7 Appendix

We first state the large deviation inequality for vector-valued martingales, which is the generalization of Azuma-Hoeffding inequality for scalar valued martingales.

Theorem 1.8 of [13]: Let X_0, X_1, \ldots, X_m be a weak martingale sequence taking values in euclidean space \mathbb{R}^d , with $\mathbb{E}[X_i|X_{i-1}] = X_{i-1}$. Let $X_0 = 0$ and $||X_i - X_{i-1}||_2 \le 1$, for $i = 1, 2, \ldots, m$. Then, for every $\epsilon > 0$,

$$\Pr[\|X_m\|_2 \ge \epsilon] < 2e^2 e^{\frac{-\epsilon^2}{m}} \tag{8}$$

We use the concentration inequality to get a uniform confidence bound, over the space of learner's action, on the deviation of estimated reward from true reward, after each estimate of mean reward vector is produced.

Lemma 5. At the end of exploration phase within phase b, b = 1, 2, ..., of Algorithm PEGE, the estimator of reward vector θ_p^* is $\hat{\theta}(b) = \frac{\sum_{i=1}^{b} \sum_{j=1}^{i^{\beta}} \tilde{\theta}_{j,i}}{\sum_{j=1}^{b} j^{\beta}}$. Then, $\forall \eta > 0$,

$$\Pr[\forall x \in \mathcal{X} : |\bar{r}(x, \hat{\theta}(b)) - \bar{r}(x, \theta_p^*)| \le \eta] \ge 1 - 2e^2 e^{\frac{-(\sum_{i=1}^{b^\beta} i^\beta)\eta^2}{R^2 \beta_\sigma^2}}$$
(9)

where β_{σ} is the constant as defined in Eq. 3 and R is the Lipschitz constant defined in Assumption 3.

Proof. Let $\{X_{i,j}\}_{\substack{j=1,\ldots,i^{\beta}\\i=1,\ldots,b}}$ be a sequence of random vectors, defined as follows:

$$X_{i,j} = \frac{\sum_{i'=1}^{i-1} \sum_{j'=1}^{i'^{\beta}} \theta_p^* + \sum_{k=1}^{j} \theta_p^* - (\sum_{i'=1}^{i-1} \sum_{j'=1}^{i'^{\beta}} \tilde{\theta}_{j',i'} + \sum_{k=1}^{j} \tilde{\theta}_{k,i})}{\sum_{i''=1}^{b} \sum_{j''=1}^{(i'')^{\beta}} \beta_{\sigma}}$$
(10)

It can be checked that the ℓ_2 norm of the difference between any two consecutive random vectors is bounded by a constant. That is, $||X_{i,j} - X_{i,j-1}||_2 = \frac{||\theta_p^* - \tilde{\theta}_{j,i}||_2}{\sum_{i''=1}^b \sum_{j''=1}^{(i'')^{\beta}} \beta_{\sigma}} \leq \frac{1}{\sum_{i''=1}^b (i'')^{\beta}}$ and

$$\|X_{i+1,1} - X_{i,i^{\beta}}\|_{2} \frac{\|\theta_{p}^{*} - \theta_{1,i+1}\|_{2}}{\sum_{i''=1}^{b} \sum_{j''=1}^{(i'')^{\beta}} \beta_{\sigma}} \le \frac{1}{\sum_{i''=1}^{b} (i'')^{\beta}}$$

Also, $\tilde{\theta}_{j,i}$ is independent of all estimators formed before $\tilde{\theta}_{j,i}$ in Algorithm PEGE. Thus,

$$\mathbb{E}[X_{i,j} - X_{i,j-1} | X_{i,j-1}] = \mathbb{E}\left[\frac{\theta_p^* - \tilde{\theta}_{j,i}}{\sum_{i''=1}^b \sum_{j''=1}^{(i'')^\beta} \beta_\sigma} | X_{i,j-1}\right]$$

$$= \mathbb{E}\left[\frac{\theta_p^* - \tilde{\theta}_{j,i}}{\sum_{i''=1}^b \sum_{j''=1}^{(i'')^\beta} \beta_\sigma}\right] = 0$$
(11)

