left(|Y\bar{K}^{-1}\mathbf{u}| \cdot (|c_2||\mathbf{u}^\top \bar{K}^{-1}\bar{K}_{\mathbf{x}}| + |c_1||\mathbf{v}^\top \bar{K}^{-1}\bar{K}_{\mathbf{x}}| \right)$$
(A250)

$$+ |Y\bar{K}^{-1}\mathbf{v}| \cdot (|c_1||\mathbf{u}^\top \bar{K}^{-1}\bar{K}_{\mathbf{x}}| - m|c_0||\mathbf{v}^\top \bar{K}^{-1}\bar{K}_{\mathbf{x}}|))$$
(A251)

$$\leq C n_0^{2c-1} \cdot \left(C n_0^{c+1/2} \cdot \left(C n_0^c C n_0^c + C n_0^{c+1/2} C n_0^{c-1/2} \right) \right) \tag{A252}$$

$$+Cn_0^c \cdot \left(Cn_0^{c+1/2}Cn_0^c + Cn_0Cn_0^cCn_0^{c-1/2}\right)\right) \tag{A253}$$

$$\leq C n_0^{2c-1} \cdot (C n_0^{3c+1/2} + C n_0^{3c+1/2})$$
 (A254)

$$\leq C n_0^{5c-1/2}.$$
(A255)

and as before since c can be chosen arbitrarily small we can write $|YT_2| \leq C n_0^{c-1/2}$.

A9.2 Gaussian equivalents

Before describing how Gaussian equivalents can be used to compute the test error in the high-dimensional limit, we make the following observation: the asymptotic test error is invariant to the centering of the activation function across the train and test distributions. More concretely, from the results in Sec. A9.1, the asymptotic test error is unchanged under the replacements $F_{ij} \to \bar{F}_{ij}$ and $f_i \to \bar{f}_i$, for all i and j, where,

$$\bar{F}_{ij} := F_{ij} - \mathbb{E}_{z \sim \mathcal{N}(0, \bar{\operatorname{tr}}(\Sigma))} \sigma(z) \quad \text{and} \quad \bar{f}_i := f_i - \mathbb{E}_{z \sim \mathcal{N}(0, \bar{\operatorname{tr}}(\Sigma^*))} \sigma(z) . \tag{A256}$$

With this simplification in mind, the proof of Thm. 5.1 relies on the concept of Gaussian equivalents and the linearization analysis developed in [2, 3, 1], which we briefly review here, though we refer the reader to these works for a more detailed description. The centered activation-constants are defined as $\bar{\zeta} = s\bar{\rho}$ with

$$\bar{\eta} := \mathbb{E}_{z \sim \mathcal{N}(0,s)}[\bar{\sigma}(z)^2] \quad \text{and} \quad \bar{\rho} := \left(\frac{1}{s} \mathbb{E}_{z \sim \mathcal{N}(0,s)}[z\bar{\sigma}(z)]\right)^2. \tag{A257}$$

Note that by the continuity of σ , we know that as $n_0 \to \infty$

$$\mathbb{E}_{z \sim \mathcal{N}(0, \bar{\mathrm{tr}}(\Sigma))}[\bar{\sigma}(z)^2] \to \bar{\eta}. \tag{A258}$$

Similarly for $\bar{\zeta}$ and $\bar{\rho}$ or when $\bar{\operatorname{tr}}(\Sigma)$ is replaced by $\bar{\operatorname{tr}}(\Sigma^*)$. To proceed, we define the moment-matched Gaussian linearizations,

$$\bar{F} \to \sqrt{\frac{\bar{\rho}}{n_0}} W X + \sqrt{\bar{\eta} - \bar{\zeta}} \Theta \quad \text{and} \quad \bar{f} \to \sqrt{\frac{\bar{\rho}}{n_0}} W \mathbf{x} + \sqrt{\bar{\eta} - \bar{\zeta}} \theta$$
 (A259)

where $\bar{f} := \bar{\sigma}(W\mathbf{x}/\sqrt{n_0})$ is the random feature representation of the test point \mathbf{x} and $y := \beta^{\top}\mathbf{x}/\sqrt{n_0}$ is its corresponding label, which we assume has no additive noise⁹.

The new objects Θ and θ are matrices of the appropriate shapes with i.i.d. standard Gaussian entries independent of the other random variables under consideration. The constants $\bar{\eta}$ and $\bar{\zeta}$ are chosen so that the mixed moments up to second order are the same for the original and linearized matrices. The Gaussian equivalents defined are essentially constructed via a Taylor expansion of the nonlinearity $\bar{\sigma}$. The explicit calculations defining these expressions can be found via the Gaussian moment matching technique in [1].

Having appropriately linearized the random feature matrices, we can map back to the definition of the original activation functions by recalling that the variable ζ , defined in Sec. 5.1 as $\zeta = s\rho$, with

$$\eta := \bar{\eta} = \mathbb{E}_{z \sim \mathcal{N}(0,s)}[(\sigma(z) - \mathbb{E}_{z \sim \mathcal{N}(0,s)}[\sigma(z)])^2] = \mathbb{V}_{z \sim \mathcal{N}(0,s)}[\sigma(z)]$$
(A260)

$$\rho := \bar{\rho} = (\frac{1}{s} \mathbb{E}_{z \sim \mathcal{N}(0,s)} [z(\sigma(z) - \mathbb{E}_{z \sim \mathcal{N}(0,s)} [\sigma(z)])])^2 = (\frac{1}{s} \mathbb{E}_{z \sim \mathcal{N}(0,s)} [z(\sigma(z)])^2$$
(A261)

by using the definition of the centering. Effectively, this is equivalent to using the linearizations,

$$F \to \bar{F} \to \sqrt{\frac{\rho}{n_0}} W X + \sqrt{\eta - \zeta} \Theta$$
 and $f \to \bar{f} \to \sqrt{\frac{\rho}{n_0}} W \mathbf{x} + \sqrt{\eta - \zeta} \theta$ (A262)

directly to compute the test error.

Simply by definition, the teacher function is exactly linear,

$$Y = \sqrt{\frac{1}{n_0}} \beta^{\mathsf{T}} X + \varepsilon \quad \text{and} \quad y = \sqrt{\frac{1}{n_0}} \beta^{\mathsf{T}} \mathbf{x} \,.$$
 (A263)

We emphasize that the restriction to linear teacher functions is simply a matter of convenience and simplicity — nonlinear teacher neural networks can be studied by means of an analogous linearization process, as discussed in [2], which merely requires introducing additional moment-matching constants and additional i.i.d. standard Gaussian terms θ and θ_y .

In the high-dimensional limit the bulk statistics we compute defining the error, bias, and variance are invariant to the above replacements by linearized Gaussian equivalents. We remark that further intuition for these linearized information-plus-noise replacements can be gathered from the universality results of [5, 6]. To summarize briefly, the final expressions we compute are tracial (nonlinear) functions of several random matrices. A large body of universality results (e.g. [6, 17]) show that in the asymptotic limit it is sufficient to calculate with an equivalent tracial functional of a (linearized) rational function of random matrices, whose moments match their nonlinear counterparts.

More specifically, two basic trace objects arise in the calculations, which take the form

$$\operatorname{tr}(AB)$$
 and $\operatorname{tr}\left(A\frac{1}{B-zI}\right)$. (A264)

For the first case, $\operatorname{tr}(AB)$, if the random matrices A and B are independent, its asymptotics can be understood via concentration of measure arguments. Conditionally on A, it is sufficient to replace B with an equivalent matrix designed to match low-order moments, at the expense of an error that vanishes asymptotically. The second case, $\operatorname{tr}\left(A\frac{1}{B-zI}\right)$, is a bit more involved. Our arguments proceed by 1) utilizing the linearized matrices in Eq. (A262) to express the trace object as a rational function of i.i.d. Gaussian matrices, and then 2) using the linear pencil method 10 [25, 45] to express it as the trace of a large (inverted) block matrix. The reason the linearization over B preserves the asymptotic statistics even for general A with correlated entries stems from the matrix Dyson equation [17].

A9.3 Decomposition of the test loss

Recall the expression for the test loss in Eq. (A84),

$$E_{\Sigma^*} = E_1 + E_2 + E_3 \tag{A265}$$

⁹Including noise on the test labels merely shifts by the total error by an irreducible additive constant.

¹⁰This is essentially an iterative application of the Schur complement formula.

with

$$E_1 = \mathbb{E}_{(\mathbf{x}, \beta, \varepsilon)} y(\mathbf{x})^2 = \mathbb{E}_{(\mathbf{x}, \varepsilon)} \operatorname{tr}(y(\mathbf{x}) y(\mathbf{x})^\top)$$
(A266)

$$E_2 = -2\mathbb{E}_{(\mathbf{x},\beta,\varepsilon)}(K_{\mathbf{x}}^{\top}K^{-1}Y)y(\mathbf{x}) = -2\mathbb{E}_{(\mathbf{x},\varepsilon)}\operatorname{tr}(K_{\mathbf{x}}^{\top}K^{-1}Y^{\top}y(\mathbf{x}))$$
(A267)

$$E_3 = \mathbb{E}_{(\mathbf{x},\beta,\varepsilon)} (K_{\mathbf{x}}^\top K^{-1} Y^\top)^2 = \mathbb{E}_{(\mathbf{x},\varepsilon)} \operatorname{tr} (K_{\mathbf{x}}^\top K^{-1} Y^\top Y K^{-1} K_{\mathbf{x}}),$$
 (A268)

where the kernels K = K(X, X) and $K_{\mathbf{x}} = K(X, \mathbf{x})$ are given by,

$$K = \frac{F^{\top}F}{n_1} + \gamma I_m$$
 and $K_{\mathbf{x}} = \frac{1}{n_1}F^{\top}f$. (A269)

Using the cyclicity and linearity of the trace, the expectation over x requires the computation of

$$\mathbb{E}_{\mathbf{x}} K_{\mathbf{x}} K_{\mathbf{x}}^{\top}, \qquad \mathbb{E}_{\mathbf{x}} y(\mathbf{x}) K_{\mathbf{x}}^{\top}, \qquad \mathbb{E}_{\mathbf{x}} y(\mathbf{x}) y(\mathbf{x})^{\top}.$$
 (A270)

As described in Sec. A9.2, without loss of generality we consider the case of a linear teacher, and Eqs. (A262) and (A263) read

$$y = \frac{1}{\sqrt{n_0}} \beta^{\mathsf{T}} \mathbf{x}$$
 and $f \to f^{\mathsf{lin}} = \frac{\sqrt{\rho}}{\sqrt{n_0}} W \mathbf{x} + \sqrt{\eta - \zeta} \theta$. (A271)

The expectations over x are now trivial and we readily find,

$$\mathbb{E}_{\mathbf{x}} K_{\mathbf{x}} K_{\mathbf{x}}^{\top} = \frac{1}{n_1^2} F^{\top} \left(\frac{\rho}{n_0} W \Sigma^* W^{\top} + (\eta - \zeta) I_{n_1} \right) F \tag{A272}$$

$$\mathbb{E}_{\mathbf{x}} y(\mathbf{x}) K_{\mathbf{x}}^{\top} = \frac{\sqrt{\rho}}{n_0 n_1} \beta^{\top} \Sigma^* W^{\top} F$$
(A273)

$$\mathbb{E}_{\mathbf{x}} y(\mathbf{x}) y(\mathbf{x})^{\top} = \frac{1}{n_0} \beta \Sigma^* \beta^{\top}$$
(A274)

One may interpret the substitution in Eq. (A271) as a tool to calculate the expectations above to leading order, which generates terms like Eq. (A264). Next, we recall the definition, $Y = \beta^{T} X / \sqrt{n_0} + \varepsilon$, and, as above, we consider the leading order behavior with respect to the random variables β to find

$$\mathbb{E}_{\beta,\varepsilon} \left[Y^{\top} Y \right] = \frac{1}{n_0} X^{\top} X + \sigma_{\varepsilon}^2 I_m \tag{A275}$$

$$\mathbb{E}_{\beta,\varepsilon} \left[Y^{\top} \mathbb{E}_{\mathbf{x}} y(\mathbf{x}) K_{\mathbf{x}}^{\top} \right] = \frac{\sqrt{\rho}}{n_0^{3/2} n_1} X^{\top} \Sigma^* W^{\top} F.$$
 (A276)

Putting these pieces together, we have

$$E_1 = \frac{\operatorname{tr}(\Sigma^*)}{n_0} \tag{A277}$$

$$E_2 = E_{21}$$
 (A278)

$$E_3 = E_{31} + E_{32} \,, \tag{A279}$$

where,

$$E_{21} = -2\frac{\sqrt{\rho}}{n_0^{3/2}n_1} \mathbb{E} \text{tr} \left(X^{\top} \Sigma^* W^{\top} F K^{-1} \right)$$
 (A280)

$$E_{31} = \sigma_{\varepsilon}^2 \mathbb{E} \operatorname{tr} \left(K^{-1} \Sigma_3 K^{-1} \right) \tag{A281}$$

$$E_{32} = \frac{1}{n_0} \mathbb{E} \text{tr} \left(K^{-1} \Sigma_3 K^{-1} X^{\top} X \right)$$
 (A282)

and,

$$\Sigma_3 = \frac{\rho}{n_0 n_1^2} F^{\top} W \Sigma^* W^{\top} F + \frac{\eta - \zeta}{n_1^2} F^{\top} F.$$
 (A283)

A9.4 Decomposition of the bias and total variance

Note that it is sufficient to calculate the bias term since given the total test loss, since the total variance can be obtained as $V_{\Sigma^*} = E_{\Sigma^*} - B_{\Sigma^*}$. Following the total multivariate bias-variance decomposition of [3], for each random variable in question we introduce an i.i.d. copy of it denoted by either the subscript 1 or 2. We can then write,

$$B_{\Sigma^*} = \mathbb{E}_{(\mathbf{x},y)} (y - \mathbb{E}_{(W,X,\varepsilon)} \hat{y}(\mathbf{x}; W, X, \varepsilon))^2$$
(A284)

$$= \mathbb{E}_{(\mathbf{x},y)} \mathbb{E}_{(W_1,X_1,\varepsilon_1)} \mathbb{E}_{(W_2,X_2,\varepsilon_2)} (y - \hat{y}(\mathbf{x};W_1,X_1,\varepsilon_1)) (y - \hat{y}(\mathbf{x};W_2,X_2,\varepsilon_2))$$
(A285)

$$= \frac{\operatorname{tr}(\Sigma^*)}{n_0} + E_{21} + H_{000}, \tag{A286}$$

where an expression for E_{21} was given previously and H_{000} satisfies

$$H_{000} = \mathbb{E}\hat{y}(\mathbf{x}; W_1, X_1, \varepsilon_1)\hat{y}(\mathbf{x}; W_2, X_2, \epsilon_2), \tag{A287}$$

where the expectations are over $\mathbf{x}, W_1, X_1, \varepsilon_1, W_2, X_2$, and ϵ_2 . Recalling the definition of \hat{y} ,

$$\hat{y}(\mathbf{x}; W, X, \varepsilon) := Y(X, \epsilon)K(X, X; W)^{-1}K(X, \mathbf{x}; W) \tag{A288}$$

and the techniques described in the previous section, it is straightforward to analyze the above term. First note we can write,

$$\mathbb{E}_{\mathbf{x}}K(X_1, \mathbf{x}; W_1)K(\mathbf{x}, X_2; W_2) = \frac{\rho}{n_0 n_1^2} F_{11}^\top W_1 \Sigma^* W_2^\top F_{22}$$
(A289)

since the f linearizations use different sources of auxiliary randomness. Here we have defined $F_{11} \equiv F(W_1, X_1)$ and $F_{22} \equiv F(W_2, X_2)$. Now we proceed to calculate H_{000} as

$$H_{000} = \mathbb{E}\hat{y}(\mathbf{x}; W_{1}, X_{1}, \varepsilon)\hat{y}(\mathbf{x}; W_{2}, X_{2}, \epsilon_{2})$$

$$= \mathbb{E}K(\mathbf{x}, X_{2}; W_{2})K(X_{2}, X_{2}; W_{2})^{-1}Y(X_{2}, \epsilon_{2})^{\top}Y(X_{1}, \varepsilon_{1})K(X_{1}, X_{1}; W_{1})^{-1}K(X_{1}, \mathbf{x}; W)$$

$$= \mathbb{E}\operatorname{tr}\left(K(X_{2}, X_{2}; W_{2})^{-1}X_{2}^{\top}X_{1}K(X_{1}, X_{1}; W_{1})^{-1}K(X_{1}, \mathbf{x}; W)K(\mathbf{x}, X_{2}; W_{2})\right)$$

$$= \frac{\rho}{n_{0}^{2}n_{1}^{2}}\mathbb{E}\operatorname{tr}\left(K_{22}^{-1}X_{2}^{\top}X_{1}K_{11}^{-1}F_{11}^{\top}W_{1}\Sigma^{*}W_{2}^{\top}F_{22}\right)$$

$$= E_{4},$$
(A294)

where in the second-to-last line we have defined $K_{11} \equiv K(X_1, X_1; W_1)$ and $K_{22} \equiv K(X_2, X_2; W_2)$.

