

1 We thank the reviewers for their positive feedback, indicating that our method is novel, theoretically justified and leads  
 2 to improved results (all); acknowledging the solid contribution of this work (R1), its usefulness for future research and  
 3 practitioners (R2) and high significance to the study of adversarial learning (R3). Next, we address individual concerns.

4 **R1** [Despite decreasing FIDs, it’s hard to pinpoint a noticeable increase in visual quality]: A lower FID can be attributed  
 5 to not only increased visual quality but also the improved sample diversity. By looking at generated images in Fig. 3  
 6 and Fig. S4 in the sup. mat., we observed that PA mostly increases the variation of samples. This is expected as PA  
 7 being a regularizer doesn’t modify the GAN architecture, as in PG-GAN (Karras’18) or BigGAN (Brock’19), to directly  
 8 improve the visual quality. For further evaluation, we measured the MS-SSIM of 10k synthetic CELEBA-HQ samples.  
 9 PA reduces it from 0.283 to 0.266, where the MS-SSIM of 10k real samples is 0.263 and PG-GAN reported 0.283.  
 10 Thus we believe that the quality of our generated samples is comparable to the ones of SoTA models, such as PG-GAN.

11 **R1** [A solid contribution, but does not appear to bring dramatic new capability]: We believe PA introduces a novel  
 12 mechanism to balance the two-player game in GAN training and partially alleviates the need of fine hyper-parameter  
 13 tuning (such as D and G learning rates in Tab. S4 in the sup. mat. or number of training iterations in Fig. 1 below),  
 14 which is, as known by the practitioners, often the key in achieving good quality and diversity of synthetic GAN samples.  
 15 To showcase this effect of PA, in Fig. 1 we present a toy example on MNIST. Note that PA effectively regularizes the  
 16 training and enables continuous learning, maintaining a good sample diversity (FID stays  $\sim 2.5$  across iterations).  
 17 Without PA, the training rapidly becomes unstable, leading to mode dropping (digit 1 occurs more frequently).

18 **R1** [Reservation regarding datasets, comparison with PG-GAN]: For our experiments we selected "a wide range of  
 19 important datasets" (R2), which serve as default benchmarks in image synthesis literature. Despite their different  
 20 resolutions ( $28 \sim 128$ ) and numbers of classes (1, 10 and 200), PA leads to consistent improvement over SoTA models.  
 21 For instance, with the SoTA SA GAN across CIFAR10 ( $32^2$ ), T-Imagenet ( $64^2$ ) and CELEBA-HQ ( $128^2$ ), PA improves  
 22 FID by 2.7, 2.9 and 2.4, respectively. Thus, we believe the similar trend would occur for high resolution image  
 23 generation. Unfortunately, due to high computational load, we were not able to finish high resolution experiments on  
 24 time. At the smaller resolution 64 of CELEBA, PA improves the SA GAN FID of 4.11 to 3.35, being on a par with  
 25 COCO-GAN (Lin’19), FID of 3.57, that outperforms PG-GAN at the resolution 128, i.e., FID 5.74 vs. 7.30.

26 **R1** [How variable are the results based on which layer the dropout applied to]: We report these results in Tab. 1 and Tab.  
 27 S2, S3 in the supp. material. Adding PA is beneficial independent of the dropout settings (keep rate and applied layer),  
 28 it helps to reduce the FID sensitivity to the dropout hyperparameter choice.

29 **R2** [Motivation of adding Gaussian noise]: We agree that  
 30 the initial motivation of adding noise in [1, 29] was to  
 31 ensure a joint support of the data and model distributions,  
 32 which results in a harder task for discriminator. We will  
 33 clarify this point in the related work.

34 **R2** [Good to be more clear that the numbers reported  
 35 do not use any label conditioning]: We thank R2 for the  
 36 suggestion. Our trained models indeed do not use any label information, while in the case of SS-GAN [6] plus PA  
 37 combination achieving the FID score of 14.9 on CIFAR10, comparable to the supervised case with large scale BigGAN  
 38 [4] training. We will make this point clear in Sec.4.

39 **R3** [Input space augmentation with other regularization  
 40 techniques]: We provide the requested results in Tab. 2.  
 41 PA is consistently beneficial when combining with other  
 42 regularization techniques, independent of augmentation  
 43 space. Additional FID gain can come along with fine  
 44 selection of the augmentation space. We will add the numbers to the paper.

45 **R3** [Clarity of Fig.1,2]: We thank R3 for the detailed comments and will integrate the suggested changes into the paper.

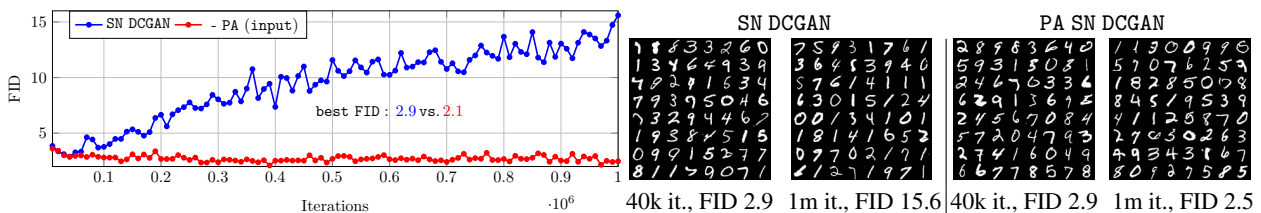
46 **R3** [The claim that D performs a binary classification seems disputable]: We agree that, strictly speaking,  $D(x)$  aims to  
 47 learn the probability of  $x$  being real/fake rather than to perform classification. However,  $D(x)$  can also be regarded as  
 48 the sigmoid response of classification with cross entropy loss. We will adjust our claim in Sec. 3.1 to avoid confusion.

**Table 1:** PA with Dropout on CIFAR10 with SN DCGAN.

Dropout PA(feat <sub>N/8</sub> )	input(N)		feat <sub>N/2</sub>		feat <sub>N/4</sub>		feat <sub>N/8</sub>	
	X	✓	X	✓	X	✓	X	✓
0.9	26.4	22.6	25.1	21.9	23.4	21.2	24.6	21.6
Keep rate	0.7	28.0 22.9	25.6 21.3	<u>22.1</u> 20.6	24.4	22.5		
0.5	27.1	23.1	25.9	22.3	23.1	21.2	24.0	22.1
$\Delta$ PA	4.5		3.7		1.9		2.3	

**Table 2:** PA with different regularizations on CIFAR10.

Method	PA	GAN	Lab. sm.	GP	GP <sub>zero-cent</sub>	Dropout	SS	$\Delta$ PA
SN DCGAN	X	26.0	25.8	26.7	26.5	22.1	-	-
	input	22.2	23.1	21.8	22.3	21.9	-	3.0
	feat	22.6	22.3	22.7	23.0	<b>20.6</b>	-	3.0
SA GAN	X	18.8	-	17.8	17.8	16.2	15.7	-
	input	16.1	-	15.8	16.1	15.5	<b>14.7</b>	1.3
	feat	16.3	-	16.1	15.9	15.6	14.9	1.5



**Figure 1:** PA enables continuous learning and prevents mode collapsing to a subset of classes (e.g., digit 1).