Thus, $\{X_{i,j}\}_{\substack{j=1,\ldots,i^{\beta}\\i=1,\ldots,b}}$ satisfy the criteria of weak martingale sequence and hence, by the large deviation inequality of vector valued martingales, we have,

$$\forall \epsilon > 0, \Pr[\|X_{b,b^{\beta}}\|_{2} \ge \epsilon] < 2e^{2}e^{\left(\frac{-\epsilon^{2}}{\sum_{i=1}^{b} \sum_{j=1}^{i^{\beta}} 1}{\left(\sum_{i=1}^{b} i^{\beta}\right)^{2}}\right)} = 2e^{2}e^{-\epsilon^{2}\sum_{i=1}^{b} i^{\beta}}.$$

Now, it can be clearly seen that $\|\theta_p^* - \hat{\theta}(b)\|_2 = \beta_\sigma \|X_{b,b^\beta}\|_2$ and let $\eta = \beta_\sigma \epsilon$. Then, $\forall \eta > 0$, we get

$$\Pr[\|\theta_p^* - \hat{\theta}(b)\|_2 \ge \eta] \le 2e^2 e^{\frac{-(\sum_{i=1}^{b^\beta} i^\beta)\eta^2}{\beta_\sigma^2}}$$

Using the Lipschitz property of expected reward function (Assumption 3), we have

$$\Pr(\exists x \in \mathcal{X} : |\bar{r}(x, \hat{\theta}(b)) - \bar{r}(x, \theta_p^*)| \ge \eta) \le \Pr(R \cdot ||\theta_p^* - \hat{\theta}(b)||_2 \ge \eta)$$
$$\le 2e^2 e^{\frac{-(\sum_{i=1}^{b^3} i^\beta)\eta^2}{R^2 \beta_\sigma^2}}$$
(12)

Taking complement of the event completes the proof.

7.1 **Proof of Results in Section 3**

7.1.1 **Proof of Theorem 1**

We first restate the theorem.

Distribution Independent Regret: When Algorithm PEGE is initialized with the parameters $C(a) = \log a$, $\alpha = 1/2$ and $\beta = 0$, and the online game is played over T rounds, we get the following bound on expected regret:

$$R(T) \le R_{max} |\sigma| T^{2/3} + 2R\beta_{\sigma} T^{2/3} \sqrt{\log 2e^2 + 2\log T} + R_{max}$$
(13)

where β_{σ} is the constant as defined in Eq. 3.

Proof. Let Algorithm PEGE run for K phases, with parameters initialized as $C(a) = \log a$, $\alpha = 1/2$ and $\beta = 0$.

Exploration regret: During every exploration phase, the expected regret is bounded by $|\sigma|R_{max}$, where R_{max} is as given in Assumption 3. Thus, total expected regret due to exploration is $K|\sigma|R_{max}$.

Exploitation regret: Let $x^* \in \operatorname{argmax}_{x \in \mathcal{X}} \bar{r}(x, \theta_p^*)$ and $x(b) \in \operatorname{argmax}_{x \in \mathcal{X}} \bar{r}(x, \hat{\theta}(b))$. During every exploitation round within phase *b* of Algorithm PEGE, the expected regret is $|\bar{r}(x(b), \theta_p^*) - \bar{r}(x^*, \theta_p^*)|$.

Now, from Lemma 5, with $\beta = 0$, the following holds w.p. $\geq 1 - \delta_b$,

$$\forall x, \ |\bar{r}(x,\theta_p^*) - \bar{r}(x,\hat{\theta}(b)| \le \underbrace{\sqrt{\frac{R^2 \beta_\sigma^2 \log(\frac{2e^2}{\delta_b})}{b}}}_{\eta_b}$$
(14)

Then, w.p. $\geq 1 - \delta_b$, the following event holds true: $|\bar{r}(x^*, \theta_p^*) - \bar{r}(x(b), \theta_p^*)| \leq 2\eta_b$, as explained:

$$\begin{split} \bar{r}(x^*, \theta_p^*) &\leq \bar{r}(x^*, \hat{\theta}(b)) + \eta_b \text{ from Eq. 14} \\ &\leq \bar{r}(x(b), \hat{\theta}(b)) + \eta_b \\ &\leq \bar{r}(x(b), \theta_p^*) + 2\eta_b \text{ from Eq. 14} \end{split}$$

Thus, the event $|\bar{r}(x^*, \theta_p^*) - \bar{r}(x(b), \theta_p^*)| \le 2\eta_b$ holds true w.p. $\ge 1 - \delta_b$, for every fixed phase b. Then, w.p. $\ge 1 - \sum_{i=1}^{K} \delta_i$, the following holds true:

$$\forall b, |\bar{r}(x^*, \theta_p^*) - \bar{r}(x(b), \theta_p^*)| \le 2\eta_b$$

Note that the expected regret per round is always bounded by R_{\max} (since expected reward is bounded by R_{\max}).