A9.5 Summary of linearized trace terms

We now summarize the requisite terms needed to compute the total test error, bias, and variance after using cyclicity of the trace to rearrange several of them. In the following, we slightly change notation in order to make explicit the dependence on the population covariance matrices Σ and Σ^* . To be specific, whereas above we assumed that the columns of X_1 and X_2 were drawn from multivariate Gaussians with covariance Σ , below we assume that they are drawn from multivariate Gaussians with identity covariance. This change is equivalent to replaceing $X_1 \to \Sigma^{1/2} X_1$ and $X_2 \to \Sigma^{1/2} X_2$ in the above expressions. We utilize this definition so that X_1 , X_2 , W_1 , W_2 , and Θ all have i.i.d.

standard Gaussian entries. From the previous computations, we can now write the requisite terms as,

$$\Sigma_3 = \frac{\rho}{n_0 n_1^2} F_{11}^{\top} W_1 \Sigma^* W_1^{\top} F_{11} + \frac{\eta - \zeta}{n_1^2} F_{11}^{\top} F_{11}$$
 (A295)

$$E_{21} = -2 \frac{\sqrt{\rho}}{n_0^{3/2} n_1} \operatorname{tr} \left(X_1^{\top} \Sigma^{1/2} \Sigma^* W_1^{\top} F_{11} K_{11}^{-1} \right)$$
 (A296)

$$E_{31} = \sigma_{\epsilon}^{2} \operatorname{tr} \left(K_{11}^{-1} \Sigma_{3} K_{11}^{-1} \right) \tag{A297}$$

$$E_{32} = \frac{1}{n_0} \operatorname{tr} \left(K_{11}^{-1} \Sigma_3 K_{11}^{-1} X_1^{\top} \Sigma X_1 \right)$$
 (A298)

$$E_4 = \frac{\rho}{n_0^2 n_1^2} \text{tr} \left(F_{22} K_{22}^{-1} X_2^{\top} \Sigma X_1 K_{11}^{-1} F_{11}^{\top} W_1 \Sigma^* W_2^{\top} \right)$$
 (A299)

$$E_{\Sigma^*} = \frac{\operatorname{tr}(\Sigma^*)}{n_0} + E_{21} + E_{31} + E_{32}$$
 (A300)

$$B_{\Sigma^*} = \frac{\operatorname{tr}(\Sigma^*)}{n_0} + E_{21} + E_4$$
 (A301)
 $V_{\Sigma^*} = E_{\Sigma^*} - B_{\Sigma^*}$ (A302)

$$V_{\Sigma^*} = E_{\Sigma^*} - B_{\Sigma^*} \tag{A302}$$

In the remainder of this section we use the machinery of operator-valued free probability [45] and a series of lengthy algebraic computations to compute the asymptotic tracial expressions in $E_{21}, E_{31}, E_{32}, E_4$, from which the total test error, bias, and variance can be reconstructed.

A9.6 Calculation of error terms

To compute the test error, bias, and total variance, we need to evaluate the asymptotic trace objects appearing in the expressions for E_{21} , E_{31} , E_{32} , and E_{4} , defined in the previous section. As these expressions are essentially rational functions of the random matrices X, W, Θ, Σ , and Σ^* , these computations can be accomplished by constructing a linear pencil [19] and using the theory of operator-valued free probability [45]. These techniques and their application to problems of this type have been well-established elsewhere [1, 2, 3], we only sketch the mathematical details, referring the reader to the literature for a more pedagogical overview. Instead, we focus on presenting the details of the requisite calculations.

Relative to the prior work of [2, 3], the main challenge in the current setting is generalizing the calculations to include an arbitrary training covariance matrix Σ . This generalization is facilitated by the general theory of operator-valued free probability, and in particular through the subordinated form of the operator-valued self-consistent equations that we first present in Eq. (A322). The form of this equation enables the simple computation of the operator-valued R-transform of the remaining random matrices, W, X, and Θ , which are all i.i.d. Gaussian and can therefore be obtained simply by using the methods of [19]. The remaining complication amounts to performing the trace in Eq. (A322), which becomes an integral over the LJSD μ in the limit. While this might in general lead to a complicated coupling of many transcendental equations, it turns out that the trascendentality can be entirely factored into a single scalar fixed-point equation, whose solution we denote by x (see Eq. (A345)), and the remaining equations are purely algebraic given x. To facilitate this particular simplification, it is necessary to first compute all of the entries in the operator-valued Stieltjes transform of the kernel matrix K, which we do in Sec. A9.6.1. Using these results, we compute the remaining error terms in the subsequent sections.

As a matter of notation, note that throughout this entire section whenever a matrix X, X_1 , or X_2 appears it is composed of i.i.d. standard Gaussian entries as in Sec. A9.5. This differs from the notation of the main paper, but we follow this prescription to ease the already cumbersome presentation. This definition of X allows us to explicitly extract and represent the training covariance Σ in our calculations.

A9.6.1 K^{-1}

Define the block matrix $Q^{K^{-1}}$ as,

$$Q^{K^{-1}} = \begin{pmatrix} I_m & \frac{\sqrt{\eta - \zeta}\Theta^{\top}}{\gamma\sqrt{n_1}} & \frac{\sqrt{\rho}X^{\top}}{\gamma\sqrt{n_0}} & 0 & 0 & 0\\ -\frac{\Theta\sqrt{\eta - \zeta}}{\sqrt{n_1}} & I_{n_1} & 0 & 0 & -\frac{\sqrt{\rho}W}{\sqrt{n_1}} & 0\\ 0 & 0 & I_{n_0} & -\Sigma^{1/2} & 0 & 0\\ 0 & -\frac{W^{\top}}{\sqrt{n_1}} & 0 & I_{n_0} & 0 & 0\\ 0 & 0 & 0 & 0 & I_{n_0} & -\Sigma^{1/2}\\ -\frac{X}{\sqrt{n_0}} & 0 & 0 & 0 & 0 & I_{n_0} \end{pmatrix}.$$
 (A303)

$$G_{1,1}^{K^{-1}} = \gamma \, \bar{\text{tr}}(K^{-1})$$
 (A304)

$$G_{2,2}^{K^{-1}} = \gamma \, \bar{\text{tr}}(\hat{K}^{-1})$$
 (A305)

$$G_{3,3}^{K^{-1}} = G_{6,6}^{K^{-1}} = 1 - \frac{\sqrt{\rho} \operatorname{tr} \left(\Sigma^{1/2} W^{\top} F K^{-1} X^{\top} \right)}{\sqrt{n_0} n_1}$$
 (A306)

$$G_{4,3}^{K^{-1}} = G_{6,5}^{K^{-1}} = \bar{\operatorname{tr}}(\Sigma^{1/2}) - \frac{\sqrt{\rho} \, \bar{\operatorname{tr}} \left(\Sigma W^{\top} F K^{-1} X^{\top}\right)}{\sqrt{n_0} n_1}$$
 (A307)

$$G_{4,3}^{K^{-1}} = G_{6,5}^{K^{-1}} = \bar{\operatorname{tr}}(\Sigma^{1/2}) - \frac{\sqrt{\rho} \,\bar{\operatorname{tr}} \left(\Sigma W^{\top} F K^{-1} X^{\top}\right)}{\sqrt{n_0} n_1}$$

$$G_{5,3}^{K^{-1}} = G_{6,4}^{K^{-1}} = \frac{\gamma \sqrt{\rho} \,\bar{\operatorname{tr}} \left(\Sigma^{1/2} W^{\top} \hat{K}^{-1} W\right)}{n_1}$$
(A308)

$$G_{6,3}^{K^{-1}} = \frac{\gamma\sqrt{\rho}\,\bar{\text{tr}}\left(\Sigma W^{\top}\hat{K}^{-1}W\right)}{n_1}$$

$$G_{3,4}^{K^{-1}} = G_{5,6}^{K^{-1}} = -\frac{\sqrt{\rho}\,\bar{\text{tr}}\left(FK^{-1}X^{\top}W^{\top}\right)}{\sqrt{n_0}n_1\psi}$$
(A309)

$$G_{3,4}^{K^{-1}} = G_{5,6}^{K^{-1}} = -\frac{\sqrt{\rho} \operatorname{tr} \left(F K^{-1} X^{\top} W^{\top} \right)}{\sqrt{n_0} n_1 \psi}$$
 (A310)

$$G_{4,4}^{K^{-1}} = G_{5,5}^{K^{-1}} = 1 - \frac{\sqrt{\rho} \operatorname{tr} \left(\Sigma^{1/2} W^{\top} F K^{-1} X^{\top} \right)}{\sqrt{n_0} n_1}$$
 (A311)

$$G_{4,4}^{K^{-1}} = G_{5,5}^{K^{-1}} = 1 - \frac{\sqrt{\rho} \operatorname{tr} \left(\Sigma^{1/2} W^{\top} F K^{-1} X^{\top} \right)}{\sqrt{n_0} n_1}$$

$$G_{5,4}^{K^{-1}} = \frac{\gamma \sqrt{\rho} \operatorname{tr} \left(\hat{K}^{-1} W W^{\top} \right)}{n_1 \psi}$$
(A311)

$$G_{3,5}^{K^{-1}} = G_{4,6}^{K^{-1}} = -\frac{\sqrt{\rho} \operatorname{tr} \left(\Sigma^{1/2} X K^{-1} X^{\top} \right)}{n_0}$$

$$G_{4,5}^{K^{-1}} = -\frac{\sqrt{\rho} \operatorname{tr} \left(\Sigma X K^{-1} X^{\top} \right)}{n_0}$$
(A313)

$$G_{4,5}^{K^{-1}} = -\frac{\sqrt{\rho} \operatorname{tr} \left(\Sigma X K^{-1} X^{\top} \right)}{n_0}$$
 (A314)

$$G_{3,5}^{K^{-1}} = G_{4,6}^{K^{-1}} = -\frac{\sqrt{\rho} \operatorname{tr} \left(\sum X K^{-1} X^{\top} \right)}{n_0}$$

$$G_{4,5}^{K^{-1}} = -\frac{\sqrt{\rho} \operatorname{tr} \left(K^{-1} X^{\top} X \right)}{n_0},$$
(A314)
$$G_{3,6}^{K^{-1}} = -\frac{\sqrt{\rho} \operatorname{tr} \left(K^{-1} X^{\top} X \right)}{n_0 \phi},$$
(A315)

where $G^{K^{-1}} := \mathrm{id}_6 \otimes \bar{\mathrm{tr}}\,[(Q^{K^{-1}})^\top]^{-1} \in M_6(\mathbb{C})$ is a scalar 6×6 matrix whose i,j entry $G^{K^{-1}}_{i,j}$ is the normalized trace of the (i,j)-block of the inverse of $[Q^{K^{-1}}]^\top$, and we have defined $\hat{K} = 0$ $\frac{1}{n_1}FF^{\top} + \gamma I_{n_1}$.

We aim to compute the limiting values of these trace terms as $n_0, n_1, m \to \infty$, as they will be related to the error terms of interest. Both here and in the sequel, to ease the already cumbersome presentation, we use G to denote the limiting values as well as the non-limiting values and we refrain from explicitly denoting the limit operation itself, noting its existing can be inferred from context.

To proceed, recall that the asymptotic block-wise traces of the inverse of $Q^{K^{-1}}$ can be determined from its operator-valued Stieltjes transform [45]. The simplest way to apply the results of [19, 45] is to augment $Q^{K^{-1}}$ to form the self-adjoint matrix $\bar{Q}^{K^{-1}}$

$$\bar{Q}^{K^{-1}} = \begin{pmatrix} 0 & [Q^{K^{-1}}]^{\top} \\ Q^{K^{-1}} & 0 \end{pmatrix}, \tag{A316}$$

and observe that we can write $\bar{Q}^{K^{-1}}$ as,

$$\begin{split} \bar{Q}^{K^{-1}} &= \bar{Z} - \bar{Q}_{W,X,\Theta}^{K^{-1}} - \bar{Q}_{\Sigma}^{K^{-1}} \\ &= \begin{pmatrix} 0 & Z^{\top} \\ Z & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{W,X,\Theta}^{K^{-1}}\right]^{\top} \\ Q_{W,X,\Theta}^{K^{-1}} & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{\Sigma}^{K^{-1}}\right]^{\top} \\ Q_{\Sigma}^{K^{-1}} & 0 \end{pmatrix}, \end{split}$$
(A317)

where $Z = I_{m+4n_0+n_1}$, and,

$$Q_{W,X,\Theta}^{K^{-1}} = \begin{pmatrix} 0 & \frac{\sqrt{\eta - \zeta}\Theta^{\top}}{\gamma\sqrt{n_1}} & \frac{\sqrt{\rho}X^{\top}}{\gamma\sqrt{n_0}} & 0 & 0 & 0\\ -\frac{\Theta\sqrt{\eta - \zeta}}{\sqrt{n_1}} & 0 & 0 & 0 & -\frac{\sqrt{\rho}W}{\sqrt{n_1}} & 0\\ 0 & 0 & 0 & 0 & 0 & 0\\ 0 & -\frac{W^{\top}}{\sqrt{n_1}} & 0 & 0 & 0 & 0\\ 0 & 0 & 0 & 0 & 0 & 0\\ -\frac{X}{\sqrt{n_0}} & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$(A318)$$

