

1 **Response to Reviewer #1** We thank the reviewer for taking the time to review our submission and for their helpful  
2 suggestions. Regarding recovery of  $k$ -NN graphs, you are correct that a best- $k$  strategy could be used to identify  
3 individual edges. The main challenge would be working out the condition for when the triangle inequality implies  
4 elimination. A point is eliminated if we can certify that there are  $k$  closer points due to either triangle inequalities or  
5 symmetry. That is ensured if for a given  $j$ , there are  $k$  distinct previous points  $i$  that satisfy the condition of Lemma 4.3.  
6 In the case of clustered data, as long as any cluster has at least  $k$  points, the same separation condition will apply, and  
7 this should give an additional factor of  $k$  in theorems 4.5 and 4.6. We will add a discussion of extending to  $k$ -NN graphs  
8 to the paper and correct the references to the algorithms.

9 **Response to Reviewer #2** We thank the reviewer for their comments on our work and all helpful suggestions for how  
10 to improve it. To the best of our knowledge, we are unaware of any prior work that uses noisy triplet queries to learn  
11 the NN-graph. In the noiseless setting, there are techniques for nearest neighbor search using triplets [1,2], which  
12 potentially could be modified and used as a sub-routine by an algorithm that finds the NN-graph when there is no noise.  
13 We will elaborate on works relevant to the noiseless triplet setting in the related work section. Regarding provided code,  
14 we included example code zipped in the supplementary to preserve double blindness and apologize for the confusion  
15 with the checklist. On the note of the metric assumption, in the supplementary, we compare against an implementation  
16 that does not use the triangle inequality. Compared to the method that uses triangle inequality, we see slightly worse  
17 initial performance but similar gains over random sampling at higher accuracy levels. We will move this discussion to  
18 the main body to highlight it. Thank you also for pointing out the typos. We will correct them, simplify the notation,  
19 and define the quantities in Lemma 3.1 before the statement of the Lemma.

20 **Response to Reviewer #3** We thank the reviewer for taking the time to review our work and all their suggestions,  
21 especially about how to clarify and contextualize the selection criteria.

22 *Re: quantification of entropy over NN-graphs.* That is an interesting way of looking at the problem. In some problem  
23 instances, the number of queries made by our algorithm is within a constant factor of the minimum bits required to  
24 specify the answer from a list of all possible NN-graphs. There are a total of  $n^{n-1}$  possible NN-graphs, hence each can  
25 be specified using  $(n-1)\log n$  bits. If the dataset consists of hierarchical clusters as in the condition for Theorem 4.6,  
26 then ANNEasy finds the NN-graph after making  $O(n\log(n)\overline{\Delta}^{-2})$  queries. Thus even though our noisy distance oracle is  
27 weaker than an oracle that answers arbitrary yes/no queries (e.g. membership queries of the form: is the true NN-graph  
28 present in a particular subset of all possible NN-graphs?), we are able to identify the NN-graph within a factor of the  
29 optimum number of queries and a multiplicative penalty to account for the noise in each answer.

30 The effect of having a weaker oracle can be seen in a different problem instance where  $\Omega(n^2)$  distance queries are  
31 necessary to identify the NN-graph by any algorithm that uses the weaker oracle. For example, consider a dataset  
32 consisting of points  $x_i = e_i + \epsilon \in \mathbb{R}^n \forall i$  where  $e_i$  is the unit vector with 1 in the  $i$ th component and 0 elsewhere, and  $\epsilon$   
33 is small independent zero-mean noise. Then all points are roughly at the same distance from each other, and for finding  
34  $x_{i^*}$  we have to query  $Q(i, j)$  for all  $j \neq i$ . This is made more explicit in the discussion following Theorem 4.4.

35 *Re: selection criteria for  $Q(i, j)$ .* Our algorithm iterates over points  $x_i$  in the dataset and finds  $x_{i^*}$  before starting  
36 the procedure for  $x_{i+1}$ . In the  $i$ th round, we use a modified successive elimination algorithm for bandit best-arm  
37 identification to find  $x_{i^*}$ . It is known that this algorithm matches instance-dependent lower bounds for best-arm  
38 identification within log-factors [3]. In that sense, for a given  $x_i$ , our algorithm optimally selects  $x_j$  while querying  
39  $Q(i, j)$  to find  $x_{i^*}$ . We will add this discussion before our reference to Algorithm 2. The triangle inequality bounds  
40 used for elimination are also optimal. [4] show that this Floyd-Warshall style approach yields the tightest upper and  
41 lower bounds on the distance matrix in the entry-wise  $L_1$  norm.

42 The order in which the points  $\{x_i\}$  are processed follows their subscript index, which is randomly chosen and fixed  
43 before starting the algorithm. Different orders in which  $\{x_i\}$  are processed can affect the query complexity of our  
44 algorithm as discussed in the paragraph after Theorem 4.4. However it is not always possible to find an optimal order  
45 for  $\{x_i\}$  from only noisy distance samples without assumptions on the metric. For example, if the oracle is noiseless,  
46 there are datasets where the pair  $(i, j)$  with the smallest  $d_{i,j}$ , must be queried within the first  $n$  queries to identify the  
47 NN-graph using the minimum number of queries. Since that cannot be ensured by an algorithm that only has access to  
48 information via a distance oracle, it is not possible to achieve the minimum number of queries in such examples.

- 49 [1] Haghiri, S., Ghoshdastidar, D., Luxburg, U.v. (2017). *Comparison-Based Nearest Neighbor Search*. Proceedings of the  
50 20th International Conference on Artificial Intelligence and Statistics, in PMLR 54:851-859  
51 [2] Houle, Michael E., and Michael Nett (2013), *Rank cover trees for nearest neighbor search*, International Conference on  
52 Similarity Search and Applications. Springer, Berlin, Heidelberg.  
53 [3] Emilie Kaufmann, Olivier Cappé, and Aurélien Garivier. 2016. *On the complexity of best-arm identification in multi-armed*  
54 *bandit models*. J. Mach. Learn. Res. 17, 1 (January 2016), 1-42.  
55 [4] Singla, Adish, Sebastian Tschiatschek, and Andreas Krause. *Actively learning hemimetrics with applications to eliciting*  
56 *user preferences*. International Conference on Machine Learning. 2016.