The number of rounds of exploitation in phase b is b^{α} . Hence, the total expected regret due to exploitation, over K phases is:

$$\sum_{i=1}^{K} \left(\underbrace{(1 - \sum_{j=1}^{K} \delta_j) \frac{2R\beta_{\sigma}\sqrt{\log(2e^2/\delta_i)}}{\sqrt{i}} + (\sum_{j=1}^{K} \delta_j)R_{\max}}_{\text{expected regret per exploitation round}} \right) i^{\alpha}$$

Taking $\delta_1 = \delta_2 = \ldots = \delta_K = \delta$, and summing over exploration and exploitation regret over K phases, we get

$$R(T) \le K |\sigma| R_{max} + \sum_{i=1}^{K} \left((1 - K\delta) \frac{2R\beta_{\sigma}\sqrt{\log(2e^2/\delta)}}{\sqrt{i}} + (K\delta)R_{max} \right) i^{\alpha}$$
(15)

Using the inequality $\sum_{i=1}^{K} i^{y} \leq \int_{0}^{K} i^{y} dy \leq K^{y+1}$, we get expected regret:

$$R(T) \le K |\sigma| R_{max} + (1 - K\delta) 2R\beta_{\sigma} \sqrt{\log(2e^2/\delta)} K^{\alpha + 1/2} + K\delta R_{\max} K^{\alpha + 1}$$
(16)

Now, we relate K to total time T as: $T = |\sigma|K + \sum_{i=1}^{K} i^{\alpha} \sim K^{\alpha+1}$, for large K.

Hence $K \sim T^{\frac{1}{1+\alpha}}$. Substituting value of K in Eq 16, and taking $\alpha = 1/2$ and $\delta = \frac{1}{KT}$ gives us the required bound on expected regret.

Our next lemma shows that as the number of phases b grows in Algorithm PEGE, the probability of selecting a sub-optimal arm for greedy exploitation shrinks.

Lemma 6. At the end of exploration phase within phase b, b = 1, 2, ..., the estimator constructed is $\hat{\mu}_{i,1} = \sum_{j=1}^{b} \tilde{\theta}_{j,i}$

$$(b) = \frac{\sum_{j=1}^{b} \sum_{j=1}^{b} j^{\beta}}{\sum_{j=1}^{b} j^{\beta}}.$$
 Then the following holds,
$$\Pr(a_{j}, \dots, p_{j}) \in \Omega, 2 + \frac{-(\sum_{j=1}^{b} i^{\beta})\Delta^{2}}{4B^{2}\alpha^{2}}$$
(17)

$$\Pr(\operatorname*{argmax}_{x \in \mathcal{X}} \bar{r}(x, \hat{\theta}(b)) \not\subseteq \operatorname*{argmax}_{x \in \mathcal{X}} \bar{r}(x, \theta_p^*)) \le 2e^2 e^{\frac{-(\sum_{i=1}^{n} i^\beta)\Delta^2}{4R^2\beta_{\sigma}^2}}$$
(17)

Proof. Let us assume $x' \in \operatorname{argmax}_{x \in \mathcal{X}} \bar{r}(x, \hat{\theta}(b))$ such that $x' \notin \operatorname{argmax}_{x \in \mathcal{X}} \bar{r}(x, \theta_p^*)$. Let $x^* \in \operatorname{argmax}_{x \in \mathcal{X}} \bar{r}(x, \theta_p^*)$. Then, by our assumption, $\bar{r}(x', \hat{\theta}(b)) \geq \bar{r}(x^*, \hat{\theta}(b))$. By definition of gap Δ , we also have $\bar{r}(x^*, \theta_p^*) - \bar{r}(x', \theta_p^*) \geq \Delta$. The two inequalities imply that at least one of the following two inequalities has to hold: either $|\bar{r}(x^*, \theta_p^*) - \bar{r}(x^*, \hat{\theta}(b))| \geq \frac{\Delta}{2}$ or $|\bar{r}(x', \hat{\theta}(b)) - \bar{r}(x', \theta_p^*)| \geq \frac{\Delta}{2}$.