Note that we have separated the i.i.d. Gaussian matrices W, X, Θ from the constant terms and from the Σ -dependent terms. Denote by $\bar{G}^{K^{-1}} \in M_{12}(\mathbb{C})$ the block matrix

$$\bar{G}^{K^{-1}} = \begin{pmatrix} 0 & [G^{K^{-1}}]^{\top} \\ G^{K^{-1}} & 0 \end{pmatrix} = \mathrm{id}_{12} \otimes \bar{\mathrm{tr}} \left(\bar{Q}^{K^{-1}}\right)^{-1}, \tag{A320}$$

and by $\bar{G}^{K^{-1}}_\Sigma\in M_{12}(\mathbb{C})$ the operator-valued Stieltjes transform of $\bar{Q}^{K^{-1}}_\Sigma$. Using Eq. (A317) and the definition of the operator-valued Stieltjes transform $G_{\bar{Q}^{K^{-1}}_{W,X,\Theta}+\bar{Q}^{K^{-1}}_\Sigma}$, we can write

$$\bar{G}^{K^{-1}} = \mathrm{id}_{12} \otimes \bar{\mathrm{tr}} \left(\bar{Z} - \bar{Q}_{W,X,\Theta}^{K^{-1}} - \bar{Q}_{\Sigma}^{K^{-1}} \right)^{-1} = G_{\bar{Q}_{W,X,\Theta}^{K^{-1}} + \bar{Q}_{\Sigma}^{K^{-1}}}(\bar{Z}) \,. \tag{A321}$$

Thus using the subordinated form of the equations for addition of free variables (45; section 9.2 Thm. 11), and the defining equation for $\bar{G}_{\Sigma}^{K^{-1}}$, the operator-valued theory of free probability shows that in the limit $n_0, n_1, m \to \infty$, the Stieltjes transform $\bar{G}^{K^{-1}}$ satisfies the following 12×12 matrix equation,

$$\bar{G}^{K^{-1}} = \bar{G}_{\Sigma}^{K^{-1}} (\bar{Z} - \bar{R}_{W,X,\Theta}^{K^{-1}} (\bar{G}^{K^{-1}}))
= id \otimes \bar{\operatorname{tr}} \left(\bar{Z} - \bar{R}_{W,X,\Theta}^{K^{-1}} (\bar{G}^{K^{-1}}) - \bar{Q}_{\Sigma}^{K^{-1}} \right)^{-1} ,$$
(A322)

where $\bar{R}^{K^{-1}}_{W,X,\Theta}(\bar{G}^{K^{-1}}) \in M_{12}(\mathbb{C})$ is the operator-valued R-transform of $\bar{Q}^{K^{-1}}_{W,X,\Theta}$. Here the normalized trace $\bar{\operatorname{tr}}$ acts on the constituent blocks, and the identity operator id acts on the space of 12×12 matrices. As described by [2, 3], since $\bar{Q}^{K^{-1}}_{W,X,\Theta}$ is a block matrix whose blocks are i.i.d. Gaussian matrices (and their transposes), an explicit expression for $\bar{R}^{K^{-1}}_{W,X,\Theta}(\bar{G}^{K^{-1}})$ can be obtained through a covariance map, denoted by η [19]. In particular, $\eta:M_d(\mathbb{C})\to M_d(\mathbb{C})$ is defined by,

$$[\eta(D)]_{ij} = \sum_{k,l} \sigma(i,k;l,j)\alpha_k D_{kl}, \qquad (A323)$$

where α_k is dimensionality of the kth block and $\sigma(i,k;l,k)$ denotes the covariance between the entries of the blocks ij block of $\bar{Q}_{W,X,\Theta}^{K^{-1}}$ and entries of the kl block of $\bar{Q}_{W,X,\Theta}^{K^{-1}}$. Here d=12 is the number of blocks. When the constituent blocks are i.i.d. Gaussian matrices and their transposes, as is the case here, then $\bar{R}_{W,X,\Theta}^{K^{-1}} = \eta$ [45], and therefore the entries of $\bar{R}_{W,X,\Theta}^{K^{-1}}$ can be read off

from Eq. (A316). To simplify the presentation, we only report the entries of $\bar{R}_{W,X,\Theta}^{K^{-1}}(G^{K^{-1}})$ that are nonzero, given the specific sparsity pattern of $G^{K^{-1}}$. The latter follows from Eq. (A322) in the manner described in [45, 19]. Practically speaking, the sparsity pattern can be obtained by iterating an Eq. (A322), starting with an ansatz sparsity pattern determined by \bar{Z} , and stopping when the iteration converges to a fixed sparsity pattern. In this case (and all cases that follow in the subsequent sections), the number of necessary iterations is small and can be done explicitly. We omit the details and instead simply report the following results for the nonzero entries:

$$\bar{R}_{W,X,\Theta}^{K^{-1}}(\bar{G}^{K^{-1}}) = \begin{pmatrix} 0 & R_{W,X,\Theta}^{K^{-1}}(G^{K^{-1}})^{\top} \\ R_{W,X,\Theta}^{K^{-1}}(G^{K^{-1}}) & 0 \end{pmatrix},$$
(A324)

where,

$$[R_{W,X,\Theta}^{K^{-1}}(G^{K^{-1}})]_{1,1} = \frac{G_{2,2}^{K^{-1}}(\zeta - \eta) - \sqrt{\rho}G_{6,3}^{K^{-1}}}{\gamma}$$
(A325)

$$[R_{W,X,\Theta}^{K^{-1}}(G^{K^{-1}})]_{2,2} = \frac{\psi G_{1,1}^{K^{-1}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{4,5}^{K^{-1}}$$
(A326)

$$[R_{W,X,\Theta}^{K^{-1}}(G^{K^{-1}})]_{4,5} = \sqrt{\rho}G_{2,2}^{K^{-1}}$$
(A327)

$$[R_{W,X,\Theta}^{K^{-1}}(G^{K^{-1}})]_{6,3} = -\frac{\sqrt{\rho}G_{1,1}^{K^{-1}}}{\gamma\phi}, \tag{A328}$$

and the remaining entries of $R_{W,X,\Theta}^{K^{-1}}(G^{K^{-1}})$ are zero. Owing to the large degree of sparsity, the matrix inverse in Eq. (A322) can be performed explicitly and yields relatively simple expressions that depend on the entries of $G^{K^{-1}}$ and the matrix Σ . For example, the (9,6) entry of the self-consistent equation reads,

$$G_{3,6}^{K^{-1}} = \left[id \otimes \bar{tr} \left(\bar{Z} - \bar{R}_{W,X,\Theta}^{K^{-1}} (\bar{G}^{K^{-1}}) - \bar{Q}_{\Sigma}^{K^{-1}} \right)^{-1} \right]_{9,6}$$
 (A329)

$$= \operatorname{tr}\left[\sqrt{\rho}G_{1,1}^{K^{-1}}\left(-\Sigma\rho G_{1,1}^{K^{-1}}G_{2,2}^{K^{-1}}-\gamma\phi I_{n_0}\right)^{-1}\right]$$
(A330)

$$\stackrel{n_0 \to \infty}{=} \mathbb{E}_{\mu} \left[\frac{\sqrt{\rho} G_{1,1}^{K^{-1}}}{-\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} - \gamma \phi} \right], \tag{A331}$$

where to compute the asymptotic normalized trace we moved to an eigenbasis of Σ and recalled the definition of the LJSD μ . The remaining entries of the Eq. (A322) can be obtained in a similar manner and together yield the following set of coupled equations for the entries of $G^{K^{-1}}$,

$$G_{1,1}^{K^{-1}} = -\frac{\gamma}{-G_{2,2}^{K^{-1}}(-\zeta + \eta + \rho) + \rho G_{2,2}^{K^{-1}} - \sqrt{\rho} G_{6,3}^{K^{-1}} - \gamma}$$
(A332)

$$G_{2,2}^{K^{-1}} = \frac{\gamma \phi}{\psi G_{1,1}^{K^{-1}} (\eta - \zeta) - \gamma \phi \left(\sqrt{\rho \psi} G_{4,5}^{K^{-1}} - 1\right)}$$
(A333)

$$G_{3,6}^{K^{-1}} = \mathbb{E}_{\mu} \left[\frac{\sqrt{\rho} G_{1,1}^{K^{-1}}}{-\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} - \gamma \phi} \right]$$
(A334)

$$G_{4,5}^{K^{-1}} = \mathbb{E}_{\mu} \left[\frac{\lambda \sqrt{\rho} G_{1,1}^{K^{-1}}}{-\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} - \gamma \phi} \right]$$
(A335)

$$G_{5,4}^{K^{-1}} = \mathbb{E}_{\mu} \left[-\frac{\gamma \sqrt{\rho} \phi G_{2,2}^{K^{-1}}}{-\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} - \gamma \phi} \right]$$
(A336)

$$G_{6,3}^{K^{-1}} = \mathbb{E}_{\mu} \left[-\frac{\gamma \lambda \sqrt{\rho} \phi G_{2,2}^{K^{-1}}}{-\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} - \gamma \phi} \right]$$
(A337)

$$G_{3,4}^{K^{-1}} = G_{5,6}^{K^{-1}} = \mathbb{E}_{\mu} \left[\frac{\sqrt{\lambda} \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}}}{-\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} - \gamma \phi} \right]$$
(A338)

$$G_{3,5}^{K^{-1}} = G_{4,6}^{K^{-1}} = \mathbb{E}_{\mu} \left[-\frac{G_{1,1}^{K^{-1}} \sqrt{\lambda \rho}}{\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} + \gamma \phi} \right]$$
(A339)

$$G_{4,3}^{K^{-1}} = G_{6,5}^{K^{-1}} = \mathbb{E}_{\mu} \left[-\frac{\gamma \sqrt{\lambda} \phi}{-\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} - \gamma \phi} \right]$$
 (A340)

$$G_{5,3}^{K^{-1}} = G_{6,4}^{K^{-1}} = \mathbb{E}_{\mu} \left[\frac{\gamma \phi G_{2,2}^{K^{-1}} \sqrt{\lambda \rho}}{\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} + \gamma \phi} \right]$$
(A341)

$$G_{3,3}^{K^{-1}} = G_{4,4}^{K^{-1}} = G_{5,5}^{K^{-1}} = G_{6,6}^{K^{-1}} = \mathbb{E}_{\mu} \left[\frac{\gamma \phi}{\lambda \rho G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}} + \gamma \phi} \right], \tag{A342}$$

where we have used the fact that, asymptotically, the normalized trace becomes equivalent to an expectation over μ . After eliminating $G_{6,3}^{K^{-1}}$ and $G_{4,5}^{K^{-1}}$ from the first two equations, it is straightforward to show that

$$\tau \equiv \bar{\text{tr}}(K^{-1}) = \frac{1}{\gamma} G_{1,1}^{K^{-1}} = \frac{\sqrt{(\psi - \phi)^2 + 4x\psi\phi\gamma/\rho} + \psi - \phi}{2\psi\gamma}$$
(A343)

$$\bar{\tau} \equiv \bar{\text{tr}}(\hat{K}^{-1}) = \frac{1}{\gamma} G_{2,2}^{K^{-1}} = \frac{1}{\gamma} + \frac{\psi}{\phi} (\tau - \frac{1}{\gamma})$$
 (A344)

where $\bar{\tau}$ is the companion transform of τ , and where x satisfies the self-consistent equation,

$$x = \frac{1 - \gamma \tau}{\omega + I_{1,1}} = \frac{1 - \frac{\sqrt{(\psi - \phi)^2 + 4x\psi\phi\gamma/\rho} + \psi - \phi}{2\psi}}{\omega + \mathcal{I}_{1,1}}.$$
 (A345)

Here we used the two-index set of functionals of μ , $\mathcal{I}_{a,b}$ defined in Eq. (14).

Note that the product $\tau \bar{\tau}$ is simply related to x,

$$x = \gamma \rho \tau \bar{\tau} \,, \tag{A346}$$

so that, given x, the equations for the remaining entries of $G^{K^{-1}}$ completely decouple. In particular,

$$G_{3,6}^{K^{-1}} = -\frac{\sqrt{\rho}\tau \mathcal{I}_{0,1}}{\phi} \tag{A347}$$

$$G_{4,5}^{K^{-1}} = -\frac{\sqrt{\rho}\tau \mathcal{I}_{1,1}}{\phi}$$
 (A348)

$$G_{5,4}^{K^{-1}} = \gamma \sqrt{\rho} \bar{\tau} \mathcal{I}_{0,1}$$
 (A349)

$$G_{6,3}^{K^{-1}} = \gamma \sqrt{\rho} \bar{\tau} \mathcal{I}_{1,1}$$
 (A350)

$$G_{3,4}^{K^{-1}} = G_{5,6}^{K^{-1}} = -\frac{x\mathcal{I}_{\frac{1}{2},1}}{\phi}$$
 (A351)

$$G_{3,5}^{K^{-1}} = G_{4,6}^{K^{-1}} = -\frac{\sqrt{\rho}\tau \mathcal{I}_{\frac{1}{2},1}}{\phi}$$
 (A352)

$$G_{4,3}^{K^{-1}} = G_{6,5}^{K^{-1}} = \mathcal{I}_{\frac{1}{2},1}$$
 (A353)

$$G_{5,3}^{K^{-1}} = G_{6,4}^{K^{-1}} = \gamma \sqrt{\rho} \bar{\tau} \mathcal{I}_{\frac{1}{2},1}$$
 (A354)

$$G_{3,3}^{K^{-1}} = G_{4,4}^{K^{-1}} = G_{5,5}^{K^{-1}} = G_{6,6}^{K^{-1}} = \mathcal{I}_{0,1},$$
 (A355)

which will be important intermediate results for the subsequent sections.

