

1 We thank the reviewers for their extremely helpful feedback. We also thank all reviewers for pointing out the typos,
2 which we shall all correct in the final revision.

3 **Organization, Clarity, Notation:** We appreciate your feedback regarding the organization. Due to space constraints,
4 we provided a brief proof sketch, and chose not to include further details of the StrongEuler algorithm. However, we
5 recognize that this can obfuscate the intuition about both the algorithm and its analysis. We therefore propose the
6 following reorganization: **Optimistic Algorithms:** After describing the general MDP setting but before the statement
7 of our main results, we will introduce the notion of optimistic algorithms. We will explain how StrongEuler and related
8 algorithms in the literature achieve optimism by combining empirical estimates of transition probabilities/rewards with
9 confidence bound bonuses. The specific form of the bonuses for StrongEuler will remain in the appendix to save space,
10 but this should give more intuition for how StrongEuler operates. This will also address help to clarify for which class
11 of algorithms Theorem 2.3 applies (re: Reviewer 3's comments). **Proof Sketch:** In order to improve intuition and cut
12 down notation overhead, we will instead state a simplified but informal version of Prop 3.2 that specifies the dominant
13 term, albeit with a coarser dependence on the variances. This will eliminate clutter and allow us to simplify the rest
14 of proof. In addition, this will free up additional room to further explain the intuition behind the clipping in Prop 3.1.
15 In particular, we will provide intuition for the proof, and clarify why gap_{\min}/H appears in the analysis. This will in
16 turn clarify the dependence of gap_{\min} in the final bounds. **Organization of Supplement:** The proofs were structured
17 so that the proofs of the supporting lemmas were deferred until Appendix F. We now recognize that it may be easier
18 to incorporate the proofs of these lemmas at the end of the section, and so we will refactor Appendix F so that the
19 proofs of the lemmas come closer to their statements. We shall also include an "organization" section for the appendix
20 to explain how the different sections fit together, and split the supplement into groups (i.e. Part I. proof of upper
21 bounds Part II. Proof of clipping and other technical results, Part III proof of lower bounds). **Notational Overhead:**
22 Regarding the notational overhead, this seems to be a difficulty encountered by many papers in the MDP regret space,
23 and we intended our notation to be consistent with prior art. While we do include a table of notation, we appreciate
24 the reviewers suggestions that we remind the reader of notation. We will also include remarks that explain notational
25 rational (e.g. overline means "optimistic estimate"). We attempted to lighten notation by providing bounds at three
26 levels of granularity: (in the body, in App A, and in App C), and because of this, we should be able to simplify notation
27 in the proof sketch in the body of the paper by incorporating an informal statement of Prop 3.2 as described above.

28 **Reviewer 1:** Regarding your concern about the horizon dependence of the gaps, we define a horizon dependent gap in
29 Definition 1 (i.e., for times $h \in [H]$). For simplicity, we state the results in the main text in terms of the minimum over
30 the horizon dependent gaps, though more granular bounds are given in Appendix C. We confirm your suspicion that
31 gap_{\min} , as defined, may be zero if $\text{gap}_h(x, a) = 0$ for all x, a . However, our results will go through with a more refined
32 definition of $\text{gap}_{\min} := \min_{x, a, h} \{\text{gap}_h(x, a) : \text{gap}_h(x, a) > 0\}$, and we will be sure to restate our results to use this
33 definition instead. This way, gap_{\min} is strictly positive unless all actions are equally good for all states and all stages (in
34 which case the regret is trivially zero). We will also include a remark to clarify this point.

35 **Reviewer 2** Thank you for your helpful feedback. I hope your major concerns are addressed in the organization
36 suggestions listed above. Regarding the general comments: **1.** Line 97 regarding "average" reward. We apologize for
37 the imprecision. **2.** Line 168: We state in Sec 1.2 (the problem setting) that the rewards is a variable is bounded in $[0,1]$.
38 **3.** Line 200: We will include the quantifier for $h \in [H]$. Thanks for pointing out the omission

39 **Reviewer 3:** Thank you for the detail feedback **1.** We hope we addressed your concerns about organization in the
40 discussion above. **2.** Regarding point 2, yes you are correct an algorithm is optimistic with high probability. It would
41 be more accurate to state in the definition that "an algorithm satisfies (strong) optimism if...", and then say that we
42 informally refer to an optimistic algorithm as one that satisfies optimism with high probability. **3.** In appendix H, the
43 formal statement of the lower bound does explicitly give the class of algorithms which suffer Thm 2.3, and we will do a
44 better job to signpost this. To our knowledge, every low regret algorithm in the literature for this setting falls under this
45 class, and we can add this clarification as well. Moreover, as mentioned in the discussion about organization above,
46 explaining how optimistic algorithms are constructed from confidence bonuses will allow us to provide, in the main text,
47 an intuitive explanation of the formal class of algorithms which suffer the lower bound. **Additional comments: 4.** We
48 can explain the intuition for the ϵ parameter in the bound, and add a quantifier ($\forall \epsilon$) in the definition of Z_{sub} . Since the
49 bound takes a minimum over ϵ , it is not a parameter that requires specification. **5.** Thanks for the clarification of Jaksch.
50 We will clarify to state that their gap gap_* depends on measures of ergodicity that show up implicitly in the other
51 asymptotic analyses. **6.** To clarify what we mean by "almost" gap-independent, we will add a term $\text{poly}(\log(\text{gap}_{\min}))$
52 to capture an at most poly logarithmic dependence on the min gap. **7.** \tilde{S} and capital P are typos - thanks for the catch!
53 **8.** Thank you, we will clarify that uniqueness is essential for the proof of [15] **9.** For the inequality on 897 we will
54 clarify that a, b are positive. Then $\sqrt{a} + \sqrt{b} \leq \sqrt{a+b} + \sqrt{a+b} = 2\sqrt{a+b}$, whence the inequality follows.