Thus, $\operatorname{argmax}_{x \in \mathcal{X}} \bar{r}(x, \hat{\theta}(b)) \not\subseteq \operatorname{argmax}_{x \in \mathcal{X}} \bar{r}(x, \theta_p^*) \implies \exists x \in \mathcal{X} : |\bar{r}(x, \theta_p^*) - \bar{r}(x, \hat{\theta}(b))| \ge \frac{\Delta}{2}$. By using Lemma 5, and substituting $\eta = \frac{\Delta}{2}$, we get our result.

7.1.2 **Proof of Theorem 2**

We restate the theorem before proving:

Distribution Dependent Regret: When Algorithm PEGE is initialized with the parameters $C(a) = h \cdot a$, for a tuning parameter h > 0, $\alpha = 1$ and $\beta = 1$, and the online game is played over T rounds, we get the following bound on expected regret:

$$R(T) \le \sum_{x \in \sigma} \Delta_x \left(\frac{\log T}{h}\right)^2 + \frac{4\sqrt{2\pi}e^2 R \Delta_{max} \beta_\sigma}{\Delta} e^{\frac{h^2 (2R^2 \beta_\sigma^2)}{\Delta^2}}.$$
(18)

Proof. Let total number of phases that the algorithm runs for be K. We relate K to total time T as (after substituting parameters $C(a) = h \cdot a$, $\alpha = 1$ and $\beta = 1$ in Algorithm PEGE):

$$T = \sum_{i=1}^{K} |\sigma| i + \sum_{i=1}^{K} e^{hi} \ge e^{hK} \implies K \le \frac{\log T}{h}.$$

Exploration regret: Since we are in distribution dependent setting now, expected exploration regret in each exploration phase is $\sum_{x \in \sigma} \Delta_x$. Hence, total expected exploration regret is upper bounded by:

$$\sum_{i=1}^{K} (\sum_{x \in \sigma} \Delta_x) i = \sum_{x \in \sigma} \Delta_x \frac{K(K+1)}{2} \le (\sum_{x \in \sigma} \Delta_x) \frac{\log^2 T}{h^2}.$$

Exploitation regret: When a sub-optimal arm is picked in an exploitation round, the expected regret in that round is: $\leq \Delta_{max}$. Using Lemma 6 with $\beta = 1$, the total expected regret due to exploitation over K phases is upper bounded by:

$$\sum_{i=1}^{K} \underbrace{2e^{2}\Delta_{max} e^{hi - \frac{i(i+1)}{2} \frac{\Delta^{2}}{4R^{2}\beta_{\sigma}^{2}}}}_{\leq 2e^{2}\Delta_{max}} \sum_{i=1}^{\infty} e^{hi - \frac{i(i+1)}{2} \frac{\Delta^{2}}{4R^{2}\beta_{\sigma}^{2}}}$$

$$\leq 2e^{2}\Delta_{max} \sum_{i=1}^{\infty} e^{hi - \frac{i^{2}}{2} \frac{\Delta^{2}}{4R^{2}\beta_{\sigma}^{2}}}$$

$$\leq 2e^{2}\Delta_{max} \int_{-\infty}^{\infty} e^{hy - \frac{y^{2}}{2} \frac{\Delta^{2}}{4R^{2}\beta_{\sigma}^{2}}} dy$$
(19)

The integral is the moment generating function (adjusting for normalization constant) of a gaussian random variable $Y \in \mathcal{N}(0, \frac{4R^2\beta_{\sigma}^2}{\Delta^2})$. Thus, the integral is $\mathbb{E}[e^{hY}] = e^{\frac{2h^2R^2\beta_{\sigma}^2}{\Delta^2}}$ and total expected regret due to exploitation is upper bounded by: $\frac{4e^2\Delta_{max}\sqrt{2\pi}R\beta_{\sigma}}{\Delta}e^{\frac{2h^2R^2\beta_{\sigma}^2}{\Delta^2}}$.

Summing over exploration and exploitation regrets completes the proof.

7.2 **Proof of Results in Section 4**

The following theorem is about the version of PEGE that Algorithm 3 calls on line 8. It will be needed in the proof of Theorem 4.