A9.6.2 E_{21}

Define the block matrix $Q^{E_{21}}$ as,

Then block matrix inversion (i.e. repeated applications of the Schur complement formula) shows that,

$$G_{1,1}^{E_{21}} = G_{2,2}^{E_{21}} = G_{3,3}^{E_{21}} = 1$$
 (A357)

$$G_{6,6}^{E_{21}} = G_{1,1}^{K^{-1}}$$
 (A358)

$$G_{5,5}^{E_{21}} = G_{2,2}^{K^{-1}}$$
 (A359)

$$G_{4,4}^{E_{21}} = G_{7,7}^{E_{21}} = G_{8,8}^{E_{21}} = G_{9,9}^{E_{21}} = G_{3,3}^{K^{-1}}$$
 (A360)

$$G_{7.8}^{E_{21}} = G_{9.4}^{E_{21}} = G_{3.4}^{K^{-1}} (A361)$$

$$G_{7,8}^{E_{21}} = G_{9,4}^{E_{21}} = G_{3,4}^{K^{-1}}$$

$$G_{4,8}^{E_{21}} = G_{9,7}^{E_{21}} = G_{3,5}^{K^{-1}}$$
(A361)

$$G_{9,8}^{E_{21}} = G_{3,6}^{K^{-1}}$$
 (A363)

$$G_{4,9}^{E_{21}} = G_{8,7}^{E_{21}} = G_{4,3}^{K^{-1}}$$
 (A364)

$$G_{4,7}^{E_{21}} = G_{4,5}^{K^{-1}}$$
 (A365)

$$G_{7,9}^{E_{21}} = G_{8,4}^{E_{21}} = G_{5,3}^{K^{-1}}$$
 (A366)

$$G_{7,4}^{E_{21}} = G_{5,4}^{K^{-1}} (A367)$$

$$G_{8,9}^{E_{21}} = G_{6,3}^{K^{-1}}$$
 (A368)

$$G_{3.1}^{E_{21}} = \bar{\operatorname{tr}}(\Sigma^{1/2})$$
 (A369)

$$G_{7,3}^{E_{21}} = \frac{\gamma\sqrt{\rho}\,\operatorname{tr}\left(\hat{K}^{-1}W\Sigma^*W^{\top}\right)}{n_1\psi} \tag{A370}$$

$$G_{7,3}^{E_{21}} = \frac{\gamma\sqrt{\rho}\,\bar{\mathrm{tr}}\left(\hat{K}^{-1}W\Sigma^*W^{\top}\right)}{n_1\psi}$$

$$G_{7,1}^{E_{21}} = G_{8,3}^{E_{21}} = \frac{\gamma\sqrt{\rho}\,\bar{\mathrm{tr}}\left(\Sigma^{1/2}W^{\top}\hat{K}^{-1}W\Sigma^*\right)}{n_1}$$

$$G_{9,3}^{E_{21}} = -\frac{\sqrt{\rho}\,\bar{\mathrm{tr}}\left(FK^{-1}X^{\top}\Sigma^*W^{\top}\right)}{\sqrt{n_0}n_1\psi}$$

$$(A371)$$

$$(A372)$$

$$\gamma\sqrt{\rho}\,\bar{\mathrm{tr}}\left(\Sigma W^{\top}\hat{K}^{-1}W\Sigma^*\right)$$

$$G_{9,3}^{E_{21}} = -\frac{\sqrt{\rho} \, \bar{\text{tr}} \left(F K^{-1} X^{\top} \Sigma^* W^{\top} \right)}{\sqrt{n_0} n_1 \psi} \tag{A372}$$

$$G_{8,1}^{E_{21}} = \frac{\gamma \sqrt{\rho} \, \text{tr} \left(\Sigma W^{\top} \hat{K}^{-1} W \Sigma^{*} \right)}{n_{1}}$$

$$G_{9,1}^{E_{21}} = -\frac{\sqrt{\rho} \, \text{tr} \left(\Sigma^{1/2} X F^{\top} \hat{K}^{-1} W \Sigma^{*} \right)}{\sqrt{n_{0}} n_{1}}$$
(A374)

$$G_{9,1}^{E_{21}} = -\frac{\sqrt{\rho} \, \bar{\text{tr}} \left(\Sigma^{1/2} X F^{\top} \hat{K}^{-1} W \Sigma^* \right)}{\sqrt{n_0} n_1} \tag{A374}$$

$$G_{6,2}^{E_{21}} = \frac{\gamma \phi \, \bar{\text{tr}} \left(\Sigma^{1/2} X F^{\top} \hat{K}^{-1} W \Sigma^* \right)}{\sqrt{n_0} n_1} \tag{A375}$$

$$G_{6,2}^{E_{21}} = \frac{\gamma \phi \, \bar{\text{tr}} \left(\Sigma^{1/2} X F^{\top} \hat{K}^{-1} W \Sigma^{*} \right)}{\sqrt{n_{0}} n_{1}}$$

$$G_{4,3}^{E_{21}} = \bar{\text{tr}} (\Sigma^{*}) - \frac{\sqrt{\rho} \, \bar{\text{tr}} \left(\Sigma^{1/2} X F^{\top} \hat{K}^{-1} W \Sigma^{*} \right)}{\sqrt{n_{0}} n_{1}}$$
(A376)

$$G_{4,1}^{E_{21}} = \bar{\operatorname{tr}}(\Sigma^{1/2}\Sigma^*) - \frac{\sqrt{\rho}\,\bar{\operatorname{tr}}\left(\Sigma X F^{\top} \hat{K}^{-1} W \Sigma^*\right)}{\sqrt{n_0}n_1}, \tag{A377}$$

where $G_{i,j}^{E_{21}}$ denotes the normalized trace of the (i,j)-block of the inverse of $\left(Q^{E_{21}}\right)^{\top}$. Comparing to Eq. (A280), we see that the error term E_{21} is related to $G_{6.2}^{E_{21}}$ by

$$E_{21} = -\frac{2\sqrt{\rho}}{\gamma\phi}G_{6,2}^{E_{21}}. (A378)$$

To compute the limiting values of these traces, we require the asymptotic block-wise traces of $Q^{E_{21}}$, which may be determined from the operator-valued Stieltjes transform. Proceeding as above, we first augment $Q^{E_{21}}$ to form the self-adjoint matrix $\bar{Q}^{E_{21}}$,

$$\bar{Q}^{E_{21}} = \begin{pmatrix} 0 & [Q^{E_{21}}]^{\top} \\ Q^{E_{21}} & 0 \end{pmatrix}. \tag{A379}$$

and observe that we can write $\bar{Q}^{E_{21}}$ as

$$\begin{split} \bar{Q}^{E_{21}} &= \bar{Z} - \bar{Q}_{W,X,\Theta}^{E_{21}} - \bar{Q}_{\Sigma}^{E_{21}} \\ &= \begin{pmatrix} 0 & Z^{\top} \\ Z & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{W,X,\Theta}^{E_{21}}\right]^{\top} \\ Q_{W,X,\Theta}^{E_{21}} & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{\Sigma}^{E_{21}}\right]^{\top} \\ Q_{\Sigma}^{E_{21}} & 0 \end{pmatrix}, \end{split} \tag{A380}$$

where $Z = I_{2m+6n_0+n_1}$, and,

The operator-valued Stieltjes transforms satisfy.

$$\bar{G}^{E_{21}} = \bar{G}_{\Sigma}^{E_{21}} (\bar{Z} - \bar{R}_{W,X,\Theta}^{E_{21}} (\bar{G}^{E_{21}}))
= id \otimes \bar{tr} \left(\bar{Z} - \bar{R}_{W,X,\Theta}^{E_{21}} (\bar{G}^{E_{21}}) - \bar{Q}_{\Sigma}^{E_{21}} \right)^{-1} ,$$
(A383)

where $\bar{R}^{E_{21}}_{W,X,\Theta}(\bar{G}^{E_{21}})$ is the operator-valued R-transform of $\bar{Q}^{E_{21}}_{W,X,\Theta}$. As discussed above, since $ar{Q}_{W,X,\Theta}^{E_{21}}$ is a block matrix whose blocks are i.i.d. Gaussian matrices (and their transposes), an explicit expression for $\bar{R}^{E_{21}}_{WX,\Theta}(\bar{G}^{E_{21}})$ can be obtained from the covariance map η , which can be read off from Eq. (A379). As above, we use the specific sparsity pattern for $G^{E_{21}}$ that is induced by Eq. (A383), to obtain,

$$\bar{R}_{W,X,\Theta}^{E_{21}}(\bar{G}^{E_{21}}) = \begin{pmatrix} 0 & R_{W,X,\Theta}^{E_{21}}(G^{E_{21}})^{\top} \\ R_{W,X,\Theta}^{E_{21}}(G^{E_{21}}) & 0 \end{pmatrix}, \tag{A384}$$

where,

$$[R_{W,X,\Theta}^{E_{21}}(G^{E_{21}})]_{2,6} = G_{8,1}^{E_{21}}$$
(A385)

$$\left[R_{W,X,\Theta}^{E_{21}}(G^{E_{21}})\right]_{4,7} = \sqrt{\rho}G_{5,5}^{E_{21}} \tag{A386}$$

$$\left[R_{W,X,\Theta}^{E_{21}}(G^{E_{21}})\right]_{5,5} = \frac{\psi G_{6,6}^{E_{21}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{4,7}^{E_{21}}$$
(A387)

$$\left[R_{W,X,\Theta}^{E_{21}}(G^{E_{21}})\right]_{6,6} = \frac{G_{5,5}^{E_{21}}(\zeta - \eta) - \sqrt{\rho}G_{8,9}^{E_{21}}}{\gamma}$$
(A388)

$$\left[R_{W,X,\Theta}^{E_{21}}(G^{E_{21}})\right]_{8,1} = \frac{G_{2,6}^{E_{21}}}{\phi} \tag{A389}$$

$$\left[R_{W,X,\Theta}^{E_{21}}(G^{E_{21}})\right]_{8,9} = -\frac{\sqrt{\rho}G_{6,6}^{E_{21}}}{\gamma\phi},\tag{A390}$$

and the remaining entries of $R_{W,X,\Theta}^{E_{21}}(G^{E_{21}})$ are zero.

Owing to the large degree of sparsity, the matrix inverse in Eq. (A383) can be performed explicitly and yields relatively simple expressions that depend on the entries of $G^{E_{21}}$ and the matrices Σ and Σ^* . For example, the (13,3) entry of the self-consistent equation reads,

$$G_{4,3}^{E_{21}} = \left[id \otimes \bar{tr} \left(\bar{Z} - \bar{R}_{W,X,\Theta}^{E_{21}} (\bar{G}^{E_{21}}) - \bar{Q}_{\Sigma}^{E_{21}} \right)^{-1} \right]_{13,3}$$
 (A391)

$$= \bar{\mathrm{tr}} \left[\Sigma^* \left(I_{n_0} + \frac{\rho}{\gamma \phi} G_{5,5}^{E_{21}} G_{6,6}^{E_{21}} \Sigma \right)^{-1} \right]$$
 (A392)

$$\stackrel{n_0 \to \infty}{=} \mathbb{E}_{\mu} \left[\frac{r}{1 + \frac{\rho}{2\pi^{\frac{1}{2}}} \lambda G_{5.5}^{E_{21}} G_{6.6}^{E_{21}}} \right]$$
 (A393)

$$= \mathbb{E}_{\mu} \left[\frac{r}{1 + \frac{\rho}{\gamma \phi} \lambda G_{1,1}^{K^{-1}} G_{2,2}^{K^{-1}}} \right]$$
 (A394)

$$= \phi \mathbb{E}_{\mu} \left[\frac{r}{\phi + x\lambda} \right] \tag{A395}$$

$$= \mathcal{I}_{1,1}^*$$
 (A396)

To obtain Eq. (A393), we computed the asymptotic normalized trace by moving to an eigenbasis of Σ and recalling the definition of the LJSD μ . We also used Eqs. (A359) and (A358) to obtain Eq. (A394) and Eqs. (A343), (A344), and (A346) to obtain Eq. (A395). The final line follows from the definition of \mathcal{I}^* in Eq. (14). The remaining nonzero entries of Eq. (A383) can be obtained in a similar manner and together yield the following set of coupled equations for the entries of $G^{E_{21}}$,

$$G_{3,1}^{E_{21}} = \frac{\mathcal{I}_{\frac{1}{2},0}}{\phi} \tag{A397}$$

$$G_{4,1}^{E_{21}} = \mathcal{I}_{\frac{3}{2},1}^*$$
 (A398)

$$G_{4,3}^{E_{21}} = \mathcal{I}_{1,1}^*$$
 (A399)

$$G_{6,2}^{E_{21}} = \gamma \tau G_{8,1}^{E_{21}} \tag{A400}$$

$$G_{7,3}^{E_{21}} = \gamma \sqrt{\rho} \bar{\tau} \mathcal{I}_{1,1}^*$$
 (A401)

$$G_{8,1}^{E_{21}} = \gamma \sqrt{\rho} \bar{\tau} \mathcal{I}_{2,1}^*$$
 (A402)

$$G_{9,1}^{E_{21}} = -\frac{x\mathcal{I}_{2,1}^*}{\phi}$$
 (A403)

$$G_{9,3}^{E_{21}} = -\frac{x\mathcal{I}_{\frac{3}{2},1}^*}{\phi} \tag{A404}$$

$$G_{7,1}^{E_{21}} = G_{8,3}^{E_{21}} = \gamma \sqrt{\rho} \bar{\tau} \mathcal{I}_{\frac{3}{2},1}^*$$
 (A405)

$$G_{1,1}^{E_{21}} = G_{2,2}^{E_{21}} = G_{3,3}^{E_{21}} = 1,$$
 (A406)

where we have again used the definition of the LJSD μ , the relations in Eqs. (A357)-(A377), as well as the results in Sec. A9.6.1 to simplify the expressions. Note that in these equations and the above example for the (13,3) entry, we have leveraged the simple manner in which Σ^* enters in Eqs. (A357)-(A377), namely linearly in the numerator, to simplify the dependence on Σ and Σ^* . In particular, by rewriting the arguments of the trace terms in an eigenbasis of Σ , the only dependence on Σ and Σ^* that remains is through the training eigenvalues λ and the overlap coefficients r. As such, the $\bar{\text{tr}}$ in (Eq. (A383)) can be written as an expectation over the LJSD μ in the limit, which leads to significant simplification through the introduction of the two-index set of functions of μ , $\mathcal{I}_{a,b}^*$, defined in Eq. (14).

It is straightforward algebra to solve these equations for the undetermined entries of $G^{E_{21}}$ and thereby obtain the following expression for E_{21} ,

$$E_{21} = -2\frac{x}{\phi} \mathcal{I}_{2,1}^* \,. \tag{A407}$$

A9.6.3 E_{31}

Define the block matrix $Q^{E_{31}} \equiv [Q_1^{E_{31}} \ Q_2^{E_{31}}]$ by,

and,

Then block matrix inversion (i.e. repeated applications of the Schur complement formula) shows that,

$$G_{1,1}^{E_{31}} = G_{10,10}^{E_{31}} = G_{1,1}^{K^{-1}}$$
 (A410)

$$G_{2,2}^{E_{31}} = G_{7,7}^{E_{31}} = G_{2,2}^{K^{-1}}$$
 (A411)

$$G_{3,3}^{E_{31}} = G_{6,6}^{E_{31}} = G_{8,8}^{E_{31}} = G_{12,12}^{E_{31}} = G_{4,4}^{E_{31}} = G_{5,5}^{E_{31}} = G_{9,9}^{E_{31}} = G_{11,11}^{E_{31}} = G_{3,3}^{K^{-1}}$$
(A412)

$$G_{3,4}^{E_{31}} = G_{5,6}^{E_{31}} = G_{8,9}^{E_{31}} = G_{11,12}^{E_{31}} = G_{3,4}^{K^{-1}}$$
(A413)

$$G_{3,4}^{E_{31}} = G_{5,6}^{E_{31}} = G_{8,9}^{E_{31}} = G_{11,12}^{E_{31}} = G_{3,4}^{K^{-1}}$$
 (A413)

$$G_{3,5}^{E_{31}} = G_{4,6}^{E_{31}} = G_{8,11}^{E_{31}} = G_{9,12}^{E_{31}} = G_{3,5}^{K^{-1}}$$
 (A414)

$$G_{3,6}^{E_{31}} = G_{8,12}^{E_{31}} = G_{3,6}^{K^{-1}}$$
 (A415)

$$G_{4,3}^{E_{31}} = G_{6,5}^{E_{31}} = G_{9,8}^{E_{31}} = G_{12,11}^{E_{31}} = G_{4,3}^{K^{-1}}$$
 (A416)

$$G_{3,6}^{E_{31}} = G_{8,12}^{E_{31}} = G_{3,6}^{K^{-1}}$$

$$G_{4,3}^{E_{31}} = G_{6,5}^{E_{31}} = G_{9,8}^{E_{31}} = G_{12,11}^{E_{31}} = G_{4,3}^{K^{-1}}$$

$$G_{4,5}^{E_{31}} = G_{9,11}^{E_{31}} = G_{4,5}^{K^{-1}}$$
(A415)
$$G_{4,5}^{E_{31}} = G_{9,11}^{E_{31}} = G_{4,5}^{K^{-1}}$$
(A417)

$$G_{5,3}^{E_{31}} = G_{6,4}^{E_{31}} = G_{11,8}^{E_{31}} = G_{12,9}^{E_{31}} = G_{5,3}^{K^{-1}}$$
 (A418)

$$G_{5.4}^{E_{31}} = G_{11.9}^{E_{31}} = G_{5.4}^{K^{-1}}$$
 (A419)

$$G_{5,3}^{E_{31}} = G_{6,4}^{E_{31}} = G_{11,8}^{E_{31}} = G_{12,9}^{E_{31}} = G_{5,3}^{K^{-1}}$$

$$G_{5,4}^{E_{31}} = G_{11,9}^{E_{31}} = G_{5,4}^{K^{-1}}$$

$$G_{6,3}^{E_{31}} = G_{12,8}^{E_{31}} = G_{6,3}^{K^{-1}}$$
(A418)
$$G_{6,3}^{E_{31}} = G_{12,8}^{E_{31}} = G_{6,3}^{K^{-1}}$$
(A420)

$$G_{10,1}^{E_{31}} = \frac{\gamma \phi}{\psi \sigma_{\varepsilon}^2} E_{31} ,$$
 (A421)

where $G_{i,j}^{E_{31}}$ denotes the normalized trace of the (i,j)-block of the inverse of $\left(Q^{E_{31}}\right)^{\top}$. For brevity, we have suppressed the expressions for the other non-zero blocks.

