- We thank the reviewers for their careful reading of the manuscript, and for their constructive comments. We feel that
- the reviews are largely positive. In the remainder, we want to address some of the issues raised, and we will address
- 3 them in detail in the revision:
- 4 Reviewer 1: "Could you comment on the possibility to generalize these results, for example, to regularized LS, LASSO,
- 5 elastic net regularization, TLS, etc.?" Generalizing to ridge regression is possible using random matrix theory, but very
- 6 nontrivial, and in fact we are currently pursuing this. In our view, this would be a different project. Generalizing to
- 7 Lasso, elastic net, TLS seems like a much more difficult problem. It may be possible to handle lasso using approximate
- 8 message passing (AMP), but this would be a new project.
- 9 "In the simulation experiment the input matrix X should be studied for other distributions." We have simulations with
- 10 correlated t-distributed data in Appendix A.14
- "Also a finite-time analysis would be more convincing." For Gaussian and iid projections, it may be possible to
- 12 obtain convergence rates using known results on the convergence rate of Stieltjes transforms. However, for Hadamard
- 13 transforms, the only results we are aware of are asymptotic, as they are based on free probability theory. Thus
- 14 finite-sample results may be hard.
- 15 Reviewer 2: "'we get more accurate results for the performance of sketching' what exactly does this mean? How
- 16 is accuracy measured? It means that our results are more accurate in simulations, and "get the right constant". See
- 17 Appendix 16.
- 18 Maybe this is common in statistics but why is it reasonable to assume that p and n would grow together with the aspect
- 19 ratio converging? Why do we inherently expect more parameters with more data points? This is actually just a model
- 20 for "large n, large p". We do not really think that the number of parameters is growing.
- 21 Table 1 is very hard to read. Not sure if lines are divisions or line breaks. Many entries are missing and alignments
- 22 makes it impossible to tell which values are supposed to fall in which column. Variables in leverage score line are
- 23 undefined. We have made the table easier to read: add separators, copy values in multiple columns.
- 24 What talking about comparison to Raskutti and Mahoney in related work what sketching method does the 1 + 44p/r
- 25 term apply to? Also what are the stronger assumptions? I don't see any nontrivial assumptions listed for the random
- projection case in the table or in Theorem 2.1. It refers to their subsampling and subgaussian projection results. The
- 27 stronger conditions refer to subsampling, when we need ortho-invariance
- In Theorem 2.3 what does it mean that X's esd converges if X is just a matrix? Doe you mean that there is a function
- 29 mapping n and p to deterministic matrices and the esps of these matrices converge as n and p increase? We mean the
- 30 $esd\ of\ X^TX$
- Line 233: what does it mean for a matrix to be orthogonally invariant? This is the same as rotationally invariant, defined
- in lines 239-242
- 33 The rotationally invariant assumption seems super strong. This isn't even the case when each row is a p-dimensional
- 34 Gaussian with some fixed covariance Sigma right? Indeed, this condition is quite strong and does not hold for correlated
- 35 Gaussians. However, it seems that the current proof technique (asymptotic freeness, Theorem 4.3.11 of Hiai and Petz
- 36 (2006)) requires it
- Line 255: what does it mean it doesn't 'introduce enough randomness?' How is this measured? This is an intuitive
- 38 claim and we do not know how to measure it
- ³⁹ I don't see how the line in 280 gives leverage score sampling. Where does the eta-transform come up? Would be helpful
- 40 to explain a bit more. We will explain more, but the eta-transform is the limit of the leverage score
- 41 Although would be a lot more convincing if more than just a single dataset were tested. Figure 2 has two datasets
- What about at least X with Gaussian rows with a non identity covariance? We have simulations with correlated
- 43 t-distributed data in Appendix A.14, "Simulation for nonuniform data"
- Was leverage score sampling just not tested because you couldn't compute the theoretical bounds in closed form? See
- 45 Appendix 13 for simulations with leverage scores
- 46 Under Prop A.1, what is eps_t ? Under Proof of Theorem 2.1 $tr((X^TX)^{-1})$ shouldn't have an expectation around it. X
- 47 is fixed here right? eps_t is test noise. Indeed no expectation
- 48 "I think the biggest thing is to push forward the proof techniques and give some intuition. Too much of the paper
- 49 is spent just describing the results and explaining why they are good. More should be spent actually explaining the
- results." We will work on explaining the results and proof techniques, and giving intuition.