Theorem 7. (Distribution Dependent Regret, version 2) When Algorithm 1 is initialized with the parameters $C(a) = h \cdot a$, for a tuning parameter $0 < h < \frac{\Delta^2}{4R^2\beta_{\sigma}^2}$, $\alpha = 1$ and $\beta = 0$, and the online game is played over T rounds, we get the following bound on expected regret:

$$R(T) \le \sum_{x \in \sigma} \Delta_x \frac{\log T}{h} + \frac{2e^2 \Delta_{max}}{\frac{\Delta^2}{4R^2 \beta_{\sigma}^2} - h}$$
(20)

Note: Compared to Theorem 2, the regret bound has better dependence on $T - O(\log T)$ instead of $O(\log^2 T)$ — but it also has a disadvantage. If the tuning parameter h is incorrectly set, say $h \ge \frac{\Delta^2}{4B^2\beta^2}$, then the bound does not even apply.

Proof. The proof is similar to proof of Theorem 2. We highlight the key steps:

Let total number of phases that the algorithm runs for be K. First: $T = \sum_{i=1}^{K} |\sigma| + \sum_{i=1}^{K} e^{hi} \ge e^{hK}$ $\implies K \le \frac{\log T}{h}.$

Expected regret due to exploration: $\sum_{i=1}^{K} (\sum_{x \in \sigma} \Delta_x) = \sum_{x \in \sigma} \Delta_x K \le (\sum_{x \in \sigma} \Delta_x) \frac{\log T}{h}.$

Expected regret due to exploitation: When a sub-optimal arm is picked, expected regret $\leq \Delta_{max}$. Using Lemma 6 with $\beta = 0$, and tuning parameter $h < \frac{\Delta^2}{4R^2\beta_{\sigma}^2}$, we get total expected regret due to exploitation

$$2e^{2}\Delta_{max}\sum_{i=1}^{K}e^{hi-i\frac{\Delta^{2}}{4R^{2}\beta_{\sigma}^{2}}} \leq 2e^{2}\Delta_{max}\sum_{i=1}^{\infty}e^{hi-i\frac{\Delta^{2}}{4R^{2}\beta_{\sigma}^{2}}}$$
$$= 2e^{2}\Delta_{max}\sum_{i=1}^{\infty}e^{-i(\frac{\Delta^{2}}{4R^{2}\beta_{\sigma}^{2}}-h)}$$
$$\leq 2e^{2}\Delta_{max}\int_{0}^{\infty}e^{-y(\frac{\Delta^{2}}{4R^{2}\beta_{\sigma}^{2}}-h)}dy$$
$$= \frac{2e^{2}\Delta_{max}}{\frac{\Delta^{2}}{4R^{2}\beta_{\sigma}^{2}}-h}$$

7.2.1 Proof of Theorem 3

Proof. Note that Assumption 1 through Assumption 3 hold. Therefore, from Lemma 5, with $\beta = 0$ we get, with probability at least $1 - \delta_b$,

$$\begin{aligned} \forall x, \ |\bar{r}(x,\theta_p^*) - \bar{r}(x,\hat{\theta}(b)| \leq \sqrt{\frac{R^2 \beta_{\sigma}^2 \log(\frac{2e^2}{\delta_b})}{b}} \end{aligned}$$
 Let $\delta_b = \delta/2b^2$ which implies $\sum_{b\geq 1} \delta_b = \pi^2 \delta/12 < \delta$. Thus, setting $w(b) = \sqrt{\frac{R^2 \beta_{\sigma}^2 \log(\frac{4e^2b^2}{\delta})}{b}},$

the event E defined as

$$\forall b \ge 1, \forall x \in \mathcal{X}, |\bar{r}(x, \hat{\theta}(b)) - \bar{r}(x, \theta_p^*)| \le w(b).$$
(22)

holds with probability at least $1 - \delta$.

1. Note that $b \ge T_1(\delta)$ implies $8w(b) < \Delta$. This is because the latter has the form $e^{Lb} > Mb$ with $M = 2e/\delta$ and $L = \Delta^2/(128R^2\beta_{\sigma}^2)$. Setting $b \ge 2/L\log(2M/L)$ guarantees that $e^{Lb/2} > 2M/L$ which implies that $e^{Lb} > Mb$ since $e^{Lb/2} > 1 + Lb/2 > Lb/2$.