To compute the limiting values of these traces, we require the asymptotic block-wise traces of $Q^{E_{31}}$, which may be determined from the operator-valued Stieltjes transform. Proceeding as above, we first augment $Q^{E_{31}}$ to form the self-adjoint matrix $\bar{Q}^{E_{31}}$,

$$\bar{Q}^{E_{31}} = \begin{pmatrix} 0 & [Q^{E_{31}}]^{\top} \\ Q^{E_{31}} & 0 \end{pmatrix}. \tag{A422}$$

and observe that we can write $\bar{Q}^{E_{31}}$ as,

$$\begin{split} \bar{Q}^{E_{31}} &= \bar{Z} - \bar{Q}_{W,X,\Theta}^{E_{31}} - \bar{Q}_{\Sigma}^{E_{31}} \\ &= \begin{pmatrix} 0 & Z^{\top} \\ Z & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{W,X,\Theta}^{E_{31}}\right]^{\top} \\ Q_{W,X,\Theta}^{E_{31}} & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{\Sigma}^{E_{31}}\right]^{\top} \\ Q_{\Sigma}^{E_{31}} & 0 \end{pmatrix}, \end{split}$$
(A423)

where $Z=I_{2m+8n_0+2n_1},$ $Q_{W,X,\Theta}^{E_{31}}\equiv[[Q_{W,X,\Theta}^{E_{31}}]_1\;[Q_{W,X,\Theta}^{E_{31}}]_2]$ and,

The operator-valued Stieltjes transforms satisfy,

$$\bar{G}^{E_{31}} = \bar{G}_{\Sigma}^{E_{31}} (\bar{Z} - \bar{R}_{W,X,\Theta}^{E_{31}}(\bar{G}^{E_{31}}))
= id \otimes \bar{tr} \left(\bar{Z} - \bar{R}_{W,X,\Theta}^{E_{31}}(\bar{G}^{E_{31}}) - \bar{Q}_{\Sigma}^{E_{31}} \right)^{-1},$$
(A427)

where $\bar{R}^{E_{31}}_{W,X,\Theta}(\bar{G}^{E_{31}})$ is the operator-valued R-transform of $\bar{Q}^{E_{31}}_{W,X,\Theta}$. As discussed above, since $\bar{Q}^{E_{31}}_{W,X,\Theta}$ is a block matrix whose blocks are i.i.d. Gaussian matrices (and their transposes), an explicit expression for $\bar{R}^{E_{31}}_{W,X,\Theta}(\bar{G}^{E_{31}})$ can be obtained from the covariance map η , which can be read off from Eq. (A422). As above, we use the specific sparsity pattern for $G^{E_{31}}$ that is induced by Eq. (A427), to obtain,

$$\bar{R}_{W,X,\Theta}^{E_{31}}(\bar{G}^{E_{31}}) = \begin{pmatrix} 0 & R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})^{\top} \\ R_{W,X,\Theta}^{E_{31}}(G^{E_{31}}) & 0 \end{pmatrix}, \tag{A428}$$

where,

$$[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})]_{1,1} = \frac{G_{2,2}^{E_{31}}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{6,3}^{E_{31}}}{\gamma} + \frac{\sqrt{\rho}G_{6,8}^{E_{31}}(\eta - \zeta)}{\gamma} + \frac{G_{2,7}^{E_{31}}(\zeta - \eta)(\zeta - \eta)}{\gamma}$$
(A429)

$$\begin{split} \left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{1,10} &= \frac{G_{7,2}^{E_{31}}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{12,3}^{E_{31}}}{\gamma} + \frac{\sqrt{\rho}G_{12,8}^{E_{31}}(\eta - \zeta)}{\gamma} \\ &\quad + \frac{G_{7,7}^{E_{31}}(\zeta - \eta)\left(\zeta - \eta\right)}{2} \end{split}$$

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{2,2} = \frac{\psi G_{1,1}^{E_{31}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{4,5}^{E_{31}} \tag{A431}$$

(A430)

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{2,7} = \frac{\psi G_{10,1}^{E_{31}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{9,5}^{E_{31}} + \frac{\psi G_{1,1}^{E_{31}}(\zeta - \eta)\left(\zeta - \eta\right)}{\gamma \phi} \tag{A432}$$

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{4.5} = \sqrt{\rho}G_{2,2}^{E_{31}} \tag{A433}$$

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{4.11} = \sqrt{\rho}G_{7,2}^{E_{31}} \tag{A434}$$

$$[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})]_{6,3} = -\frac{\sqrt{\rho}G_{1,1}^{E_{31}}}{\gamma\phi}$$
(A435)

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{6,8} = \frac{\sqrt{\rho}G_{1,1}^{E_{31}}(\eta - \zeta)}{\gamma\phi} - \frac{\sqrt{\rho}G_{10,1}^{E_{31}}}{\gamma\phi}$$
(A436)

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{7,2} = \frac{\psi G_{1,10}^{E_{31}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho \psi G_{4,11}^{E_{31}}}$$
(A437)

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{7,7} = \frac{\psi G_{10,10}^{E_{31}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{9,11}^{E_{31}} + \frac{\psi G_{1,10}^{E_{31}}(\zeta - \eta)\left(\zeta - \eta\right)}{\gamma \phi} \tag{A438}$$

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{9.5} = \sqrt{\rho}G_{2,7}^{E_{31}} \tag{A439}$$

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{9,11} = \sqrt{\rho}G_{7,7}^{E_{31}} \tag{A440}$$

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{10,1} = \frac{G_{2,7}^{E_{31}}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{6,8}^{E_{31}}}{\gamma}$$
(A441)

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{10,10} = \frac{G_{7,7}^{E_{31}}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{12,8}^{E_{31}}}{\gamma} \tag{A442}$$

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{12,3} = -\frac{\sqrt{\rho}G_{1,10}^{E_{31}}}{\gamma\phi} \tag{A443}$$

$$\left[R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})\right]_{12,8} = \frac{\sqrt{\rho}G_{1,10}^{E_{31}}\left(\eta - \zeta\right)}{\gamma\phi} - \frac{\sqrt{\rho}G_{10,10}^{E_{31}}}{\gamma\phi},\tag{A444}$$

and the remaining entries of $R_{W,X,\Theta}^{E_{31}}(G^{E_{31}})$ are zero. Similarly, following the example from $G^{E_{21}}$ above, plugging these expressions into Eq. (A427) and explicitly performing the block-matrix inverse yields the following set of coupled equations,

$$G_{7,2}^{E_{31}} = \gamma^2 \sqrt{\rho} \bar{\tau}^2 \psi G_{9,5}^{E_{31}} + \frac{\gamma \bar{\tau}^2 \psi G_{10,1}^{E_{31}}(\zeta - \eta)}{\phi} + \frac{\gamma^2 \tau \bar{\tau}^2 \psi(\zeta - \eta) (\zeta - \eta)}{\phi}$$
(A445)

$$G_{8,6}^{E_{31}} = \frac{\rho \tau \psi \phi \mathcal{I}_{0,2} \left(\eta - \zeta \right) - x^2 \mathcal{I}_{2,2}^* \rho}{\sqrt{\rho} \psi \phi} - \frac{\sqrt{\rho} G_{10,1}^{E_{31}} \mathcal{I}_{0,2}}{\gamma} + \frac{\rho^{3/2} \tau^2 G_{7,2}^{E_{31}} \mathcal{I}_{1,2}}{\phi}$$
(A446)

$$G_{9,5}^{E_{31}} = \frac{\rho \tau \mathcal{I}_{1,2} \left(\eta - \zeta \right) - \frac{\phi \mathcal{I}_{1,2}^{*} \rho}{\psi}}{\sqrt{\rho}} - \frac{\sqrt{\rho} G_{10,1}^{E_{31}} \mathcal{I}_{1,2}}{\gamma} + \frac{\rho^{3/2} \tau^{2} G_{7,2}^{E_{31}} \mathcal{I}_{2,2}}{\phi}$$
(A447)

$$G_{10,1}^{E_{31}} = \gamma \tau^2 G_{7,2}^{E_{31}}(\zeta - \eta) - \gamma \sqrt{\rho} \tau^2 G_{12,3}^{E_{31}} + \gamma \tau (\gamma \tau - 1) (\zeta - \eta)$$
(A448)

$$G_{11,4}^{E_{31}} = -\frac{\gamma^2 \sqrt{\rho} \bar{\tau}^2 \left(\phi \mathcal{I}_{1,2}^* \rho + \rho \tau \psi \mathcal{I}_{1,2} \left(\zeta - \eta\right)\right)}{\psi} + \sqrt{\rho} \phi G_{7,2}^{E_{31}} \mathcal{I}_{0,2} - \gamma \rho^{3/2} \bar{\tau}^2 G_{10,1}^{E_{31}} \mathcal{I}_{1,2} \quad (A449)$$

$$G_{12,3}^{E_{31}} = -\frac{\gamma^2 \sqrt{\rho} \bar{\tau}^2 \left(\phi \mathcal{I}_{2,2}^* \rho + \rho \tau \psi \mathcal{I}_{2,2} \left(\zeta - \eta\right)\right)}{\psi} + \sqrt{\rho} \phi G_{7,2}^{E_{31}} \mathcal{I}_{1,2} - \gamma \rho^{3/2} \bar{\tau}^2 G_{10,1}^{E_{31}} \mathcal{I}_{2,2} \quad (A450)$$

$$G_{8,3}^{E_{31}} = G_{12,6}^{E_{31}} = \frac{\gamma^2 \rho \tau \bar{\tau}^2 \mathcal{I}_{2,2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{31}} \mathcal{I}_{1,2} - \rho \bar{\tau} G_{10,1}^{E_{31}} \mathcal{I}_{1,2} + x \mathcal{I}_{1,2} \left(\eta - \zeta \right)$$
(A451)

$$G_{8,4}^{E_{31}} = G_{11,6}^{E_{31}} = \frac{\gamma^2 \rho \tau \bar{\tau}^2 \mathcal{I}_{\frac{3}{2},2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{31}} \mathcal{I}_{\frac{1}{2},2} - \rho \bar{\tau} G_{10,1}^{E_{31}} \mathcal{I}_{\frac{1}{2},2} + x \mathcal{I}_{\frac{1}{2},2} \left(\eta - \zeta \right) \tag{A452}$$

$$G_{8,5}^{E_{31}} = G_{9,6}^{E_{31}} = \frac{\frac{x}{\psi} \mathcal{I}_{\frac{3}{2},2}^* \rho + \rho \tau \mathcal{I}_{\frac{1}{2},2} \left(\eta - \zeta \right)}{\sqrt{\rho}} - \frac{\sqrt{\rho} G_{10,1}^{E_{31}} \mathcal{I}_{\frac{1}{2},2}}{\gamma} + \frac{\rho^{3/2} \tau^2 G_{7,2}^{E_{31}} \mathcal{I}_{\frac{3}{2},2}}{\phi}$$
(A453)

$$G_{9,3}^{E_{31}} = G_{12,5}^{E_{31}} = -\frac{\gamma \bar{\tau} \phi \mathcal{I}_{\frac{3}{2},2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{31}} \mathcal{I}_{\frac{3}{2},2} - \rho \bar{\tau} G_{10,1}^{E_{31}} \mathcal{I}_{\frac{3}{2},2} + x \mathcal{I}_{\frac{3}{2},2} \left(\eta - \zeta \right) \tag{A454}$$

$$G_{9,4}^{E_{31}} = G_{11,5}^{E_{31}} = -\frac{\gamma \bar{\tau} \phi \mathcal{I}_{1,2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{31}} \mathcal{I}_{1,2} - \rho \bar{\tau} G_{10,1}^{E_{31}} \mathcal{I}_{1,2} + x \mathcal{I}_{1,2} \left(\eta - \zeta \right)$$
(A455)

$$\begin{split} G_{11,3}^{E_{31}} &= G_{12,4}^{E_{31}} = -\frac{\gamma^2 \sqrt{\rho} \bar{\tau}^2 \left(\phi \mathcal{I}_{\frac{3}{2},2}^* \rho + \rho \tau \psi \mathcal{I}_{\frac{3}{2},2} \left(\zeta - \eta\right)\right)}{\psi} + \sqrt{\rho} \phi G_{7,2}^{E_{31}} \mathcal{I}_{\frac{1}{2},2} \\ &- \gamma \rho^{3/2} \bar{\tau}^2 G_{10,1}^{E_{31}} \mathcal{I}_{\frac{3}{2},2} \,, \end{split} \tag{A456}$$

Here we have used the definition of the LJSD μ , the relations in Eqs. (A410)-(A421), the definition of $\mathcal{I}_{a,b}^*$, and the results in Sec. A9.6.1 to simplify the expressions. It is straightforward algebra to solve these equations for the undetermined entries of $G^{E_{31}}$ and thereby obtain the following expression for E_{31} ,

$$E_{31} = \sigma_{\varepsilon}^2 \frac{(\eta - \zeta)A_{31} + \rho B_{31}}{D_{31}}, \tag{A457}$$

where,

$$A_{31} = \rho^{2} \tau \psi x^{2} \mathcal{I}_{2,2} \left(-\gamma \tau \psi + \psi + \phi \right) + 2\rho \tau \psi^{2} x^{2} \phi (\eta - \zeta) \mathcal{I}_{1,2} + \rho^{2} \tau \psi^{2} x^{2} \phi^{2} \mathcal{I}_{1,2}^{2} + \tau \psi \left(x^{2} \psi (\zeta - \eta)^{2} - \rho^{2} (\phi - \gamma \tau \phi) \right) - \rho^{2} \tau \psi^{2} x^{4} \mathcal{I}_{2,2}^{2}$$
(A458)

$$B_{31} = \rho \psi x^4 \phi \mathcal{I}_{2,2}^* \mathcal{I}_{2,2} - \rho \psi x^2 \phi^3 \mathcal{I}_{1,2}^* \mathcal{I}_{1,2} + \psi x^2 \phi^2 \mathcal{I}_{1,2}^* (\zeta - \eta) - \rho x^2 \phi^2 \mathcal{I}_{2,2}^*$$

$$D_{31} = -\rho^2 \psi x^4 \phi \mathcal{I}_{2,2}^2 + 2\rho \psi x^2 \phi^2 \mathcal{I}_{1,2} (\eta - \zeta) + \rho^2 \psi x^2 \phi^3 \mathcal{I}_{1,2}^2 + \rho^2 x^2 \phi \mathcal{I}_{2,2} (\psi + \phi)$$

$$+\phi \left(x^2 \psi (\zeta - \eta)^2 - \rho^2 \phi \right) .$$
(A459)

Further simplifications are possible using the raising and lowering identities in Eq. (A5), as well as the results in Sec. A9.6.1, to obtain,

$$E_{31} = \sigma_{\varepsilon}^{2} \frac{\tau \bar{\tau} x \left(\rho \frac{\psi}{\phi} (\phi \mathcal{I}_{1,2} + \omega)(\omega + \mathcal{I}_{1,1}^{*}) + \frac{x}{\tau} \mathcal{I}_{2,2}^{*}\right)}{\tau + \bar{\tau} x (\omega + \phi \mathcal{I}_{1,2}) - \tau x^{2} \frac{\psi}{\phi} \mathcal{I}_{2,2}}$$
(A461)

$$= -\sigma_{\varepsilon}^{2} \frac{\partial x}{\partial \gamma} \left(\rho \frac{\psi}{\phi} (\phi \mathcal{I}_{1,2} + \omega) (\omega + \mathcal{I}_{1,1}^{*}) + \frac{x}{\tau} \mathcal{I}_{2,2}^{*} \right), \tag{A462}$$

where we have used,

$$\frac{\partial x}{\partial \gamma} = -\frac{x}{\gamma + \rho \gamma (\frac{\psi}{\phi} \tau + \bar{\tau})(\omega + \phi \mathcal{I}_{1,2})},$$
(A463)

which follows from Eq. (A345) via implicit differentiation.