If $8w(b) < \Delta$ then clearly $2w(b) < \Delta$. Let $x \neq x^*$ be arbitrary. We have the following chain of implications:

	$2w(b) < \Delta$	
\Rightarrow	$2w(b) < \bar{r}(x^*,\theta_p^*) - \bar{r}(x^*,\theta_p^*)$	(def. of Δ)
\Rightarrow	$2w(b) < \bar{r}(x^*,\theta_p^*) - \bar{r}(x,\theta_p^*)$	(Assumption 4)
\Rightarrow	$0 < \bar{r}(x^*, \hat{\theta}(b)) - \bar{r}(x, \hat{\theta}(b)).$	(:: E holds)

This means that the If condition on line 12 will evaluate to true and $\hat{x}(b)$ on line 13 will be set to x^* .

We also have the following chain of implications:

$$\begin{split} & 8w(b) < \Delta \\ \Rightarrow & 8w(b) < \bar{r}(x^*, \theta_p^*) - \bar{r}(x_-^*, \theta_p^*) \qquad (\text{def. of } \Delta) \\ \Rightarrow & 8w(b) < \bar{r}(x^*, \theta_p^*) - \bar{r}(\hat{x}_-(b), \theta_p^*) \qquad (\because \bar{r}(\hat{x}_-(b), \theta_p^*)) \leq \bar{r}(x_-^*, \theta_p^*)) \\ \Rightarrow & 8w(b) < \bar{r}(\hat{x}(b), \theta_p^*) - \bar{r}(\hat{x}_-(b), \theta_p^*) \qquad (\because \hat{x}(b) = x^*) \\ \Rightarrow & 6w(b) < \bar{r}(\hat{x}(b), \hat{\theta}(b)) - \bar{r}(\hat{x}_-(b), \hat{\theta}(b)). \qquad (\because E \text{ holds}) \end{split}$$

This means that the If condition on line 15 will evaluate to true and the algorithm will stop and output an estimate $\hat{\Delta}$.

Now suppose the algorithm stops and does not output "threshold exceeded" which means that the If conditions on line 12 and line 15 were both true at some episode b. Let $x \neq \hat{x}(b)$ be arbitrary. We have the following chain of implications:

$$\begin{split} & 6w(b) < \bar{r}(\hat{x}(b), \hat{\theta}(b)) - \bar{r}(\hat{x}_{-}(b), \hat{\theta}(b)) \quad \text{(line 15)} \\ \Rightarrow & 6w(b) < \bar{r}(\hat{x}(b), \hat{\theta}(b)) - \bar{r}(x, \hat{\theta}(b)) \qquad (\hat{x}(b) \text{ unique maximizer by line 12)} \\ \Rightarrow & 4w(b) < \bar{r}(\hat{x}(b), \theta_p^*) - \bar{r}(x, \theta_p^*). \qquad (\because E \text{ holds}) \end{split}$$

This means, along with Assumption 4, that $\hat{x}(b) = x^*$. We also have,

$$\begin{array}{ll} 6w(b) < \bar{r}(\hat{x}(b), \theta(b)) - \bar{r}(\hat{x}_{-}(b), \theta(b)) & (\text{line 15}) \\ \Rightarrow & 6w(b) < \bar{r}(\hat{x}(b), \hat{\theta}(b)) - \bar{r}(x_{-}^{*}, \hat{\theta}(b)) & (\because \bar{r}(\hat{x}_{-}(b), \hat{\theta}(b)) \ge \bar{r}(x_{-}^{*}, \hat{\theta}(b))) \\ \Rightarrow & 4w(b) < \bar{r}(\hat{x}(b), \theta_{p}^{*}) - \bar{r}(x_{-}^{*}, \theta_{p}^{*}) & (\because E \text{ holds}) \\ \Rightarrow & 4w(b) < \bar{r}(x^{*}, \theta_{p}^{*}) - \bar{r}(x_{-}^{*}, \theta_{p}^{*}) & (\because \hat{x}(b) = x^{*}) \\ \Rightarrow & 4w(b) < \Delta. & (\text{def. of } \Delta) \end{array}$$