A9.6.4 E_{32}

Define the block matrix $Q^{E_{32}} \equiv [Q_1^{E_{32}} \ Q_2^{E_{32}}]$ by,

and.

Then block matrix inversion (i.e. repeated applications of the Schur complement formula) shows that,

$$G_{8.8}^{E_{32}} = G_{14.14}^{E_{32}} = G_{15.15}^{E_{32}} = 1$$
 (A466)

$$G_{1,1}^{E_{32}} = G_{9,9}^{E_{32}} = G_{1,1}^{K^{-1}}$$
 (A467)

$$G_{2,2}^{E_{32}} = G_{7,7}^{E_{32}} = G_{2,2}^{K^{-1}}$$
 (A468)

$$G_{3,3}^{E_{32}} \quad = \quad G_{6,6}^{E_{32}} = G_{11,11}^{E_{32}} = G_{12,12}^{E_{32}} = G_{4,4}^{E_{32}} = G_{5,5}^{E_{32}} = G_{10,10}^{E_{32}} = G_{13,13}^{E_{32}} = G_{3,3}^{K^{-1}} (\text{A469})$$

$$G_{3,4}^{E_{32}} = G_{5,6}^{E_{32}} = G_{10,11}^{E_{32}} = G_{12,8}^{E_{32}} = G_{12,13}^{E_{32}} = G_{3,4}^{K^{-1}}$$
 (A470)

$$G_{3,5}^{E_{32}} = G_{4,6}^{E_{32}} = G_{12,10}^{E_{32}} = G_{13,11}^{E_{32}} = G_{3,5}^{K^{-1}}$$
(A471)

$$G_{3,6}^{E_{32}} = G_{12,11}^{E_{32}} = G_{3,6}^{K^{-1}}$$
 (A472)

$$G_{4,3}^{E_{32}} = G_{6,5}^{E_{32}} = G_{11,10}^{E_{32}} = G_{13,12}^{E_{32}} = G_{4,3}^{K^{-1}}$$
 (A473)

$$G_{4,5}^{E_{32}} = G_{13,10}^{E_{32}} = G_{4,5}^{K^{-1}}$$
 (A474)

$$G_{5,3}^{E_{32}} = G_{6,4}^{E_{32}} = G_{10,12}^{E_{32}} = G_{11,8}^{E_{32}} = G_{5,3}^{E_{32}} = G_{5,3}^{K^{-1}}$$
 (A475)

$$G_{4,5}^{E_{3,5}} = G_{13,10} = G_{4,5}$$

$$G_{5,3}^{E_{32}} = G_{6,4}^{E_{32}} = G_{10,12}^{E_{32}} = G_{11,8}^{E_{32}} = G_{5,3}^{E_{32}}$$

$$G_{5,4}^{E_{32}} = G_{10,8}^{E_{32}} = G_{10,13}^{E_{32}} = G_{5,4}^{K^{-1}}$$

$$G_{6,3}^{E_{32}} = G_{11,12}^{E_{32}} = G_{6,3}^{K^{-1}}$$
(A475)
$$G_{6,3}^{E_{32}} = G_{11,12}^{E_{32}} = G_{6,3}^{K^{-1}}$$
(A477)

$$G_{6,3}^{E_{32}} = G_{11,12}^{E_{32}} = G_{6,3}^{K^{-1}}$$
 (A477)

$$G_{15,1}^{E_{32}} = \frac{\phi}{\psi} E_{32} \,, \tag{A478}$$

where $G_{i,j}^{E_{32}}$ denotes the normalized trace of the (i,j)-block of the inverse of $\left(Q^{E_{32}}\right)^{\top}$. For brevity, we have suppressed the expressions for the other non-zero blocks.

To compute the limiting values of these traces, we require the asymptotic block-wise traces of $Q^{E_{32}}$, which may be determined from the operator-valued Stieltjes transform. To proceed, we first augment $Q^{E_{32}}$ to form the self-adjoint matrix $\bar{Q}^{E_{32}}$,

$$\bar{Q}^{E_{32}} = \begin{pmatrix} 0 & [Q^{E_{32}}]^{\top} \\ Q^{E_{32}} & 0 \end{pmatrix}. \tag{A479}$$

and observe that we can write $\bar{Q}^{E_{32}}$ as,

$$\bar{Q}^{E_{32}} = \bar{Z} - \bar{Q}_{W,X,\Theta}^{E_{32}} - \bar{Q}_{\Sigma}^{E_{32}} \\
= \begin{pmatrix} 0 & Z^{\top} \\ Z & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{W,X,\Theta}^{E_{32}}\right]^{\top} \\ Q_{W,X,\Theta}^{E_{32}} & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{\Sigma}^{E_{32}}\right]^{\top} \\ Q_{\Sigma}^{E_{32}} & 0 \end{pmatrix},$$
(A480)

where $Z = I_{3m+10n_0+2n_1}$, $Q_{W,X,\Theta}^{E_{32}} \equiv [[Q_{W,X,\Theta}^{E_{32}}]_1 \ [Q_{W,X,\Theta}^{E_{32}}]_2]$ and,

The operator-valued Stieltjes transforms satisfy.

$$\bar{G}^{E_{32}} = \bar{G}_{\Sigma}^{E_{32}} (\bar{Z} - \bar{R}_{W,X,\Theta}^{E_{32}} (\bar{G}^{E_{32}}))
= id \otimes \bar{tr} \left(\bar{Z} - \bar{R}_{W,X,\Theta}^{E_{32}} (\bar{G}^{E_{32}}) - \bar{Q}_{\Sigma}^{E_{32}} \right)^{-1} ,$$
(A484)

where $\bar{R}^{E_{32}}_{W,X,\Theta}(\bar{G}^{E_{32}})$ is the operator-valued R-transform of $\bar{Q}^{E_{32}}_{W,X,\Theta}$. As discussed above, since $\bar{Q}^{E_{32}}_{W,X,\Theta}$ is a block matrix whose blocks are i.i.d. Gaussian matrices (and their transposes), an explicit expression for $\bar{R}^{E_{32}}_{W,X,\Theta}(\bar{G}^{E_{32}})$ can be obtained from the covariance map η , which can be read off from Eq. (A479). As above, we use the specific sparsity pattern for $G^{E_{32}}$ that is induced by Eq. (A484), to obtain,

$$\bar{R}_{W,X,\Theta}^{E_{32}}(\bar{G}^{E_{32}}) = \begin{pmatrix} 0 & R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})^{\top} \\ R_{W,X,\Theta}^{E_{32}}(G^{E_{32}}) & 0 \end{pmatrix},$$
(A485)

where,

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{1,1} = \frac{G_{2,2}^{E_{32}}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{6,3}^{E_{32}}}{\gamma} + \frac{G_{2,7}^{E_{32}}(\zeta - \eta)(\zeta - \eta)}{\gamma}$$
(A486)

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{1,9} = \frac{G_{7,2}^{E_{32}}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{11,3}^{E_{32}}}{\gamma} + \frac{G_{7,7}^{E_{32}}(\zeta - \eta)(\zeta - \eta)}{\gamma}$$
(A487)

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{1,15} = -\frac{\sqrt{\rho}G_{14,3}^{E_{32}}}{\gamma} \tag{A488}$$

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{2,2} = \frac{\psi G_{1,1}^{E_{32}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{4,5}^{E_{32}}$$
(A489)

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{2,7} = \frac{\psi G_{9,1}^{E_{32}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{8,5}^{E_{32}} + \sqrt{\rho} \psi G_{13,5}^{E_{32}}$$

$$+\frac{\psi G_{1,1}^{E_{32}}(\zeta - \eta)(\zeta - \eta)}{\gamma \phi}$$
 (A490)

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{4,5} = \sqrt{\rho}G_{2,2}^{E_{32}} \tag{A491} \label{eq:A491}$$

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{4,10} = \sqrt{\rho}G_{7,2}^{E_{32}} \tag{A492}$$

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{6,3} = -\frac{\sqrt{\rho}G_{1,1}^{E_{32}}}{\gamma\phi}$$
(A493)

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{6,12} = -\frac{\sqrt{\rho}G_{9,1}^{E_{32}}}{\gamma\phi} \tag{A494}$$

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{7,2} = \frac{\psi G_{1,9}^{E_{32}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{4,10}^{E_{32}} \tag{A495}$$

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{7,7} = \frac{\psi G_{9,9}^{E_{32}}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{8,10}^{E_{32}} + \sqrt{\rho} \psi G_{13,10}^{E_{32}}$$

$$+\frac{\psi G_{1,9}^{E_{32}}(\zeta - \eta)(\zeta - \eta)}{\gamma \phi}$$
 (A496)

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{8,5} = \sqrt{\rho}G_{2,7}^{E_{32}}$$
(A497)

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{8.10} = \sqrt{\rho}G_{7,7}^{E_{32}} \tag{A498}$$

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{9,1} = \frac{G_{2,7}^{E_{32}}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{6,12}^{E_{32}}}{\gamma}$$
(A499)

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{9,9} = \frac{G_{7,7}^{E_{32}}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{11,12}^{E_{32}}}{\gamma}$$
(A500)

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{9,15} = -\frac{\sqrt{\rho}G_{14,12}^{E_{32}}}{\gamma} \tag{A501}$$

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{11,3} = -\frac{\sqrt{\rho}G_{1,9}^{E_{32}}}{\gamma\phi}$$
(A502)

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{11,12} = -\frac{\sqrt{\rho}G_{9,9}^{E_{32}}}{\gamma\phi}$$
(A503)

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{13.5} = \sqrt{\rho}G_{2,7}^{E_{32}}$$
(A504)

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{13,10} = \sqrt{\rho}G_{7,7}^{E_{32}} \tag{A505}$$

$$[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})]_{14,3} = -\frac{\sqrt{\rho}G_{1,15}^{E_{32}}}{\gamma\phi}$$
(A506)

$$\left[R_{W,X,\Theta}^{E_{32}}(G^{E_{32}})\right]_{14,12} = -\frac{\sqrt{\rho}G_{9,15}^{E_{32}}}{\gamma\phi},\tag{A507}$$

and the remaining entries of $R^{E_{32}}_{W,X,\Theta}(G^{E_{32}})$ are zero. Similarly, following the example from $G^{E_{21}}$ above, plugging these expressions into Eq. (A484) and explicitly performing the block-matrix inverse yields the following set of coupled equations,

$$G_{7,2}^{E_{32}} = \gamma^2 \sqrt{\rho} \bar{\tau}^2 \psi G_{8,5}^{E_{32}} + \gamma^2 \sqrt{\rho} \bar{\tau}^2 \psi G_{13,5}^{E_{32}} + \frac{\gamma \bar{\tau}^2 \psi G_{9,1}^{E_{32}}(\zeta - \eta)}{\phi} + \frac{\gamma^2 \tau \bar{\tau}^2 \psi (\zeta - \eta) (\zeta - \eta)}{\phi}$$
(A508)

$$G_{8,3}^{E_{32}} = \mathcal{I}_{\frac{1}{2},1} \left(\zeta - \eta \right) - \frac{\gamma \bar{\tau} \mathcal{I}_{\frac{3}{2},1}^* \rho}{\psi} \tag{A509}$$

$$G_{8,4}^{E_{32}} = \gamma(-\bar{\tau}) \left(\frac{\mathcal{I}_{1,1}^* \rho}{\psi} + \frac{\rho \tau \mathcal{I}_{1,1} (\zeta - \eta)}{\phi} \right)$$
 (A510)

$$G_{8,5}^{E_{32}} = \frac{\rho \tau \psi \mathcal{I}_{1,1} (\eta - \zeta) - \phi \mathcal{I}_{1,1}^* \rho}{\sqrt{\rho} \psi \phi}$$
(A511)

$$G_{8,6}^{E_{32}} = \frac{\sqrt{\rho}\tau \left(\gamma \bar{\tau} \mathcal{I}_{\frac{3}{2},1}^* \rho + \psi \mathcal{I}_{\frac{1}{2},1} (\eta - \zeta)\right)}{\psi \phi}$$
(A512)

$$G_{9,1}^{E_{32}} = \gamma \tau^2 G_{7,2}^{E_{32}}(\zeta - \eta) - \gamma \sqrt{\rho} \tau^2 G_{11,3}^{E_{32}} + \gamma^2 \tau^2 \bar{\tau}(\zeta - \eta) (\zeta - \eta)$$
(A513)

$$G_{10,3}^{E_{32}} = -\frac{\gamma\sqrt{\rho}\bar{\tau}\phi\left(\gamma\bar{\tau}\mathcal{I}_{\frac{3}{2},2}^{*}\rho + \psi\mathcal{I}_{\frac{1}{2},2}\left(\eta - \zeta\right)\right)}{\psi} + \sqrt{\rho}\phi G_{7,2}^{E_{32}}\mathcal{I}_{\frac{1}{2},2} - \gamma\rho^{3/2}\bar{\tau}^{2}G_{9,1}^{E_{32}}\mathcal{I}_{\frac{3}{2},2}$$
(A514)

$$G_{10,4}^{E_{32}} = -\frac{\gamma^2 \sqrt{\rho} \bar{\tau}^2 \left(\phi \mathcal{I}_{1,2}^* \rho + \rho \tau \psi \mathcal{I}_{1,2} \left(\zeta - \eta\right)\right)}{\psi} + \sqrt{\rho} \phi G_{7,2}^{E_{32}} \mathcal{I}_{0,2} - \gamma \rho^{3/2} \bar{\tau}^2 G_{9,1}^{E_{32}} \mathcal{I}_{1,2}$$
(A515)

$$G_{10,5}^{E_{32}} = -\frac{\gamma \bar{\tau} \phi \mathcal{I}_{1,2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{32}} \mathcal{I}_{1,2} - \rho \bar{\tau} G_{9,1}^{E_{32}} \mathcal{I}_{1,2} + x \mathcal{I}_{1,2} \left(\eta - \zeta \right)$$
(A516)

$$G_{10,6}^{E_{32}} = \frac{\gamma^2 \rho \tau \bar{\tau}^2 \mathcal{I}_{\frac{3}{2},2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{32}} \mathcal{I}_{\frac{1}{2},2} - \rho \bar{\tau} G_{9,1}^{E_{32}} \mathcal{I}_{\frac{1}{2},2} + x \mathcal{I}_{\frac{1}{2},2} \left(\eta - \zeta \right) \tag{A517}$$

$$G_{11,3}^{E_{32}} = -\frac{\gamma\sqrt{\rho}\bar{\tau}\phi\left(\gamma\bar{\tau}\mathcal{I}_{2,2}^{*}\rho + \psi\mathcal{I}_{1,2}\left(\eta - \zeta\right)\right)}{\psi} + \sqrt{\rho}\phi G_{7,2}^{E_{32}}\mathcal{I}_{1,2} - \gamma\rho^{3/2}\bar{\tau}^{2}G_{9,1}^{E_{32}}\mathcal{I}_{2,2} \quad (A518)$$

$$\begin{split} G_{11,4}^{E_{32}} &= -\frac{\gamma^2 \sqrt{\rho} \bar{\tau}^2 \left(\phi \mathcal{I}_{\frac{3}{2},2}^* \rho + \rho \tau \psi \mathcal{I}_{\frac{3}{2},2} \left(\zeta - \eta\right)\right)}{\psi} + \sqrt{\rho} \phi G_{7,2}^{E_{32}} \mathcal{I}_{\frac{1}{2},2} \\ &- \gamma \rho^{3/2} \bar{\tau}^2 G_{9,1}^{E_{32}} \mathcal{I}_{\frac{3}{2},2} \end{split} \tag{A519}$$

$$G_{11,5}^{E_{32}} = -\frac{\gamma \bar{\tau} \phi \mathcal{I}_{\frac{3}{2},2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{32}} \mathcal{I}_{\frac{3}{2},2} - \rho \bar{\tau} G_{9,1}^{E_{32}} \mathcal{I}_{\frac{3}{2},2} + x \mathcal{I}_{\frac{3}{2},2} \left(\eta - \zeta\right) \tag{A520}$$

$$G_{12,4}^{E_{32}} = \frac{\gamma^2 \rho \tau \bar{\tau}^2 \mathcal{I}_{\frac{3}{2},2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{32}} \mathcal{I}_{\frac{1}{2},2} - \rho \bar{\tau} G_{9,1}^{E_{32}} \mathcal{I}_{\frac{1}{2},2} + \frac{x^2 \mathcal{I}_{\frac{3}{2},2} \left(\zeta - \eta\right)}{\phi} \tag{A521}$$

$$G_{12,5}^{E_{32}} = \frac{\frac{x\mathcal{I}_{\frac{3}{2},2}^*\rho}{\psi} + \frac{\gamma\rho^2\tau^2\bar{\tau}\mathcal{I}_{\frac{3}{2},2}(\zeta-\eta)}{\phi}}{\sqrt{\rho}} - \frac{\sqrt{\rho}G_{9,1}^{E_{32}}\mathcal{I}_{\frac{1}{2},2}}{\gamma} + \frac{\rho^{3/2}\tau^2G_{7,2}^{E_{32}}\mathcal{I}_{\frac{3}{2},2}}{\phi}$$
(A522)

$$G_{12,6}^{E_{32}} = \frac{\gamma \rho^2 \tau^2 \bar{\tau} \psi \mathcal{I}_{1,2} \left(\zeta - \eta\right) - x^2 \mathcal{I}_{2,2}^* \rho}{\sqrt{\rho} \psi \phi} - \frac{\sqrt{\rho} G_{9,1}^{E_{32}} \mathcal{I}_{0,2}}{\gamma} + \frac{\rho^{3/2} \tau^2 G_{7,2}^{E_{32}} \mathcal{I}_{1,2}}{\phi}$$
(A523)

$$G_{13,3}^{E_{32}} = \frac{\gamma^2 \rho \tau \bar{\tau}^2 \mathcal{I}_{\frac{5}{2},2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{32}} \mathcal{I}_{\frac{3}{2},2} - \rho \bar{\tau} G_{9,1}^{E_{32}} \mathcal{I}_{\frac{3}{2},2} + x \mathcal{I}_{\frac{3}{2},2} \left(\eta - \zeta \right) \tag{A524}$$

$$G_{13,4}^{E_{32}} = \frac{\gamma^2 \rho \tau \bar{\tau}^2 \mathcal{I}_{2,2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{32}} \mathcal{I}_{1,2} - \rho \bar{\tau} G_{9,1}^{E_{32}} \mathcal{I}_{1,2} + \frac{x^2 \mathcal{I}_{2,2} \left(\zeta - \eta\right)}{\phi}$$
(A525)

$$G_{13,5}^{E_{32}} = \frac{\frac{x\mathcal{I}_{2,2}^*\rho}{\psi} + \frac{\gamma\rho^2\tau^2\bar{\tau}\mathcal{I}_{2,2}(\zeta - \eta)}{\phi}}{\sqrt{\rho}} - \frac{\sqrt{\rho}G_{9,1}^{E_{32}}\mathcal{I}_{1,2}}{\gamma} + \frac{\rho^{3/2}\tau^2G_{7,2}^{E_{32}}\mathcal{I}_{2,2}}{\phi}$$
(A526)

$$G_{13,6}^{E_{32}} = \frac{\gamma \rho^2 \tau^2 \bar{\tau} \psi \mathcal{I}_{\frac{3}{2},2} \left(\zeta - \eta \right) - x^2 \mathcal{I}_{\frac{5}{2},2}^* \rho}{\sqrt{\rho} \psi \phi} - \frac{\sqrt{\rho} G_{9,1}^{E_{32}} \mathcal{I}_{\frac{1}{2},2}}{\gamma} + \frac{\rho^{3/2} \tau^2 G_{7,2}^{E_{32}} \mathcal{I}_{\frac{3}{2},2}}{\phi} \tag{A527}$$

$$G_{13,8}^{E_{32}} = -\frac{x\mathcal{I}_{1,1}}{\phi} \tag{A528}$$

$$G_{14,3}^{E_{32}} = \frac{x\psi \mathcal{I}_{2,2} \left(\zeta - \eta\right) - \gamma^2 \rho \tau \bar{\tau}^2 \mathcal{I}_{3,2}^* \rho}{\sqrt{\rho} \psi} + \sqrt{\rho} \tau G_{7,2}^{E_{32}} \mathcal{I}_{2,2} + \sqrt{\rho} \bar{\tau} G_{9,1}^{E_{32}} \mathcal{I}_{2,2}$$
(A529)

$$G_{14,4}^{E_{32}} = \frac{x^2 \psi \mathcal{I}_{\frac{5}{2},2} (\eta - \zeta) - \gamma^2 \rho \tau \bar{\tau}^2 \phi \mathcal{I}_{\frac{5}{2},2}^* \rho}{\sqrt{\rho} \psi \phi} + \sqrt{\rho} \tau G_{7,2}^{E_{32}} \mathcal{I}_{\frac{3}{2},2} + \sqrt{\rho} \bar{\tau} G_{9,1}^{E_{32}} \mathcal{I}_{\frac{3}{2},2}$$
(A530)

$$G_{14,5}^{E_{32}} = -\frac{x\mathcal{I}_{\frac{5}{2},2}^{*}\rho}{\rho\psi} + \frac{G_{9,1}^{E_{32}}\mathcal{I}_{\frac{3}{2},2}}{\gamma} - \frac{\rho\tau^{2}G_{7,2}^{E_{32}}\mathcal{I}_{\frac{5}{2},2}}{\phi} + \frac{\gamma\rho\tau^{2}\bar{\tau}\mathcal{I}_{\frac{5}{2},2}\left(\eta - \zeta\right)}{\phi} \tag{A531}$$

$$G_{14,6}^{E_{32}} = \frac{\frac{x^2 \mathcal{I}_{3,2}^* \rho}{\psi} + \gamma \rho^2 \tau^2 \bar{\tau} \mathcal{I}_{2,2} (\eta - \zeta)}{\rho \phi} + \frac{G_{9,1}^{E_{32}} \mathcal{I}_{1,2}}{\gamma} - \frac{\rho \tau^2 G_{7,2}^{E_{32}} \mathcal{I}_{2,2}}{\phi}$$
(A532)

$$G_{14,8}^{E_{32}} = \frac{x\mathcal{I}_{\frac{3}{2},1}}{\sqrt{\rho}\phi} \tag{A533}$$

$$G_{14,10}^{E_{32}} = \frac{\tau \mathcal{I}_{\frac{3}{2},1}}{\phi} \tag{A534}$$

$$G_{14,11}^{E_{32}} = \frac{\tau \mathcal{I}_{1,1}}{\phi} \tag{A535}$$

$$G_{14,12}^{E_{32}} = -\frac{\mathcal{I}_{1,1}}{\sqrt{\rho}} \tag{A536}$$

$$G_{14,13}^{E_{32}} = -\frac{\mathcal{I}_{\frac{1}{2},1}}{\sqrt{\rho}} \tag{A537}$$

$$G_{15,1}^{E_{32}} = G_{14,12}^{E_{32}} \left(\sqrt{\rho} \tau^2 G_{7,2}^{E_{32}} (\eta - \zeta) + \rho \tau^2 G_{11,3}^{E_{32}} + \gamma \sqrt{\rho} \tau^2 (-\bar{\tau}) (\zeta - \eta) (\zeta - \eta) \right)$$

$$-\sqrt{\rho}\tau G_{14,3}^{E_{32}} \tag{A538}$$

$$G_{15,9}^{E_{32}} = -\sqrt{\rho}\tau G_{14,12}^{E_{32}} \tag{A539}$$

$$G_{11,6}^{E_{32}} = G_{12,3}^{E_{32}} = \frac{\gamma^2 \rho \tau \bar{\tau}^2 \mathcal{I}_{2,2}^* \rho}{\psi} - \rho \tau G_{7,2}^{E_{32}} \mathcal{I}_{1,2} - \rho \bar{\tau} G_{9,1}^{E_{32}} \mathcal{I}_{1,2} + x \mathcal{I}_{1,2} \left(\eta - \zeta \right) \tag{A540}$$

$$G_{8.8}^{E_{32}} = G_{14.14}^{E_{32}} = G_{15.15}^{E_{32}} = 1, (A541)$$

Here we have used the definition of the LJSD μ , the relations in Eqs. (A466)-(A478), the definition of $\mathcal{I}_{a,b}^*$, and the results in Sec. A9.6.1 to simplify the expressions. It is straightforward algebra to solve these equations for the undetermined entries of $G^{E_{32}}$ and thereby obtain the following expression for E_{32} ,

$$E_{32} = \frac{(\eta - \zeta)A_{32} + \rho B_{32}}{D_{32}},$$
(A542)

where,

$$A_{32} = -\rho^{3}\tau\psi^{2}x^{4}\mathcal{I}_{1,1}\mathcal{I}_{2,2}^{2} + \rho^{2}\tau\psi x^{3}\mathcal{I}_{2,2}^{2}(\rho\phi + x\psi(\zeta - \eta)) - \rho^{3}\tau\psi^{2}x^{3}\phi\mathcal{I}_{1,1}\mathcal{I}_{1,2}\mathcal{I}_{2,2}$$

$$+ \rho^{2}\tau\psi^{2}x^{2}\mathcal{I}_{1,1}^{2}(\eta - \zeta) + \rho^{2}\tau\psi^{2}x^{2}\mathcal{I}_{1,1}\mathcal{I}_{2,2}(\rho + x(\zeta - \eta))$$

$$+ \rho^{2}\tau\psi x^{2}\phi\mathcal{I}_{1,2}\mathcal{I}_{2,2}(\rho\phi + x\psi(\zeta - \eta)) + \rho^{3}\tau\psi^{2}x^{2}\phi\mathcal{I}_{1,1}^{2}\mathcal{I}_{1,2}$$

$$- \rho^{2}\tau\psi x\phi\mathcal{I}_{1,1}\mathcal{I}_{1,2}(\rho\phi + x\psi(\zeta - \eta)) + \rho\tau\psi x\mathcal{I}_{1,1}(\zeta - \eta)(\rho\phi + x\psi(\zeta - \eta))$$

$$- \rho\tau\psi x\mathcal{I}_{2,2}(\rho + x(\zeta - \eta))(\rho\phi + x\psi(\zeta - \eta)) \qquad (A543)$$

$$B_{32} = -\rho^{2}\psi x^{6}\mathcal{I}_{3,2}^{*}\mathcal{I}_{2,2}^{2} - 2\rho^{2}\psi x^{5}\phi\mathcal{I}_{2,2}^{*}\mathcal{I}_{2,2}^{2} + 2\rho\psi x^{4}\phi\mathcal{I}_{3,2}^{*}\mathcal{I}_{1,2}(\eta - \zeta) + \rho^{2}\psi x^{4}\phi^{2}\mathcal{I}_{3,2}^{*}\mathcal{I}_{1,2}^{2}$$

$$- 2\rho^{2}\psi x^{4}\phi^{2}\mathcal{I}_{2,2}^{*}\mathcal{I}_{1,2}\mathcal{I}_{2,2} + \rho^{2}\psi x^{4}\phi\mathcal{I}_{1,1}^{*}\mathcal{I}_{2,2}^{2} + \rho^{2}x^{4}\mathcal{I}_{3,2}^{*}\mathcal{I}_{2,2}(\psi + \phi)$$

$$+ \rho^{2}\psi x^{4}\phi\mathcal{I}_{3,2}^{*}\mathcal{I}_{1,1}\mathcal{I}_{2,2} + \rho^{2}\psi x^{3}\phi\mathcal{I}_{1,1}^{*}\mathcal{I}_{1,2}\mathcal{I}_{2,2} + \rho^{2}\psi^{2}\mathcal{I}_{1,1}^{*}\mathcal{I}_{1,1}(\zeta - \eta)$$

$$- \rho x^{2}\psi x^{3}\phi^{2}\mathcal{I}_{2,2}^{*}\mathcal{I}_{1,1}\mathcal{I}_{1,2} + \rho^{2}\psi x^{3}\phi^{2}\mathcal{I}_{1,1}^{*}\mathcal{I}_{1,2}\mathcal{I}_{2,2} + \rho\psi x^{2}\phi\mathcal{I}_{1,1}^{*}\mathcal{I}_{1,1}(\zeta - \eta)$$

$$- \rho x^{2}\phi\mathcal{I}_{2,2}^{*}\mathcal{I}_{1,1}(\rho\phi + x\psi(\zeta - \eta)) - \rho\psi x^{2}\phi\mathcal{I}_{1,1}^{*}\mathcal{I}_{2,2}(\rho + x(\zeta - \eta))$$

$$- \rho^{2}\psi x^{2}\phi^{2}\mathcal{I}_{1,1}^{*}\mathcal{I}_{1,1}\mathcal{I}_{1,2} + \mathcal{I}_{3,2}^{*}(x^{4}\psi(\zeta - \eta)^{2} - \rho^{2}x^{2}\phi) \qquad (A544)$$

$$D_{32} = -\rho^{3}\psi x^{4}\phi\mathcal{I}_{2,2}^{2} + 2\rho^{2}\psi x^{2}\phi^{2}\mathcal{I}_{1,2}(\eta - \zeta) + \rho^{3}\psi x^{2}\phi^{3}\mathcal{I}_{1,2}^{2} + \rho^{3}x^{2}\phi\mathcal{I}_{2,2}(\psi + \phi)$$

$$+ \rho\phi\left(x^{2}\psi(\zeta - \eta)^{2} - \rho^{2}\phi\right). \qquad (A545)$$