Now we prove that the output $\hat{\Delta}$ lies in the right range. We have

$$\begin{split} \hat{\Delta} &= \bar{r}(\hat{x}(b), \hat{\theta}(b)) - \bar{r}(\hat{x}_{-}(b), \hat{\theta}(b)) & \text{(line 16)} \\ &\geq \bar{r}(\hat{x}(b), \theta_p^*) - \bar{r}(\hat{x}_{-}(b), \theta_p^*) - 2w(b) & (\because E \text{ holds}) \\ &= \bar{r}(x^*, \theta_p^*) - \bar{r}(\hat{x}_{-}(b), \theta_p^*) - 2w(b) & (\because \hat{x}(b) = x^*) \\ &\geq \bar{r}(x^*, \theta_p^*) - \bar{r}(x_-^*, \theta_p^*) - 2w(b) & (\because \bar{r}(\hat{x}_{-}(b), \theta_p^*) \leq \bar{r}(x_-^*, \theta_p^*)) \\ &\geq \Delta - 2w(b) & (\text{def. of } \Delta) \\ &\geq \frac{\Delta}{2}. & (\because w(b) < \Delta/4) \end{split}$$

Similarly,

$$\begin{split} \hat{\Delta} &= \bar{r}(\hat{x}(b), \hat{\theta}(b)) - \bar{r}(\hat{x}_{-}(b), \hat{\theta}(b)) & \text{(line 16)} \\ &\leq \bar{r}(\hat{x}(b), \hat{\theta}(b)) - \bar{r}(x_{-}^{*}, \hat{\theta}(b)) & (\because \bar{r}(\hat{x}_{-}(b), \hat{\theta}(b)) \geq \bar{r}(x_{-}^{*}, \hat{\theta}(b))) \\ &= \bar{r}(x^{*}, \hat{\theta}(b)) - \bar{r}(x_{-}^{*}, \hat{\theta}(b)) & (\because \hat{x}(b) = x^{*}) \\ &\leq \bar{r}(x^{*}, \theta_{p}^{*}) - \bar{r}(x_{-}^{*}, \theta_{p}^{*}) + 2w(b) & (\because E \text{ holds}) \\ &\leq \Delta + 2w(b) & (\text{def. of } \Delta) \\ &\leq \frac{3\Delta}{2}. & (\because w(b) < \Delta/4) \end{split}$$

2. In this case $T_0 \leq T_1(\delta)$ but it could still be that the algorithm stops not because the threshold is exceeded but because line 12 and line 15 were true at some episode *b*. Clearly $b < T_0$, otherwise we would have output "threshold exceeded" and not produced an estimate $\hat{\Delta}$. Under the event *E*, the previous part shows that if stopping occurs with an estimate $\hat{\Delta}$, it must be that $4w(b) < \Delta$, i.e.

$$4\sqrt{\frac{R^2\beta_{\sigma}^2\log(\frac{4e^2b^2}{\delta})}{b}} < \Delta \quad \Rightarrow \quad b > \frac{16R^2\beta_{\sigma}^2}{\Delta^2}\log\frac{4e^2}{\delta} = T_2(\delta).$$

This means $T_0 > b > T_2(\delta)$.

3. Finally, suppose Assumptions 1 through 3 hold but Assumption 4 fails. Event E still holds with probability at least $1 - \delta$. However, if there are at least two optimal actions then, under E, their confidence intervals will always overlap and If condition on line 15 will never be true. That means that the algorithm can only stop when the threshold T_0 is exceeded.

7.2.2 Proof of Theorem 4

Proof. We break the proof into the two cases mentioned in the theorem statement.

Part 1: Assumption 4 fails. From Theorem 3 we know, that with probability at least $1 - \delta$, Algorithm 2 outputs "threshold exceeded" in this case. Because of Eq. (22), we also have, for an optimal action x^* :

$$|\bar{r}(\hat{x}(T_0), \theta_p^*) - \bar{r}(x^*, \theta_p^*)| \le 2w(T_0)$$

which implies a total regret of

$$2w(T_0)(T - T_0|\sigma|) \le 2w(T_0)T$$

in the remaining $T - T_0 |\sigma|$ rounds since we execute line 5. The regret when Algorithm 2 was running is bounded by $R_{max}T_0 |\sigma|$. On the bad event, which occurs with probability at most $1 - \delta$, the regret is at most TR_{max} giving us a total expected regret of

$$2w(T_0)T + T_0|\sigma|R_{max} + \delta TR_{max} = 2\sqrt{\frac{R^2\beta_{\sigma}^2\log(\frac{4e^2T_0^2}{\delta})}{T_0}}T + T_0|\sigma|R_{max} + \delta TR_{max}$$