Further simplifications are possible using the raising and lowering identities in Eq. (A5), as well as the results in Sec. A9.6.1, to obtain,

$$E_{32} = -\frac{\partial x}{\partial \gamma} \left((\phi \mathcal{I}_{1,2} + \omega) \left(\frac{\mathcal{I}_{1,1}^*}{\tau} + \frac{\psi \rho}{\phi} \mathcal{I}_{1,1} (\omega + \mathcal{I}_{1,1}^*) \right) + \frac{\omega \psi x}{\phi \bar{\tau}} \mathcal{I}_{2,2} + \frac{\phi}{x \bar{\tau}} \mathcal{I}_{1,2}^* - \frac{\omega x}{\tau} \mathcal{I}_{2,2}^* \right), \tag{A546}$$

where

$$\frac{\partial x}{\partial \gamma} = -\frac{x}{\gamma + \rho \gamma (\tau \psi / \phi + \bar{\tau})(\omega + \phi \mathcal{I}_{1,2})}.$$
 (A547)

A9.6.5 E_4

Define the block matrix $Q^{E_4} \equiv [Q_1^{E_4} \ Q_2^{E_4}]$ by,

and,

Then block matrix inversion (i.e. repeated applications of the Schur complement formula) shows that,

$$G_{13,13}^{E_4} = G_{14,14}^{E_4} = 1$$
 (A550)

$$G_{1,1}^{E_4} = G_{8,8}^{E_4} = G_{1,1}^{K^{-1}}$$
 (A551)

$$G_{2,2}^{E_4} = G_{9,9}^{E_4} = G_{2,2}^{K^{-1}}$$
 (A552)

$$G_{3,3}^{E_4} = G_{6,6}^{E_4} = G_{11,11}^{E_4} = G_{12,12}^{E_4} = G_{5,5}^{E_4} = G_{7,7}^{E_4} = G_{10,10}^{E_4} = G_{3,3}^{K^{-1}}$$
 (A553)

$$G_{3,4}^{E_4} = G_{5,6}^{E_4} = G_{10,11}^{E_4} = G_{12,7}^{E_4} = G_{3,4}^{K^{-1}}$$
 (A554)

$$G_{5,3}^{E_4} = G_{6,4}^{E_4} = G_{10,12}^{E_4} = G_{11,7}^{E_4} = G_{3,5}^{K^{-1}}$$
 (A555)

$$G_{5,4}^{E_4} = G_{10,7}^{E_4} = G_{3,6}^{K^{-1}}$$
 (A556)

$$G_{4,3}^{E_4} = G_{6,5}^{E_4} = G_{7,12}^{E_4} = G_{11,10}^{E_4} = G_{4,3}^{K^{-1}}$$
 (A557)

$$G_{6,3}^{E_4} = G_{11,12}^{E_4} = G_{4,5}^{K^{-1}}$$
 (A558)

$$G_{6,3}^{E_4} = G_{11,12}^{E_4} = G_{4,5}^{E_4} = G_{7,11}^{E_4} = G_{5,3}^{E_4}$$
(A559)

$$G_{3,6}^{E_4} = G_{12,11}^{E_4} = G_{5,4}^{K^{-1}}$$
 (A560)

$$G_{4,5}^{E_4} = G_{7,10}^{E_4} = G_{6,3}^{K^{-1}}$$
 (A561)

$$G_{14,2}^{E_4} = \frac{\psi}{\rho} E_4 \,, \tag{A562}$$

where $G_{i,j}^{E_4}$ denotes the normalized trace of the (i,j)-block of the inverse of $\left(Q^{E_4}\right)^{\top}$. For brevity, we have suppressed the expressions for the other non-zero blocks.

To compute the limiting values of these traces, we require the asymptotic block-wise traces of Q^{E_4} , which may be determined from the operator-valued Stieltjes transform. To proceed, we first augment Q^{E_4} to form the self-adjoint matrix \bar{Q}^{E_4} ,

$$\bar{Q}^{E_4} = \begin{pmatrix} 0 & \left[Q^{E_4} \right]^\top \\ Q^{E_4} & 0 \end{pmatrix}. \tag{A563}$$

and observe that we can write \bar{Q}^{E_4} as,

$$\begin{split} \bar{Q}^{E_4} &= \bar{Z} - \bar{Q}_{W,X,\Theta}^{E_4} - \bar{Q}_{\Sigma}^{E_4} \\ &= \begin{pmatrix} 0 & Z^{\top} \\ Z & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{W,X,\Theta}^{E_4} \right]^{\top} \\ Q_{W,X,\Theta}^{E_4} & 0 \end{pmatrix} - \begin{pmatrix} 0 & \left[Q_{\Sigma}^{E_4} \right]^{\top} \\ Q_{\Sigma}^{E_4} & 0 \end{pmatrix} , \end{split}$$
(A564)

where $Z=I_{2m+9n_0+3n_1},\,Q_{W,X,\Theta}^{E_4}\equiv[[Q_{W,X,\Theta}^{E_4}]_1\;[Q_{W,X,\Theta}^{E_4}]_2]$ and,

The operator-valued Stieltjes transforms satisfy,

$$\bar{G}^{E_4} = \bar{G}_{\Sigma}^{E_4} (\bar{Z} - \bar{R}_{W,X,\Theta}^{E_4}(\bar{G}^{E_4}))
= id \otimes \bar{\text{tr}} \left(\bar{Z} - \bar{R}_{W,X,\Theta}^{E_4}(\bar{G}^{E_4}) - \bar{Q}_{\Sigma}^{E_4} \right)^{-1} ,$$
(A568)

where $\bar{R}^{E_4}_{W,X,\Theta}(\bar{G}^{E_4})$ is the operator-valued R-transform of $\bar{Q}^{E_4}_{W,X,\Theta}$. As discussed above, since $\bar{Q}^{E_4}_{W,X,\Theta}$ is a block matrix whose blocks are i.i.d. Gaussian matrices (and their transposes), an explicit expression for $\bar{R}^{E_4}_{W,X,\Theta}(\bar{G}^{E_4})$ can be obtained from the covariance map η , which can be read off from Eq. (A563). As above, we use the specific sparsity pattern for G^{E_4} that is induced by Eq. (A568), to obtain,

$$\bar{R}_{W,X,\Theta}^{E_4}(\bar{G}^{E_4}) = \begin{pmatrix} 0 & R_{W,X,\Theta}^{E_4}(G^{E_4})^\top \\ R_{W,X,\Theta}^{E_4}(G^{E_4}) & 0 \end{pmatrix}, \tag{A569}$$

where,

$$\left[R_{W,X,\Theta}^{E_4}(G^{E_4})\right]_{1,1} = \frac{G_{2,2}^{E_4}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{4,5}^{E_4}}{\gamma} \tag{A570}$$

$$\left[R_{W,X,\Theta}^{E_4}(G^{E_4})\right]_{2,2} = \frac{\psi G_{1,1}^{E_4}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{6,3}^{E_4} \tag{A571}$$

$$[R_{W,X,\Theta}^{E_4}(G^{E_4})]_{2,14} = \sqrt{\rho \psi} G_{13,3}^{E_4}$$
(A572)

$$[R_{W,X,\Theta}^{E_4}(G^{E_4})]_{4,5} = -\frac{\sqrt{\rho}G_{1,1}^{E_4}}{\gamma\phi}$$
(A573)

$$[R_{W,X,\Theta}^{E_4}(G^{E_4})]_{6.3} = \sqrt{\rho}G_{2,2}^{E_4} \tag{A574}$$

$$[R_{W,X,\Theta}^{E_4}(G^{E_4})]_{7,10} = -\frac{\sqrt{\rho}G_{8,8}^{E_4}}{\gamma\phi}$$
(A575)

$$[R_{W,X,\Theta}^{E_4}(G^{E_4})]_{8,8} = \frac{G_{9,9}^{E_4}(\zeta - \eta)}{\gamma} - \frac{\sqrt{\rho}G_{7,10}^{E_4}}{\gamma}$$
(A576)

$$[R_{W,X,\Theta}^{E_4}(G^{E_4})]_{9,9} = \frac{\psi G_{8,8}^{E_4}(\zeta - \eta)}{\gamma \phi} + \sqrt{\rho} \psi G_{11,12}^{E_4}$$
(A577)

$$[R_{W,X,\Theta}^{E_4}(G^{E_4})]_{11,12} = \sqrt{\rho}G_{9,9}^{E_4} \tag{A578}$$

$$[R_{W,X,\Theta}^{E_4}(G^{E_4})]_{13,3} = \sqrt{\rho}G_{2,14}^{E_4}, \tag{A579}$$

and the remaining entries of $R_{W,X,\Theta}^{E_4}(G^{E_4})$ are zero. Similarly, following the example from $G^{E_{21}}$ above, plugging these expressions into Eq. (A568) and explicitly performing the block-matrix inverse yields the following set of coupled equations,

$$G_{7,5}^{E_4} = -\frac{\phi \mathcal{I}_{1,2}}{\sqrt{\rho}} \tag{A580}$$

$$G_{7,6}^{E_4} = -\frac{\phi \mathcal{I}_{\frac{1}{2},2}}{\sqrt{\rho}} \tag{A581}$$

$$G_{10,4}^{E_4} = -\frac{\sqrt{\rho}\tau^2 \mathcal{I}_{1,2}}{\phi} \tag{A582}$$

$$G_{10,6}^{E_4} = \tau \mathcal{I}_{\frac{1}{2},2} \tag{A583}$$

$$G_{11,3}^{E_4} = -\frac{\sqrt{\rho}\tau^2 \mathcal{I}_{2,2}}{\phi} \tag{A584}$$

$$G_{12,3}^{E_4} = -\frac{\gamma \rho \tau^2 \bar{\tau} \mathcal{I}_{2,2}}{\phi} \tag{A585}$$

$$G_{12,4}^{E_4} = -\frac{\gamma \rho \tau^2 \bar{\tau} \mathcal{I}_{\frac{3}{2},2}}{\phi} \tag{A586}$$

$$G_{12,5}^{E_4} = \frac{x\mathcal{I}_{\frac{3}{2},2}}{\sqrt{\rho}} \tag{A587}$$

$$G_{12,6}^{E_4} = \frac{x\mathcal{I}_{1,2}}{\sqrt{\rho}} \tag{A588}$$

$$G_{13,3}^{E_4} = \frac{\gamma\sqrt{\rho}\tau^2\bar{\tau}\mathcal{I}_{3,2}^*}{\phi}$$
 (A589)

$$G_{13,4}^{E_4} = \frac{\gamma\sqrt{\rho}\tau^2\bar{\tau}\mathcal{I}_{\frac{5}{2},2}^*}{\phi} \tag{A590}$$

$$G_{13,5}^{E_4} = -\frac{x\mathcal{I}_{\frac{5}{2},2}^*}{\rho} \tag{A591}$$

$$G_{13,6}^{E_4} = -\frac{x\mathcal{I}_{2,2}^*}{\rho} \tag{A592}$$

$$G_{13,7}^{E_4} = \frac{x\mathcal{I}_{\frac{3}{2},1}^*}{\sqrt{\rho}\phi} \tag{A593}$$

$$G_{13,10}^{E_4} = \gamma(-\bar{\tau})\mathcal{I}_{\frac{3}{2},1}^* \tag{A594}$$

$$G_{13,11}^{E_4} = \gamma(-\bar{\tau})\mathcal{I}_{1,1}^* \tag{A595}$$

$$G_{13,12}^{E_4} = -\frac{\mathcal{I}_{1,1}^*}{\sqrt{\rho}} \tag{A596}$$

$$G_{14,2}^{E_4} = \gamma \sqrt{\rho} \bar{\tau} \psi G_{13,3}^{E_4} \tag{A597}$$

$$G_{7,3}^{E_4} = G_{11,5}^{E_4} = \tau \mathcal{I}_{\frac{3}{2},2} \tag{A598}$$

$$G_{10,3}^{E_4} = G_{11,4}^{E_4} = -\frac{\sqrt{\rho}\tau^2 \mathcal{I}_{\frac{3}{2},2}}{\phi}$$
 (A599)

$$G_{13,13}^{E_4} = G_{14,14}^{E_4} = 1 (A600)$$

$$G_{7,4}^{E_4} = G_{10,5}^{E_4} = G_{11,6}^{E_4} = \tau \mathcal{I}_{1,2} \,, \tag{A601} \label{eq:A601}$$

Here we have used the definition of the LJSD μ , the relations in Eqs. (A550)-(A562), the definition of $\mathcal{I}_{a,b}^*$, and the results in Sec. A9.6.1, to simplify the expressions. It is straightforward algebra to solve these equations for the undetermined entries of G^{E_4} and thereby obtain the following expression for E_4 ,

$$E_4 = \frac{x^2}{\phi} \mathcal{I}_{3,2}^* \,. \tag{A602}$$

A9.6.6 Results for total error, bias, and variance

General expressions for the total error, bias and variance in terms of $E_{21}, E_{31}, E_{32}, E_4$ can be found in Sec. A9.5. Combining the results from Sec. A9.5 and Eqs. (A407), (A461) and (A546) yields expressions for the bias and total error. Using $E_{\mu}=B_{\mu}+V_{\mu}$, these results also determine the variance. Putting all the pieces together we find,

$$B_{\mu} = \phi \mathcal{I}_{1,2}^* \tag{A603}$$

$$V_{\mu} = -\rho \frac{\psi}{\phi} \frac{\partial x}{\partial \gamma} \left(\mathcal{I}_{1,1}(\omega + \phi \mathcal{I}_{1,2})(\omega + \mathcal{I}_{1,1}^*) + \frac{\phi^2}{\psi} \gamma \bar{\tau} \mathcal{I}_{1,2} \mathcal{I}_{2,2}^* + \gamma \tau \mathcal{I}_{2,2}(\omega + \phi \mathcal{I}_{1,2}^*) \right)$$

$$+ \sigma_{\varepsilon}^{2} \Big((\omega + \phi \mathcal{I}_{1,2})(\omega + \mathcal{I}_{1,1}^{*}) + \frac{\phi}{\psi} \gamma \bar{\tau} \mathcal{I}_{2,2}^{*} \Big) \Big)$$
 (A604)

(A605)

where x is the unique positive real root of $x=\frac{1-\gamma\tau}{\omega+\mathcal{I}_{1,1}}$, as in Eq. (A345). The derivative $\frac{\partial x}{\partial \gamma}$ follows from implicit differentiation and was given in Eq. (A463),

$$\frac{\partial x}{\partial \gamma} = -\frac{x}{\gamma + \rho \gamma (\tau \psi / \phi + \bar{\tau})(\omega + \phi \mathcal{I}_{1,2})}.$$
 (A606)

The asymptotic trace objects τ and $\bar{\tau}$ were defined in Eq. (A343) and Eq. (A344) and are given by,

$$\tau = \frac{\sqrt{(\psi - \phi)^2 + 4x\psi\phi\gamma/\rho} + \psi - \phi}{2\psi\gamma} \quad \text{and} \quad \bar{\tau} = \frac{1}{\gamma} + \frac{\psi}{\phi} \left(\tau - \frac{1}{\gamma}\right). \tag{A607}$$

All together, these results prove Thm. 5.1.